

# CSE211: Compiler Design

Nov. 29, 2021

- **Topic:** Optimization Policies
- **Discussion questions:**
  - How can you determine good optimizations for a program?

# Announcements

- Friday is a big day:
  - Homework 4 is due
  - Paper reviews are due
  - Final project presentations
  - 2 hour class (1 hour extended after)
- Class on Wednesday canceled
  - use the time to study for the final, work on homeworks, or work on final project

# Announcements

- Sign-up for time slots
  - Priority given to those who cannot attend off-hours
  - For those who cannot attend off-hours, please read the blog posts for the projects you miss
- 120 minutes for 11 presentations:
  - 9 minutes per presentation (HARD, I will be using the unforgiving iphone timer)
  - try for 7 minute presentation and 2 minutes for questions.
  - Use your own computer, or if you send me your presentation, you can use mine.

# Announcements

- For blog post:
  - please submit as a PR to the class git repo:
  - <https://github.com/SorensenUCSC/CSE211-fa2021/>
  - follow the example project
  - create a directory with your name, include an .md file and all images
  - link to it in projects.md
- Write the blog post like how you'd like to read one! Lots of background, lots of images and code snippets.
  - Use only original images please!
  - Should roughly be the same amount of content as the final report would be.

# Announcements

- For reports (project and paper):
  - if you are having trouble filling in the space:
  - give more background. Imagine you are giving a CSE211 lecture!
  - give more examples and walk through them
  - show code snippets
  - discuss related works
- *At some point in your career you will transition to wanting more space rather than trying to fill up space!*

# Announcements

- Office hours:
  - Since thanksgiving office hours got canceled, I will hold a make-up hour tomorrow from 2 - 3 pm
  - There will also be normal Thursday office hours
- After Friday:
  - I will start grading HW3, HW4 and paper reviews
  - Please discuss grades with me ASAP if there are issues

# Announcements

- SETs:
  - Please fill them out!
  - They are important for non-core classes like this one
- Individual feedback is also appreciated: feel free to send an email with any thoughts you have:
  - what you enjoyed 😊
  - what you wish we would have discussed
  - what you wish we would have spent more time on
- I will also release an anonymous survey on canvas asking some of these questions. It should not replace the SETs though!

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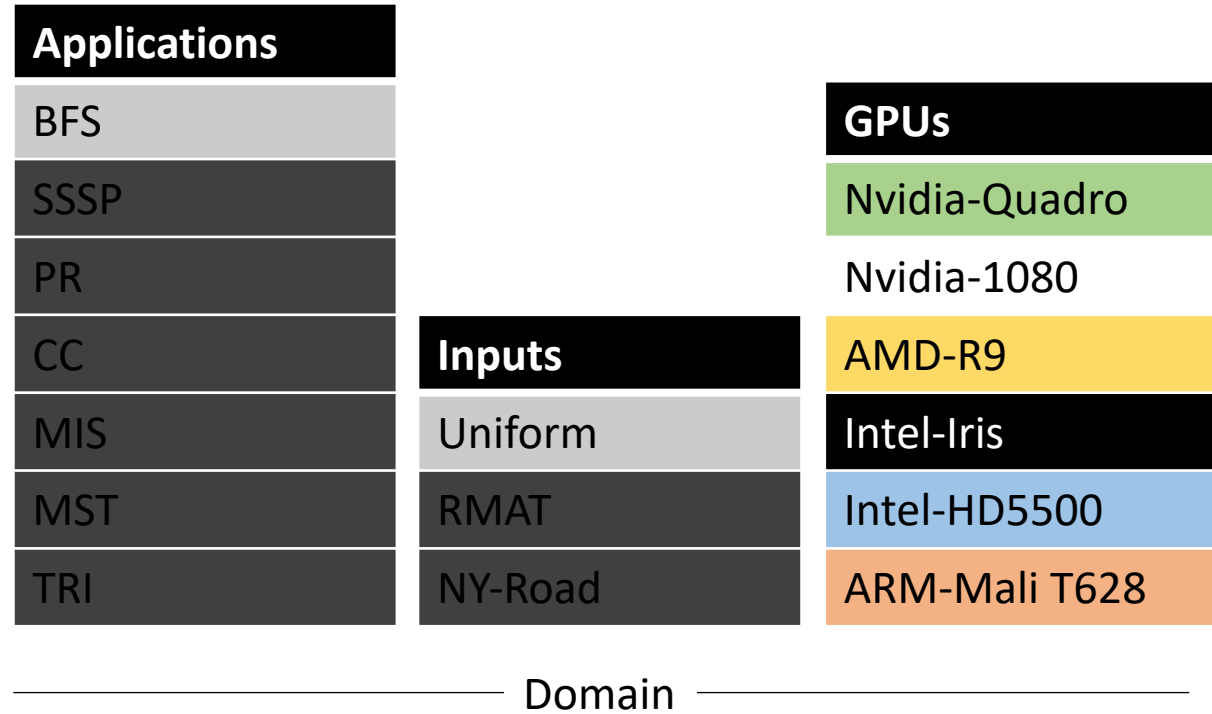
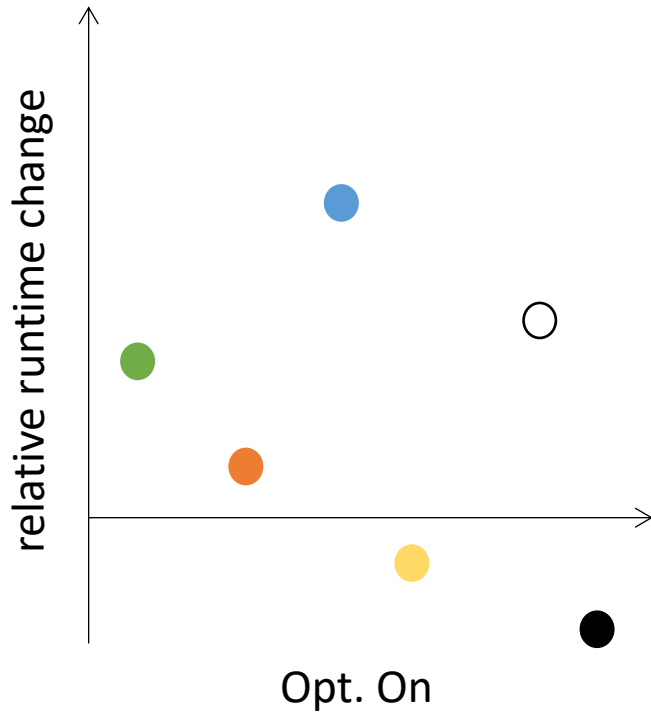
- How can you determine good optimizations for a program?

- **auto-tuning:** Halide approach
- **exhaustive enumeration:** irgl approach

# Rank-based

Pros and cons for this approach?

are points more likely to be above or below the line?



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- **Topic:** Optimization Policies

- **Discussion questions:**

- How can you determine good optimizations for a program?

- **auto-tuning:** Halide approach
- **exhaustive enumeration:** irgl approach
- What else?

# Big question

- When should optimizations be enabled or disabled?
  - if optimization adds a large compile time
  - if optimization makes debugging harder
  - if optimization makes smaller binaries
  - if optimization is not well tested
  - if optimization is likely to provide a performance increase

# What do modern compilers do?

- gcc?
  - -O0, -O1, -O2
- See differences at:  
<https://gcc.gnu.org/onlinedocs/gcc/Optimize-Options.html>
- different optimizations for different use cases
  - -Os, -Og, -Ofast

# Making programs go faster

- All of the optimizations we've examined have had performance trade-offs
- Local value numbering?



what can go wrong?

x might have gone to memory if there isn't enough registers. A memory access is more expensive than some arithmetic operations

*Same issue for Pipelining and Super Scalar re-orderings!*



# Making programs go faster

- All of the optimizations we've examined have had performance trade-offs
- Loop unrolling?
  - Pros/cons?
- Making DOALL loops parallel?
  - Pros/cons?

# Compilers are evaluated on benchmark suites

- Scientific computing
  - Rodinia, Parboil, Linpack
- Managed Languages:
  - Decapo (Java)
- Heterogeneous systems
  - SHOC
- GPU
  - Magma
- Graphs
  - GAPS

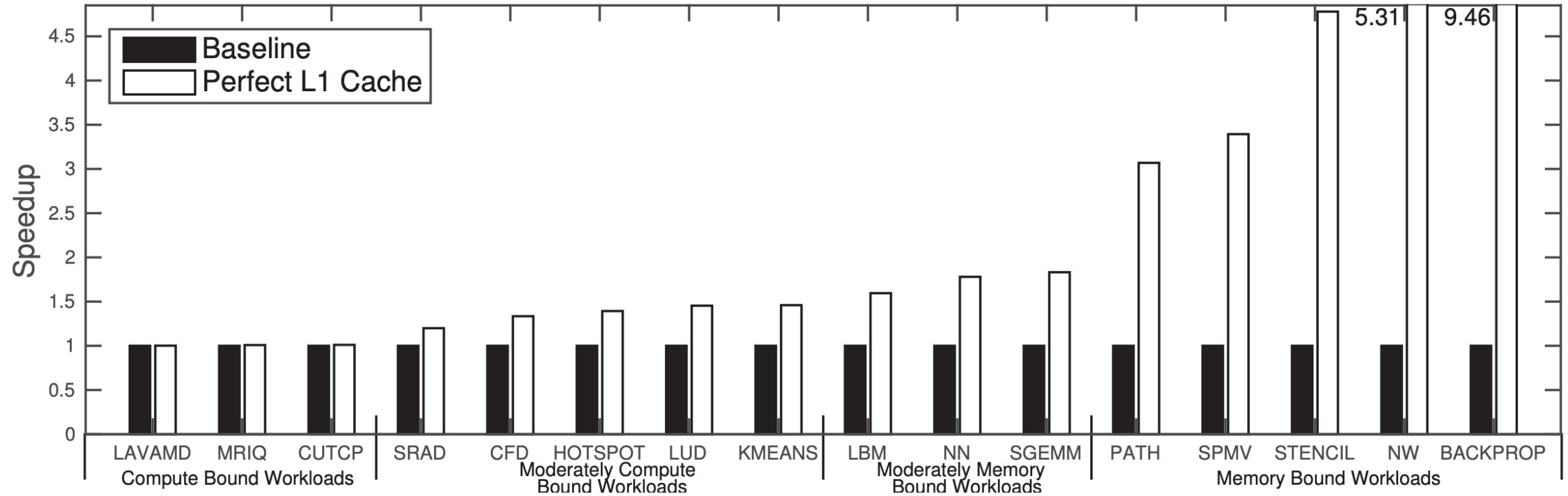
combination?

<https://www.phoronix.com/scan.php?page=article&item=gcc-clang-2019&num=1>

For general compilers, performance differences are tiny: e.g. 2%

# Benchmarks can have a variety of characteristics

*parboil and rodinia*



# Running benchmarks

- Just run it?
- Need to be careful...

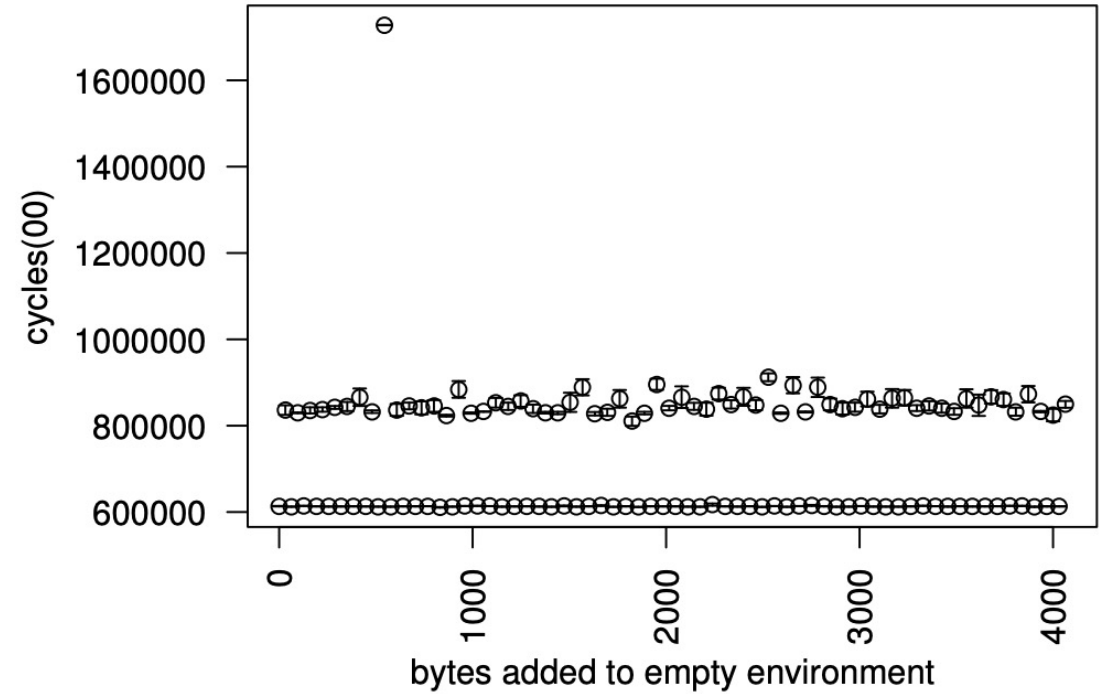


# Measurement bias

Size of environment variables on Linux?

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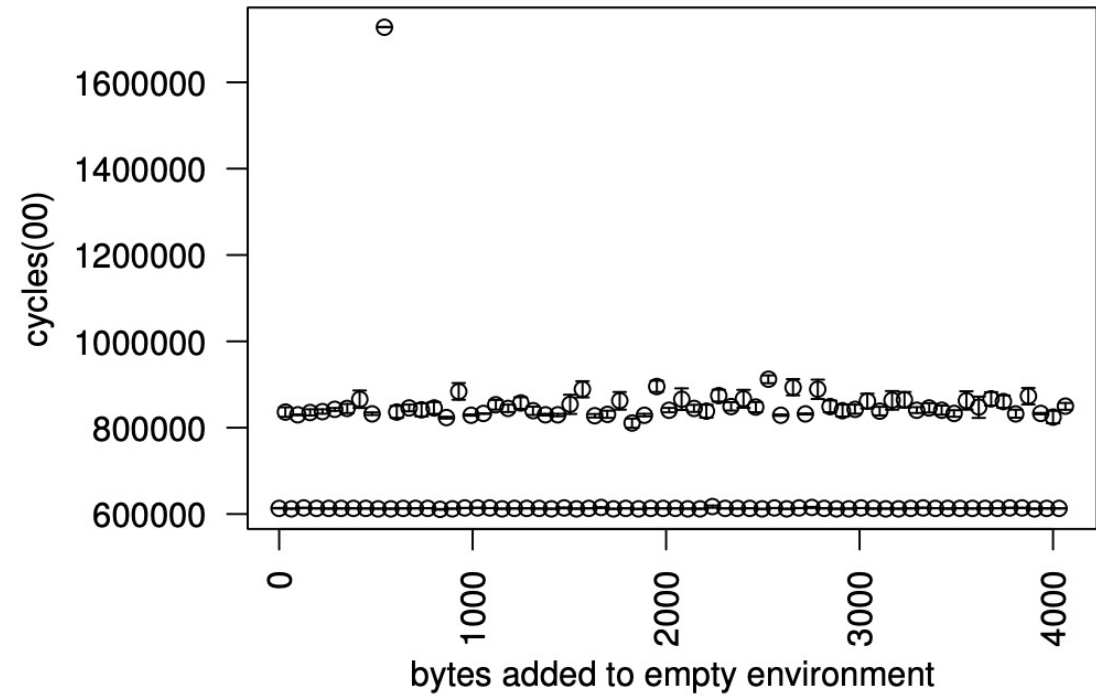


# Measurement bias

Size of environment variables on Linux?

frequently performance difference is 33%

Max is 300%





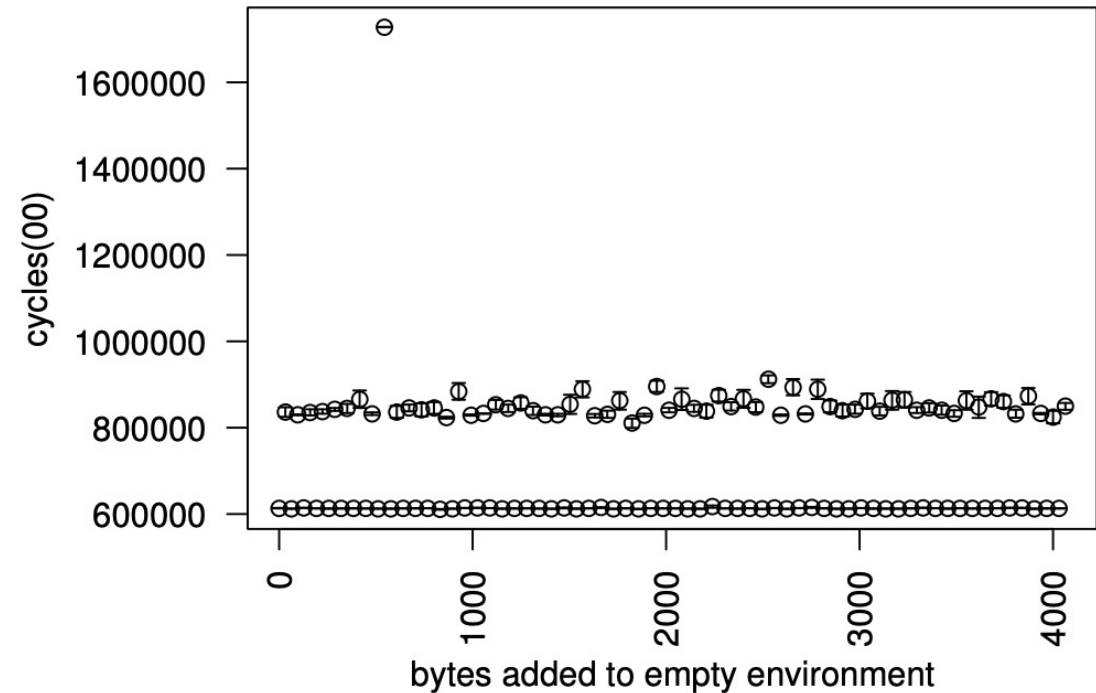
# Measurement bias

Size of environment variables on Linux?

frequently performance difference is 33%

Max is 300%

This phenomenon occurs because the UNIX environment is loaded into memory before the call stack. Thus, changing the UNIX environment size changes the location of the call stack which in turn affects the alignment of local variables in various hardware structures.



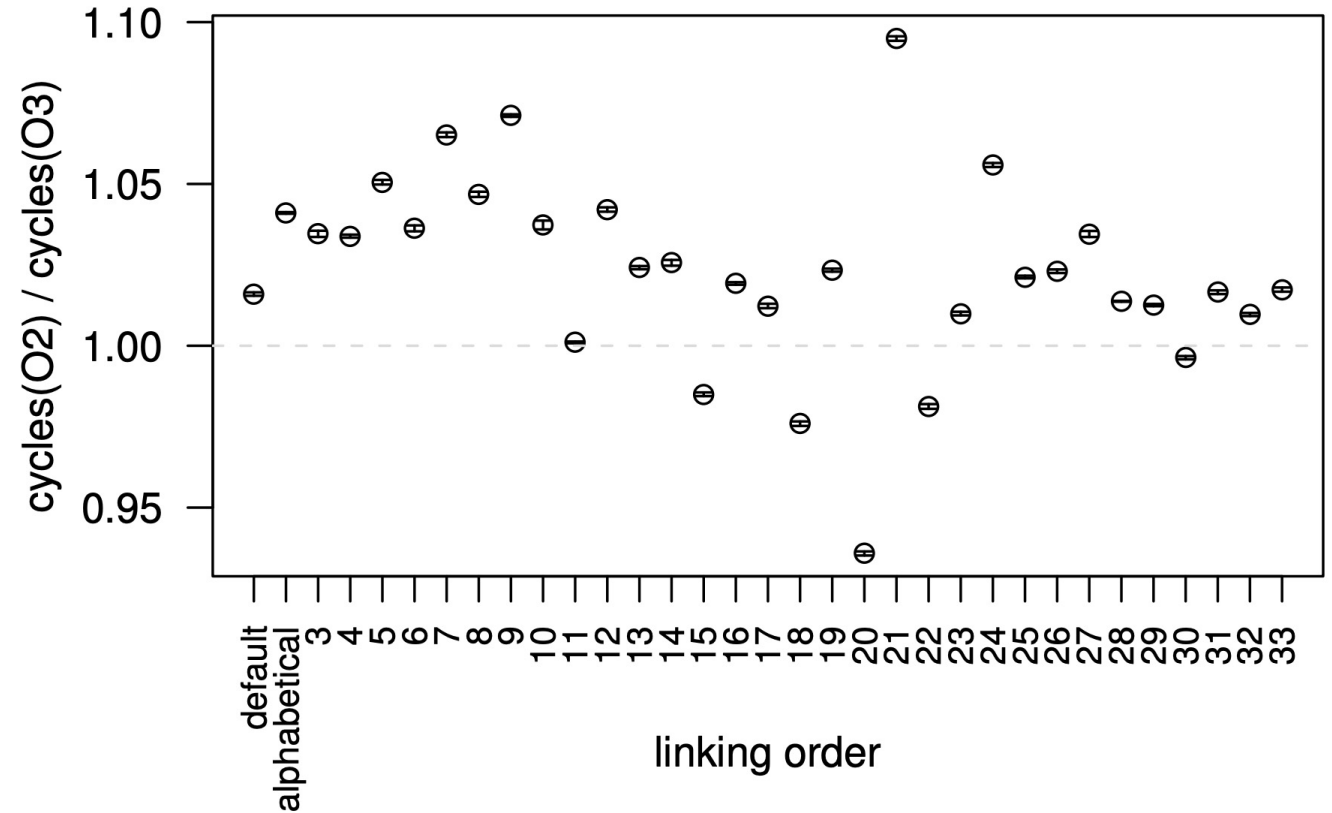
# Measurement bias

The order in which libraries are linked?

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The order in which libraries are linked?

In some cases O3 is slower than O2!



(a) Perlbench

# Measurement bias

Processes running on other cores can influence timing:

Intel chips: max of **1.15x** difference

Mobile chips: max of **10x** difference

# How to combat measurement bias?

- Run lots of times
  - The homeworks in this class have not emphasized this enough!
- Run a large enough benchmark suite
- Run in many different configurations (environment sizes, etc.)
- Results in the paper show that the difference between O2 and O3 is an average of 1.007x

# Stabilizer: a tool to help

A compiler tool to...  
evaluate compiler optimizations!

## STABILIZER: Statistically Sound Performance Evaluation

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### Abstract

Researchers and software developers require effective performance evaluation. Researchers must evaluate optimizations or measure overhead. Software developers use automatic performance regression tests to discover when changes improve or degrade performance. The standard methodology is to compare execution times before and after applying changes.

Unfortunately, modern architectural features make this approach unsound. Statistically sound evaluation requires multiple samples to test whether one can or cannot (with high confidence) reject the null hypothesis that results are the same before and after. However, caches and branch predictors make performance dependent on machine-specific parameters and the exact layout of code, stack frames, and heap objects. A single binary constitutes just one sample from the space of program layouts, regardless of the number of runs. Since compiler optimizations and code changes also alter layout, it is currently impossible to distinguish the impact of an optimization from that of its layout effects.

This paper presents STABILIZER, a system that enables the use of the powerful statistical techniques required for sound performance evaluation on modern architectures. STABILIZER forces executions to sample the space of memory configurations by repeatedly re-randomizing layouts of code, stack, and heap objects at runtime. STABILIZER thus makes it possible to control for layout effects. Re-randomization also ensures that layout effects follow a Gaussian distribution, enabling the use of statistical tests like ANOVA. We find that STABILIZER's efficiency (< 7% median overhead) and impact on the impact of LLVM's optimizations is small. We find that, while -O2

### 1. Introduction

The task of performance evaluation forms a key part of both systems research and the software development process. Researchers working on systems ranging from compiler optimizations and runtime systems to code transformation frameworks and bug detectors must measure their effect, evaluating how much they improve performance or how much overhead they impose [7, 8]. Software developers need to ensure that new or modified code either in fact yields the desired performance improvement, or at least does not cause a performance regression (that is, making the system run slower). For large systems in both the open-source community (e.g., Firefox and Chromium) and in industry, automatic performance regression tests are now a standard part of the build or release process [25, 28]. In both settings, performance evaluation typically proceeds by testing the performance of the actual application in a set of scenarios, or a range of benchmarks, both before and after applying changes or in the absence and presence of a new optimization, runtime system, etc.

In addition to measuring *effect size* (here, the magnitude of change in performance), a statistically sound evaluation must test whether it is possible with a high degree of confidence to reject the *null hypothesis*: that the performance of the new version is indistinguishable from the old. To show that a performance optimization is statistically significant, we need to reject the null hypothesis with high confidence (and show that the direction of improvement is positive). Conversely, we aim to show that it is not possible to reject the null hypothesis when we are testing for a performance regression (negative). Unfortunately, even when using current best practices (large numbers of runs and a quiescent system), the conventional approach is unsound. The problem is due to the interaction between software and modern architectural features, especially caches and branch predictors. These features are sensitive to the addresses of the objects in memory. For example, the significant performance penalty of a branch predictor is due to the significant performance penalty of a branch predictor. These features are sensitive to the addresses of the objects in memory. For example, the significant performance penalty of a branch predictor is due to the significant performance penalty of a branch predictor.







# Order in which optimizations are applied?

- Example:
  - Loop unrolling followed by ILP scheduling
  - What about the other way around?



# Compiler optimization domains

- General case:
  - Compile many diverse pieces of code, run on many different inputs and architectures
  - examples: gcc at -O3

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  - Compile one piece of code for one architecture and one input
  - examples?
  - optimizations?

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- General case:
  - Compile many diverse pieces of code, run on many different inputs and architectures
  - examples: gcc at -O3
- Fully Specialized:
  - Compile one piece of code for one architecture and one input
  - examples?
  - optimizations?
- Semi-specialized?

# Semi-specialization Examples

One binary, many architectures

- x86 binary runs on machines with different number of cores, pipeline depths, super scalar widths etc.

Many programs, one architecture

- Modern compilers are often tuned (or query device info) when they are installed

Are fully specialized applications portable?

tuned for:

Skylake CPU	90%	69%	93%	90%	90%	45%	28%	14%	21%	2%	99%	100%
Haswell CPU	12%	16%	16%	39%	43%	37%	20%	11%	17%	2%	100%	97%
Ivy Bridge CPU	21%	14%	18%	41%	40%	19%	14%	6%	13%	100%	53%	44%
RX 480	87%	74%	78%	95%	93%	99%	99%	97%	100%	2%	93%	81%
R9 Fury X	24%	20%	20%	23%	37%	100%	99%	100%	99%	62%	80%	65%
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HD 7970	23%	19%	20%	21%	33%	100%	100%	99%	100%	73%	85%	71%
GTX 1080 Ti	91%	97%	58%	98%	100%	68%	38%	28%	62%	1%	5%	4%
GTX 980 Ti	71%	69%	51%	100%	92%	53%	33%	49%	36%	5%	5%	5%
GTX 780 Ti	93%	66%	100%	95%	90%	68%	33%	32%	62%	5%	5%	4%
GTX 680	92%	100%	71%	98%	98%	55%	38%	26%	57%	1%	5%	4%
GTX 580	100%	87%	74%	53%	56%	X	X	X	X	1%	5%	4%
	<i>GTX 580</i>	<i>GTX 680</i>	<i>GTX 780 Ti</i>	<i>GTX 980 Ti</i>	<i>GTX 1080 Ti</i>	<i>HD 7970</i>	<i>R9 290X</i>	<i>R9 Fury X</i>	<i>RX 480</i>	<i>Ivy Bridge CPU</i>	<i>Haswell CPU</i>	<i>Skylake CPU</i>

ran on:



# Tuning for same vendor?

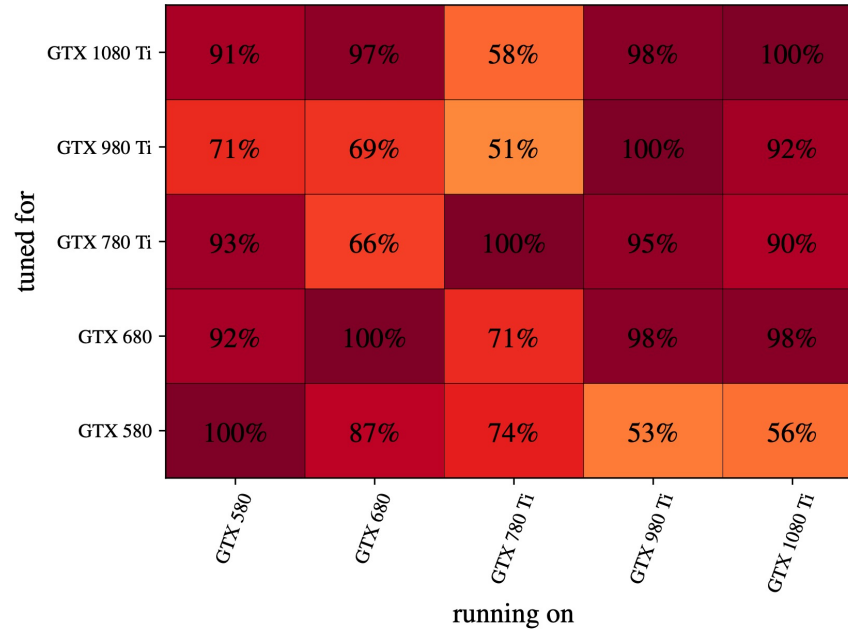
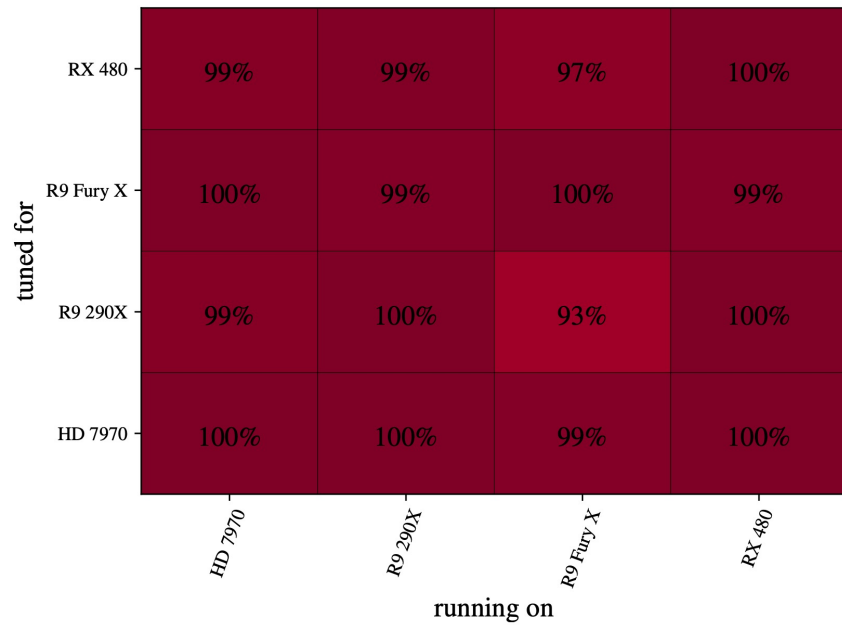
AMD

	HD 7970	R9 290X	R9 Fury X	RX 480
RX 480	99%	99%	97%	100%
R9 Fury X	100%	99%	100%	99%
R9 290X	99%	100%	93%	100%
HD 7970	100%	100%	99%	100%

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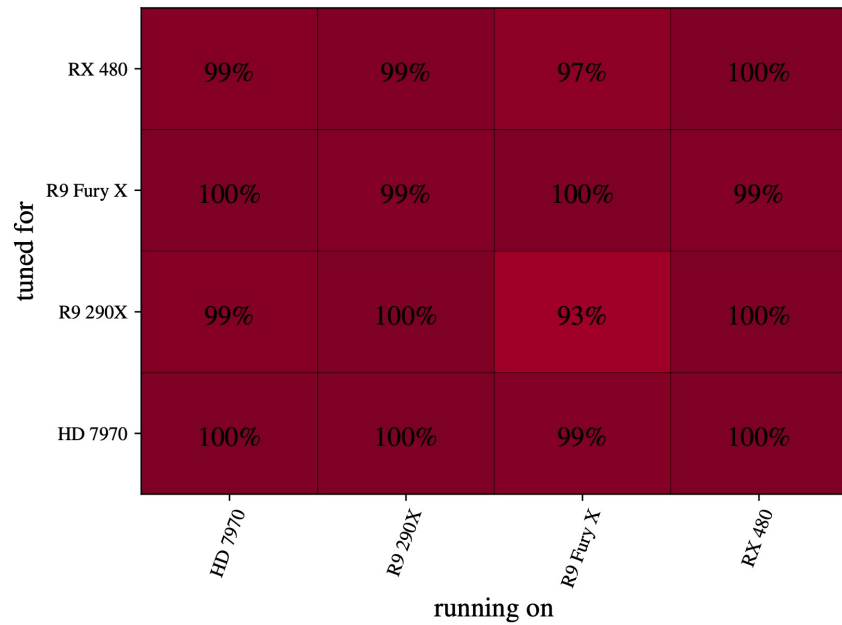
AMD

Nvidia

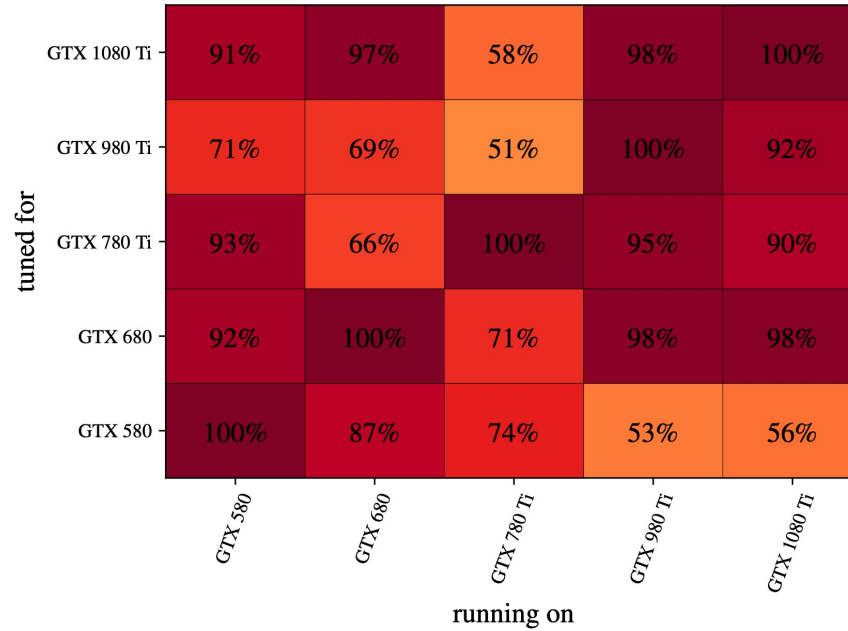


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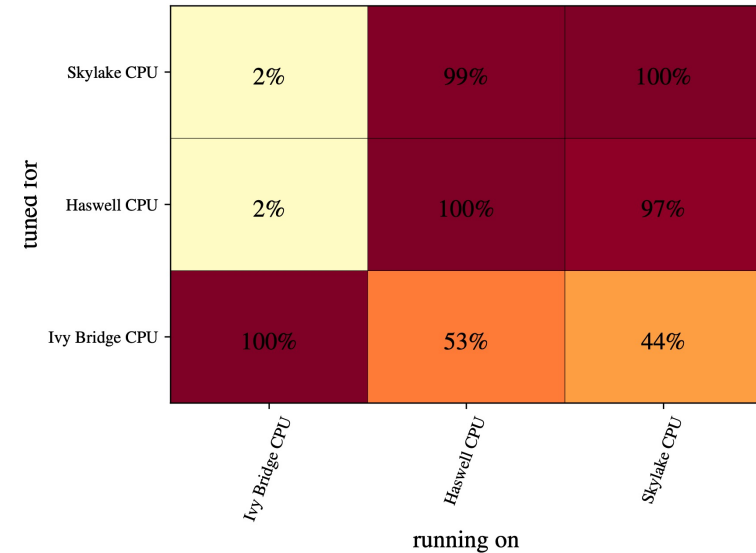
AMD



Nvidia



Intel



# Multi-objective tuning

- Example, being portable across architectures:
- $E(p, i, a, o)$  is the execution time of running program  $p$  on input  $i$  on architecture  $a$  with optimization settings  $o$
- How to evaluate a binary optimization  $c$ ?
  - i.e. should  $c$  be enabled?

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$$\frac{E(p, i, a_0, o)}{E(p, i, a_0, o + c)}$$



$$\frac{E(p, i, a_1, o)}{E(p, i, a_1, o + c)}$$



$$\frac{E(p, i, a_2, o)}{E(p, i, a_1, o + c)}$$

# Multi-objective tuning

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$speedup_0$



$speedup_1$



$speedup_n$

# Multi-objective tuning

- How to evaluate a binary optimization  $c$ ?
  - i.e. should  $c$  be enabled?
- Define a fitness function  $F$  to collapse multiple speedups into a single value:
  - $F(\textit{speedup}_0, \textit{speedup}_1, \textit{speedup}_2)$



$\textit{speedup}_0$



$\textit{speedup}_1$



$\textit{speedup}_n$



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- Options?

# Multi-objective tuning

- How to evaluate a binary optimization  $c$ ?
  - i.e. should  $c$  be enabled?
- Define a fitness function  $F$  to collapse multiple speedups into a single value:
  - $F(\textit{speedup}_0, \textit{speedup}_1, \textit{speedup}_2)$
- Options?
  - average (geomean)
  - max, min?

# Multi-objective tuning

- How to evaluate a binary compiler optimization  $c$
- Baseline: runtimes at  $E(p, i, a_n, o)$ 
  - $p$  is a program
  - $i$  is an input
  - $a_n$  is an architecture (we can have many of these)
  - $o$  is an optimization setting. The baseline has  $c$  disabled
- Call a baseline runtime for architecture  $n$  :  $B_n$

# Multi-objective tuning

- How to evaluate a binary compiler optimization  $c$
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  - $a_n$  is an architecture (we can have many of these)
  - $o$  is an optimization setting. The baseline has  $c$  disabled
- Call a baseline runtime for architecture  $n$  :  $B_n$
- optimization times: evaluate runtimes at  $E(p, i, a_n, o + c)$ 
  - Same programs and baselines, except with  $c$  enabled
  - Call these runtimes :  $C_n$

# Multi-objective tuning

A speedup for architecture  $n$  is  $\frac{B_n}{C_n}$ , call it  $S_n$

Check:

$$F(S_0, S_1, S_2, \dots, S_n) > 1.0$$

For example: if  $F$  is the **average**, then this will measure if the average effect of the optimization caused a speedup or slowdown.

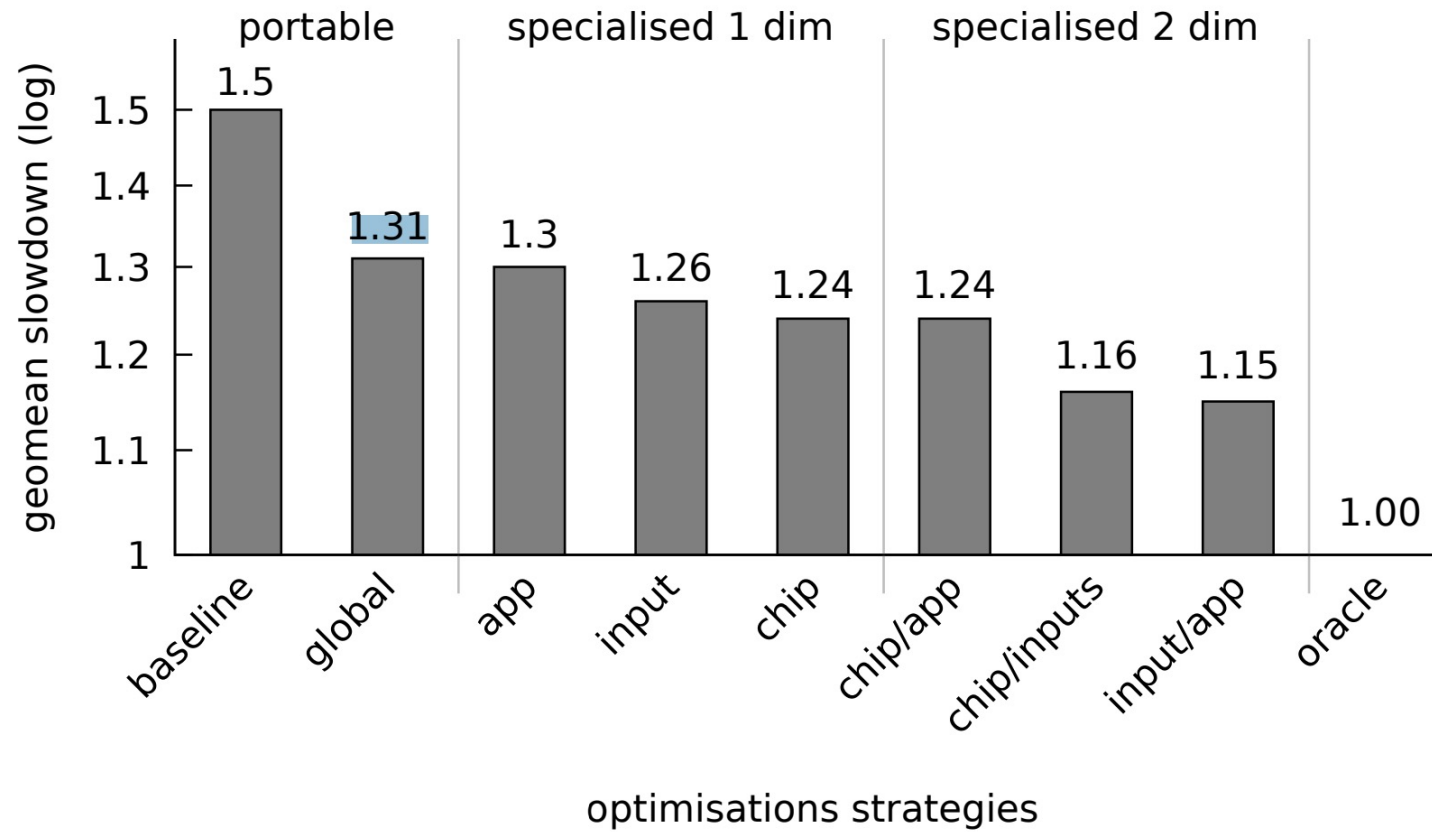
If  $F$  is **min**, then this will determine if the worst-off architecture still saw a speedup.

# Multi-objective tuning

- Options?
  - average (geomean)
  - max, **min**?
- For 3 applications, architecture portability got within:
- 85%, 70% and 70% of maximum performance

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# Performance Penalties for Portability



# Wrapping up

- No class on Wednesday
- Friday is an extended class, keep an eye out for sign-up sheets for presenters
- Office hours on Tuesday (2-3 pm) and Thursday (2-3 pm)