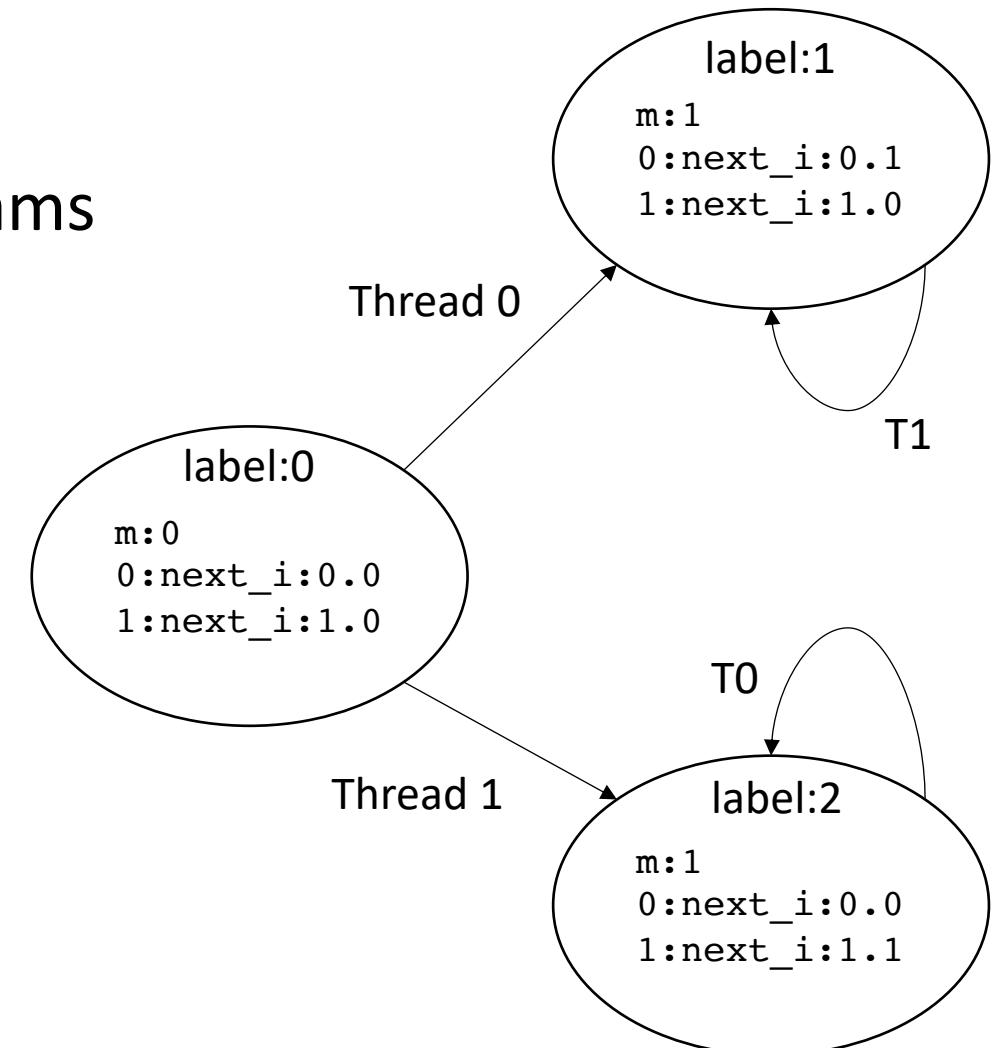


# CSE113: Parallel Programming

May 25, 2021

- **Topic:** Reasoning about concurrent programs

- Labelled Transition Systems
- Liveness Properties
- Schedulers



# Announcements

- Homework 4 is posted:
  - Due June 7th
  - PLEASE do not turn this one in late!
  - Already a typo posted in piazza (will fix tonight)
- Behind schedule a bit (grading, HW assigned, etc)
  - HW 5 is canceled
  - Each HW is worth 12.5% of your final grade
  - For those interested in GPGPU programming: The book CUDA by Example is linked on the class resource page
- HW2 grades planning on being released by midnight tomorrow!

# Announcements

- SETs are out:
  - Please remember to fill them out! They are very important, especially for new classes and new faculty
  - Any other feedback is welcome! Feel free to email or discuss during office hours

# Announcements

- Today will finish up Module 4
- Last 3 lectures: heterogeneous and distributed computing:
  - 2 lectures by me about GPGPU programming
  - last lecture by Reese about distributed system programming

# Quiz

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- Discuss answers

# Schedule

- **Labeled Transition Systems**
- Scheduler specifications

# How do we think about concurrency?

- When you write a concurrent program, how do you think about what can happen?

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- Thread Sanitizer?

# How do we think about concurrency?

- When you write a concurrent program, how do you think about what can happen?
- Interleavings?
- RMWs?
- Thread Sanitizer?
- Run the program and pray to the gods of concurrency?

Think about two threads accessing the bank account

getting paid

```
Thread 0:
//lock
while(CAS(&m,0,1) == false);
int tmp = *bank_account;
tmp++;
*bank_account = tmp;
m.store(0); //unlock
```

buying coffee

```
Thread 1:
//lock
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*assuming sequential consistency*



global timeline

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Keep track of next instruction  
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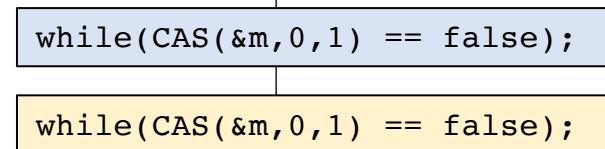
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acquired lock  
Tried and failed



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*assuming sequential consistency*

global timeline

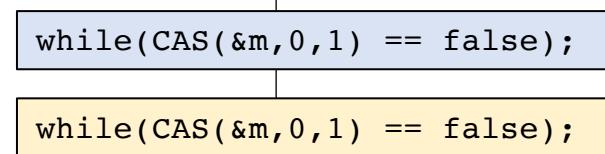
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which thread to pick next?

*assuming sequential consistency*

global timeline

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Tried and failed

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step 1 pick a thread

Keep track of next instruction  
to execute

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Keep track of next instruction  
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which thread to pick next?

*assuming sequential consistency*

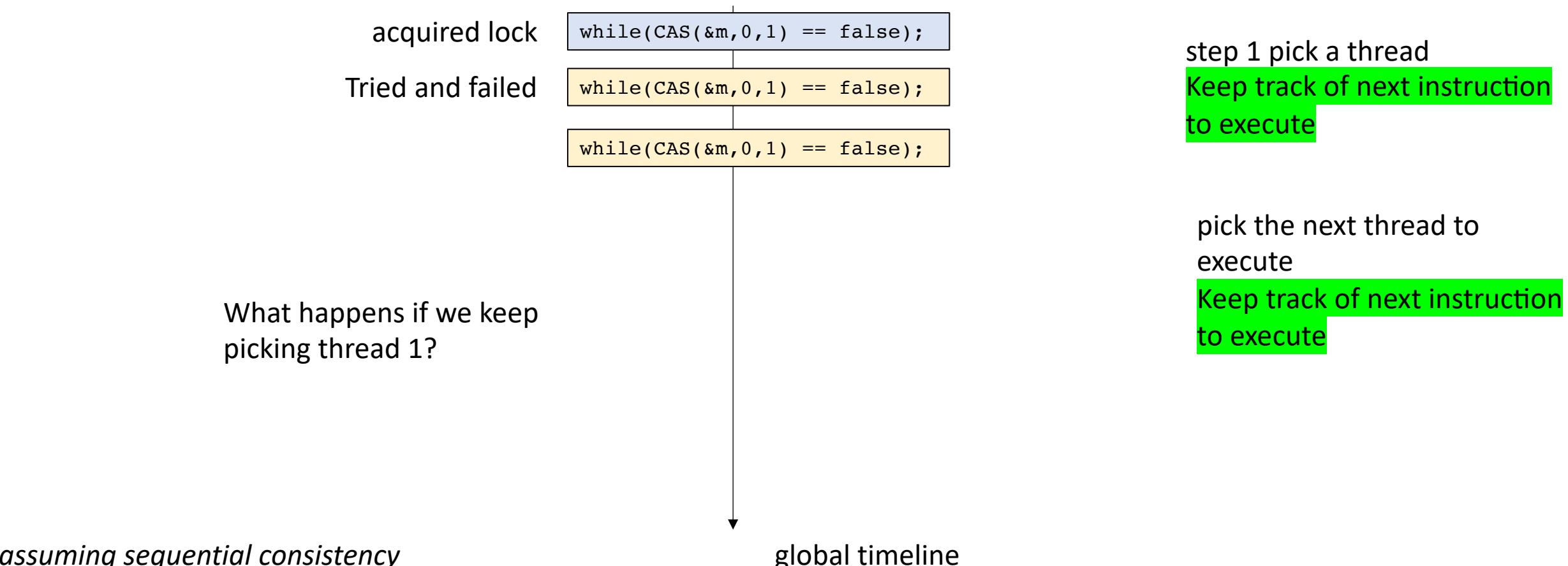
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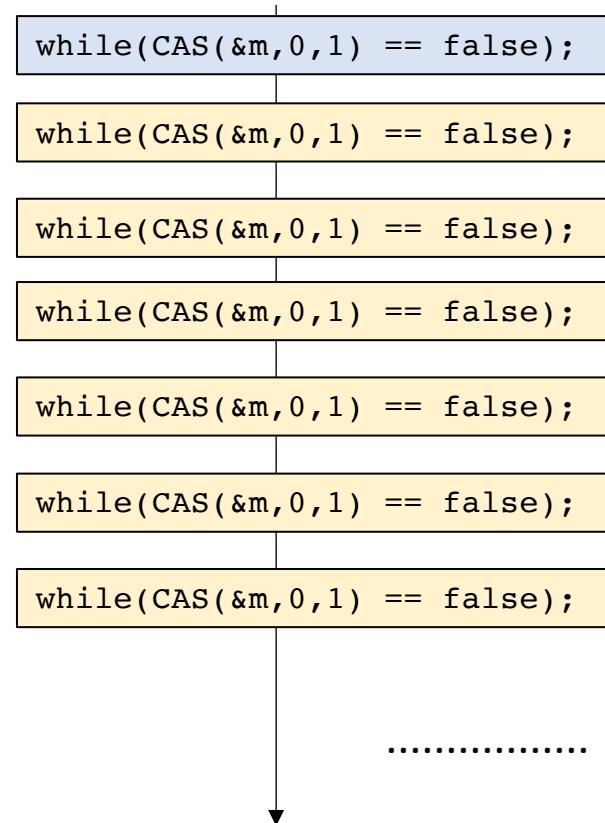
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```

acquired lock

## Tried and failed

Thread 1  
waiting  
for Thread 0  
to release  
the lock



*assuming sequential consistency*

# global timeline

## Can this keep going forever?

Is this program guaranteed  
to terminate?

# Why? Why not?

# A new way to represent concurrent executions

- Global timeline fails to capture the full picture
- Introducing Labelled Transition System (LTS)
  - Concurrent execution in a graph form.

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Lets only think about the locks and unlocks  
assume any critical section

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program location

Thread 1:

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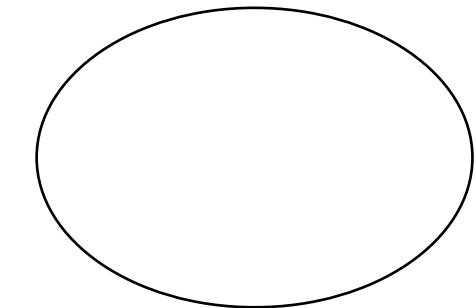
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Start making our graph, with a starting node:



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global variable values

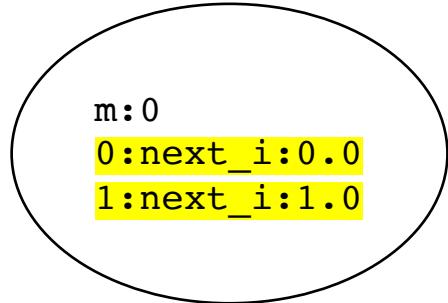
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global variable values  
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label:0

m:0  
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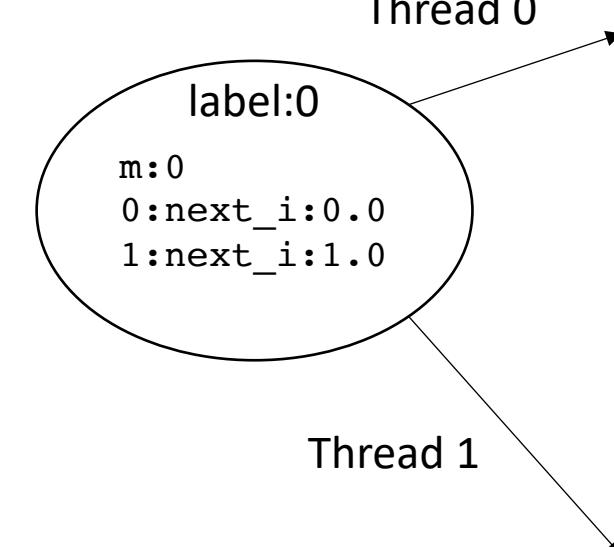
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label:0

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Thread 1

two choices:  
thread 0 executes, or thread 1 executes

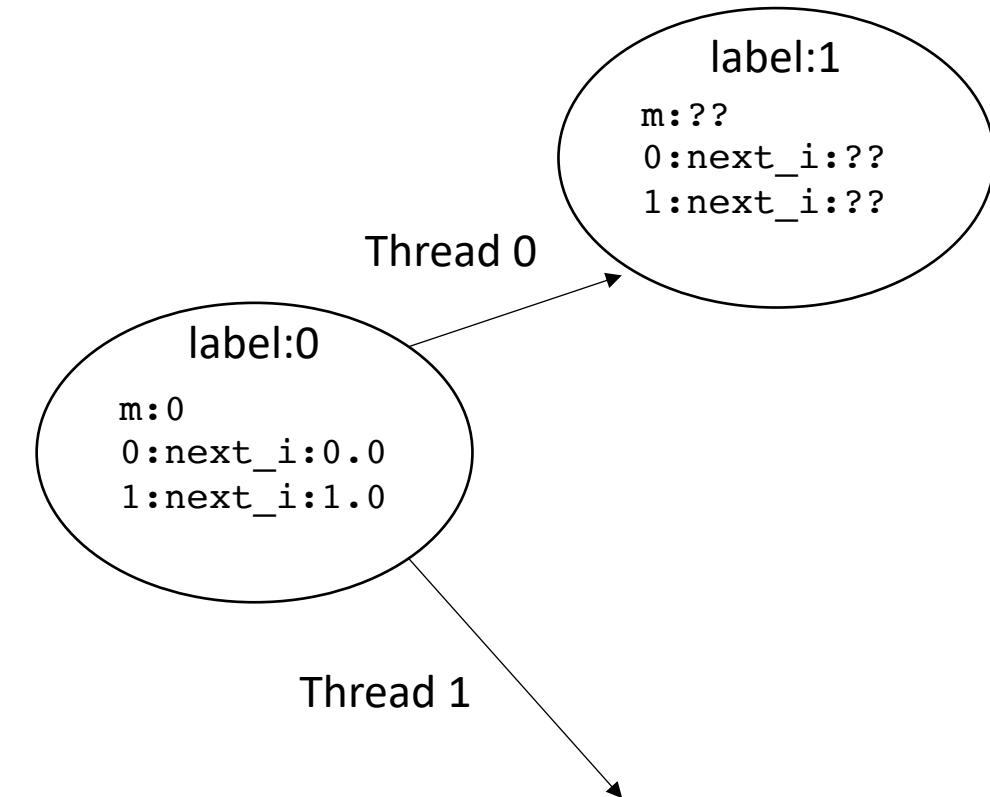


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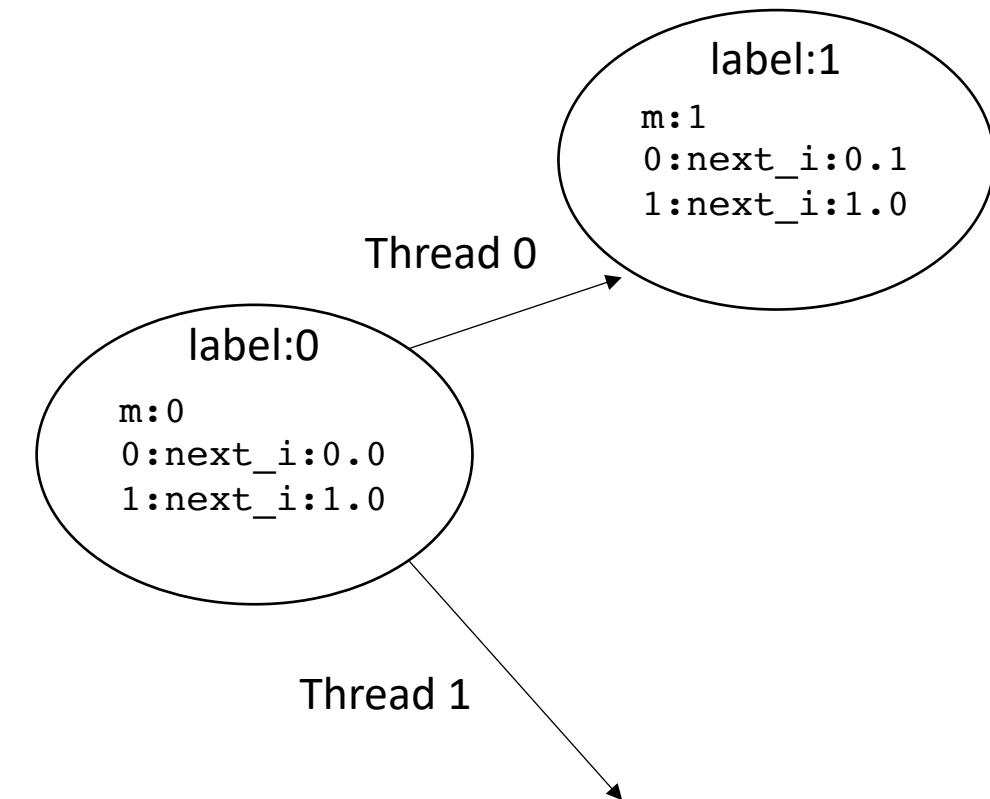


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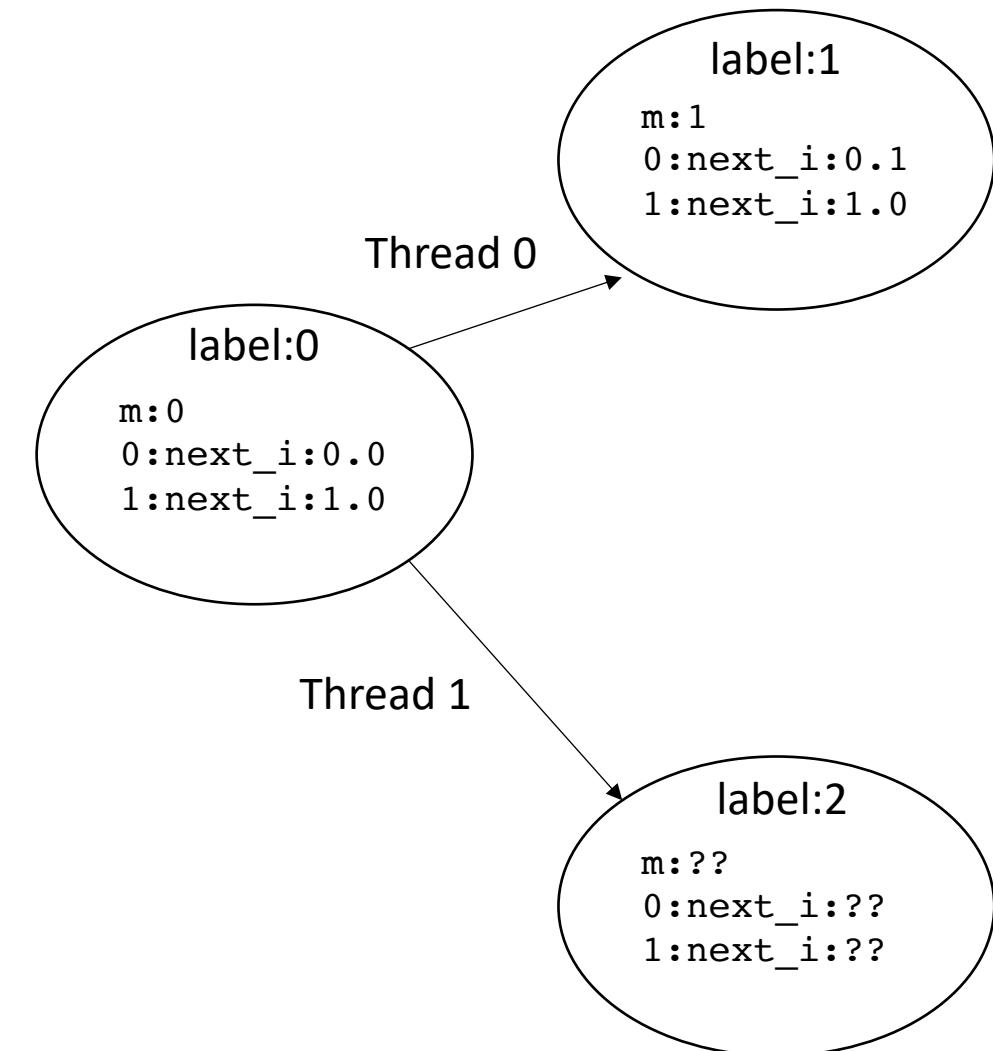


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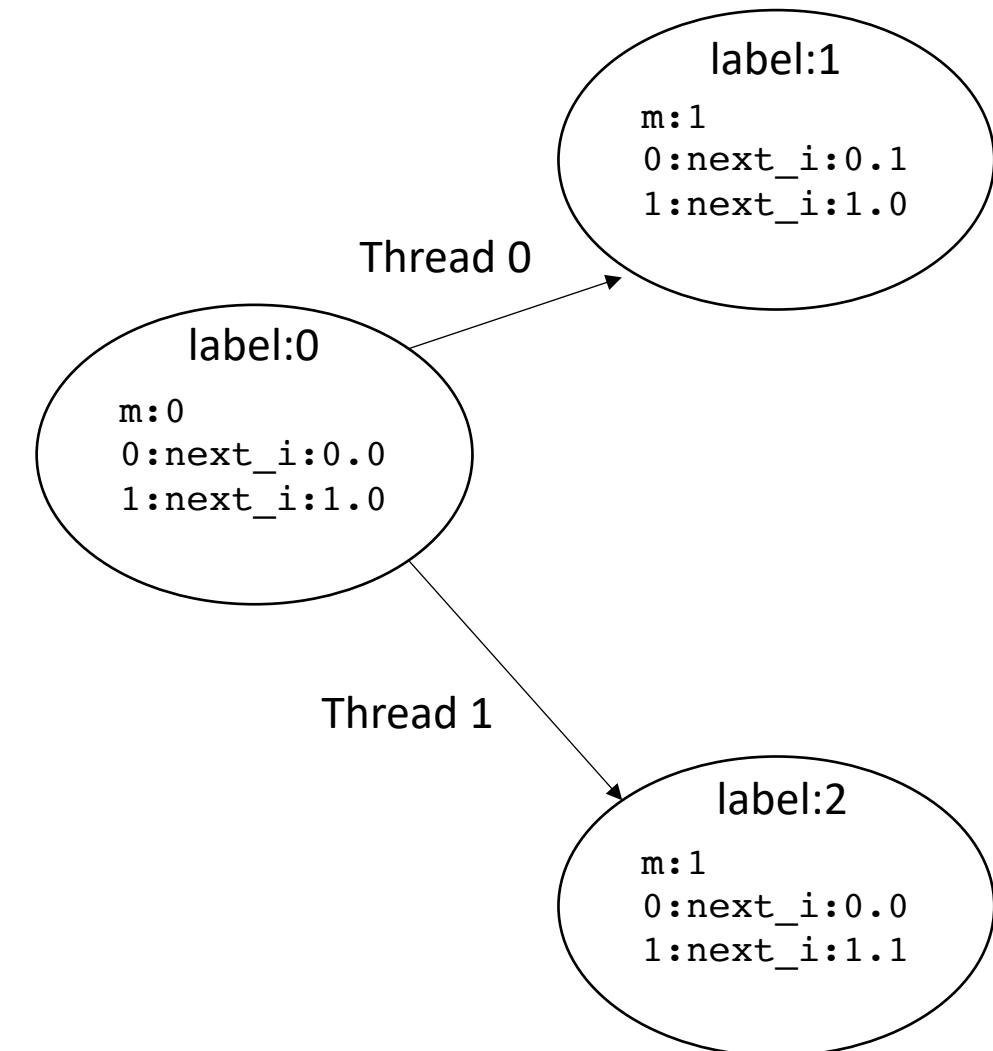


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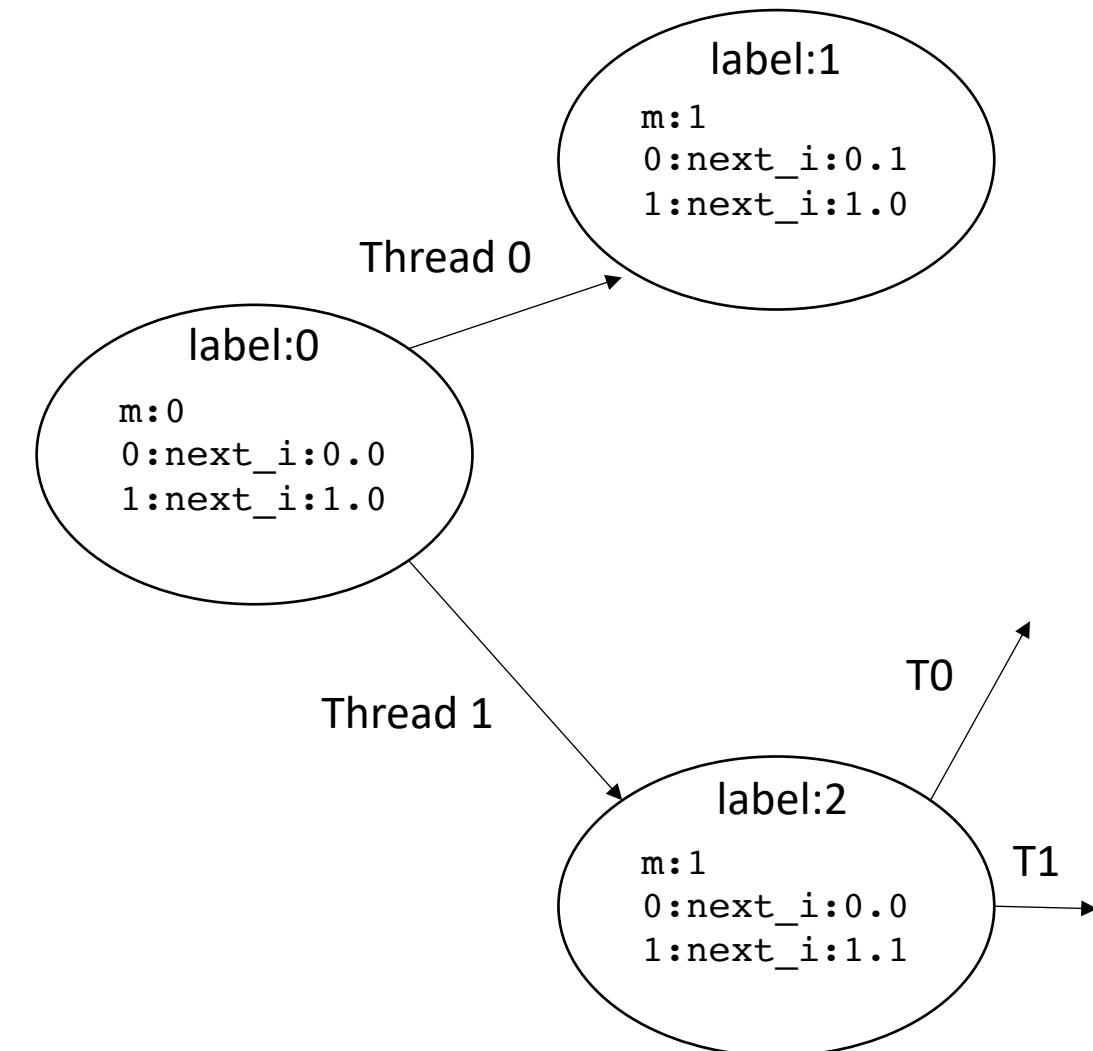


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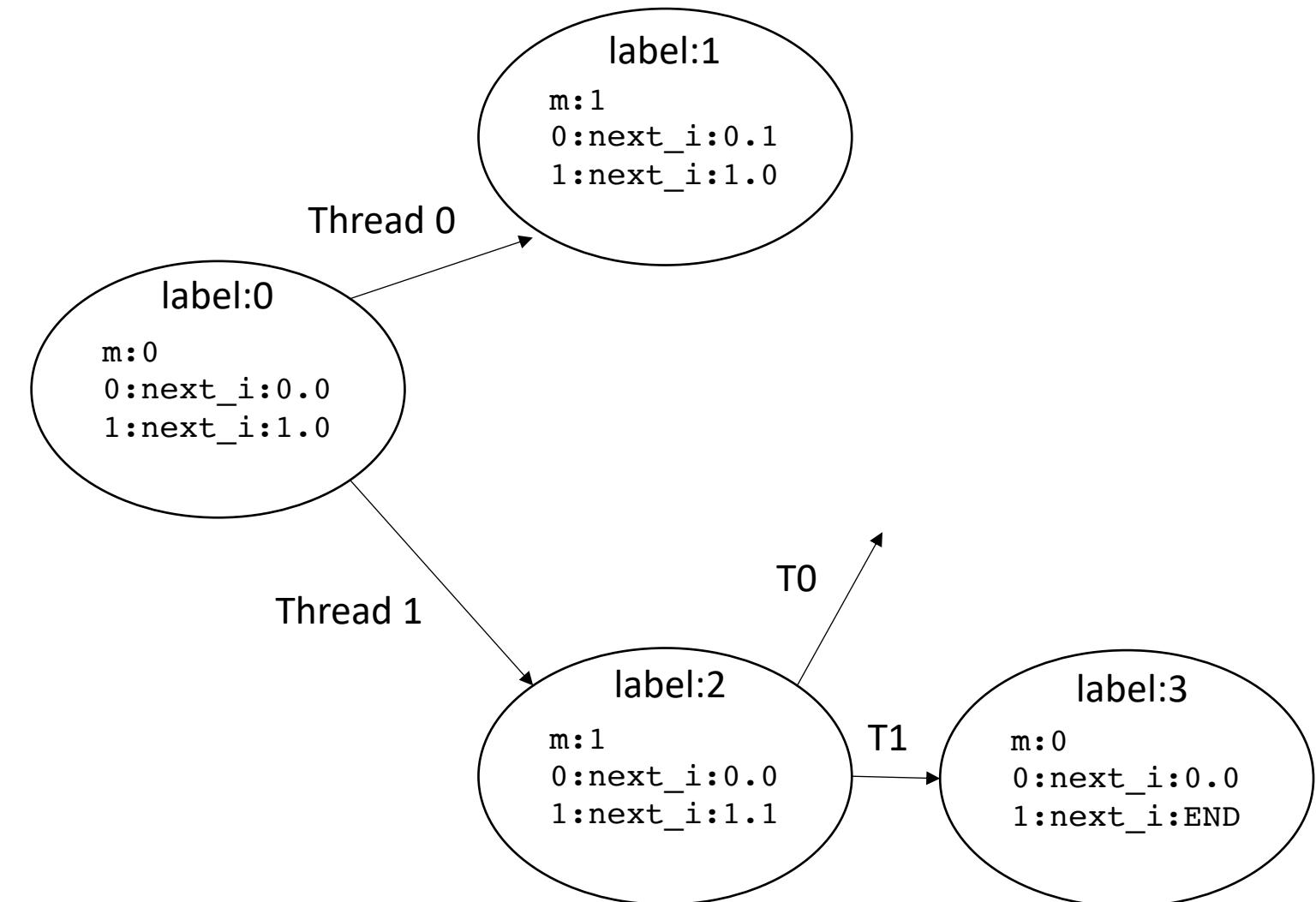
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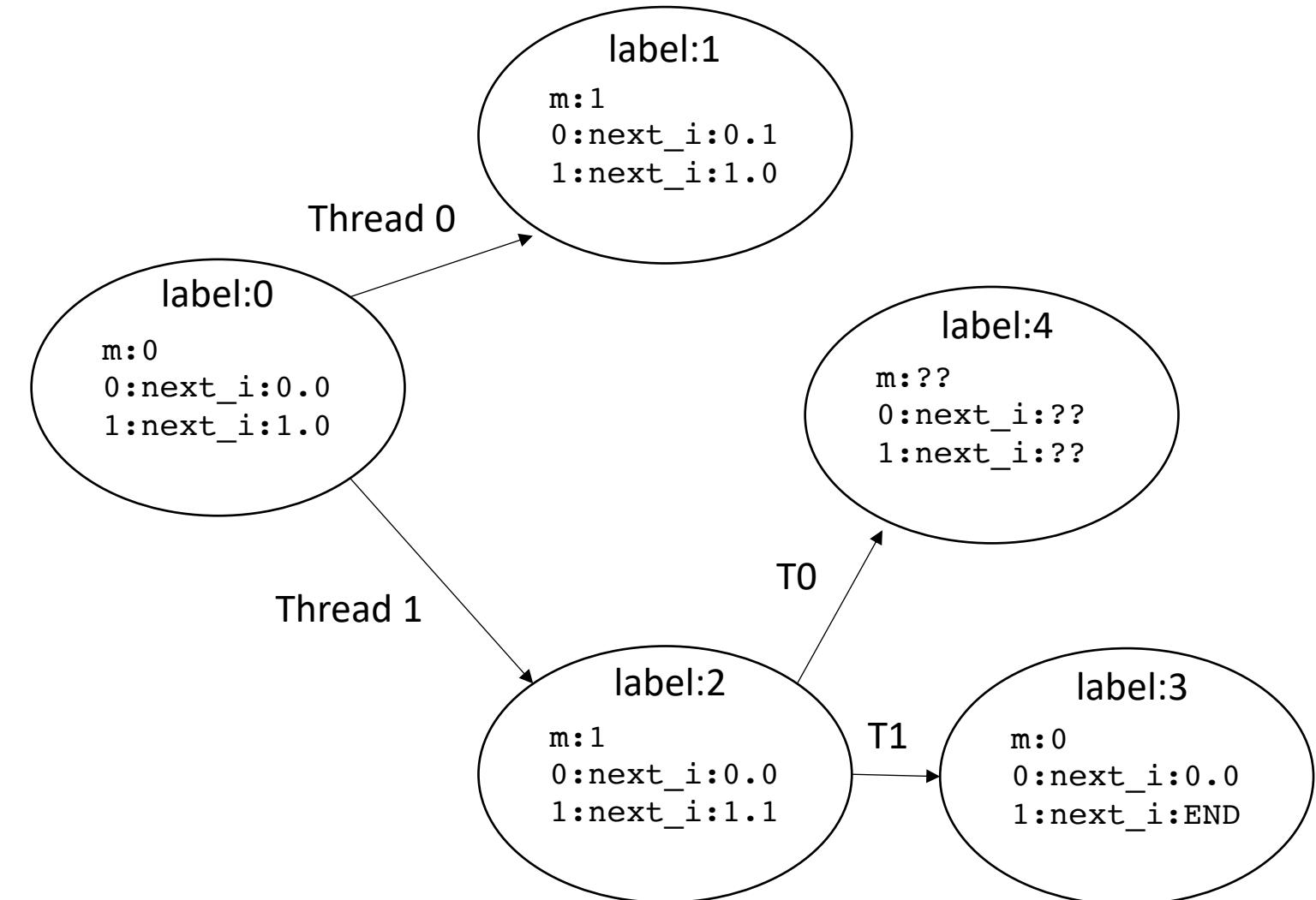
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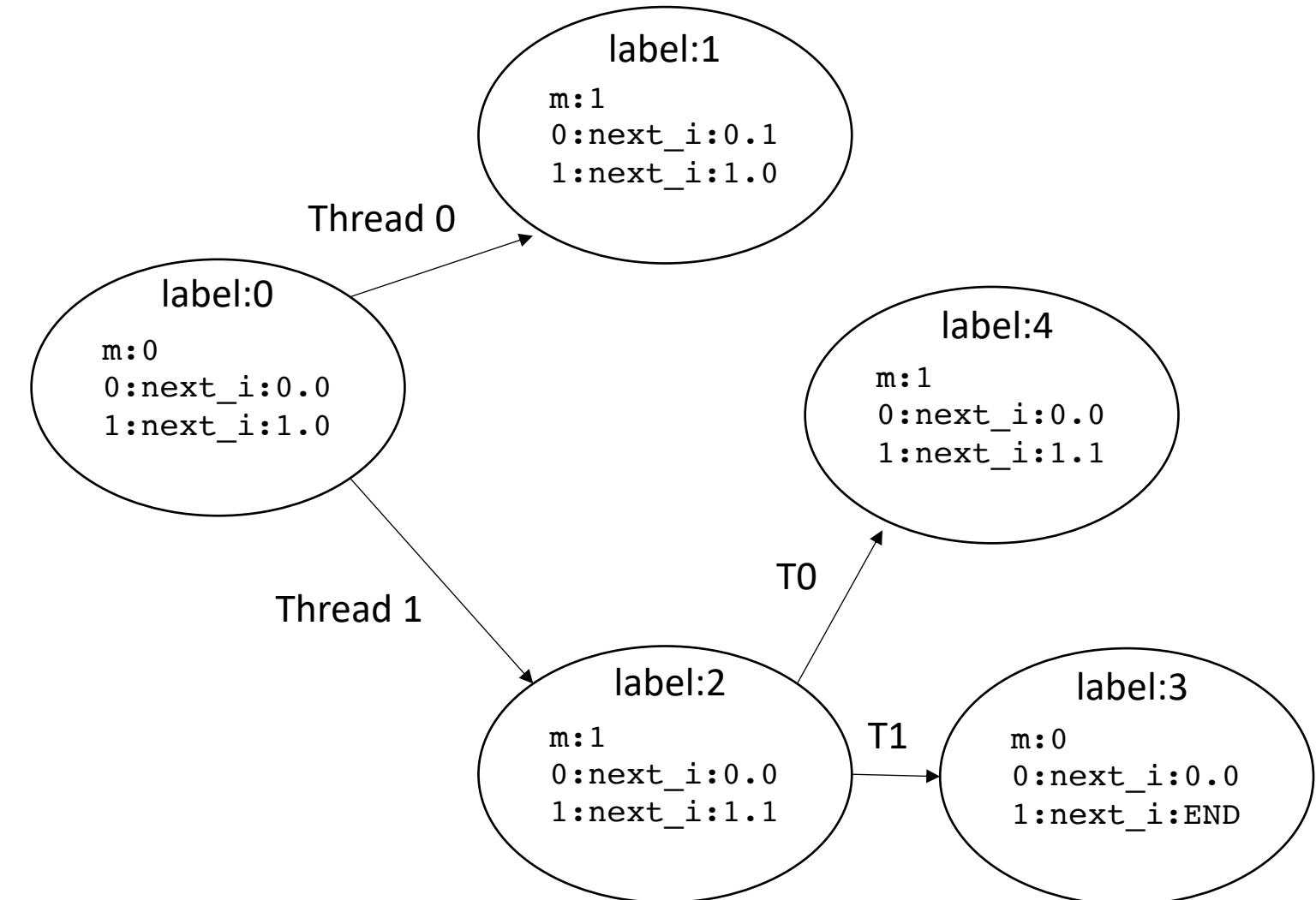
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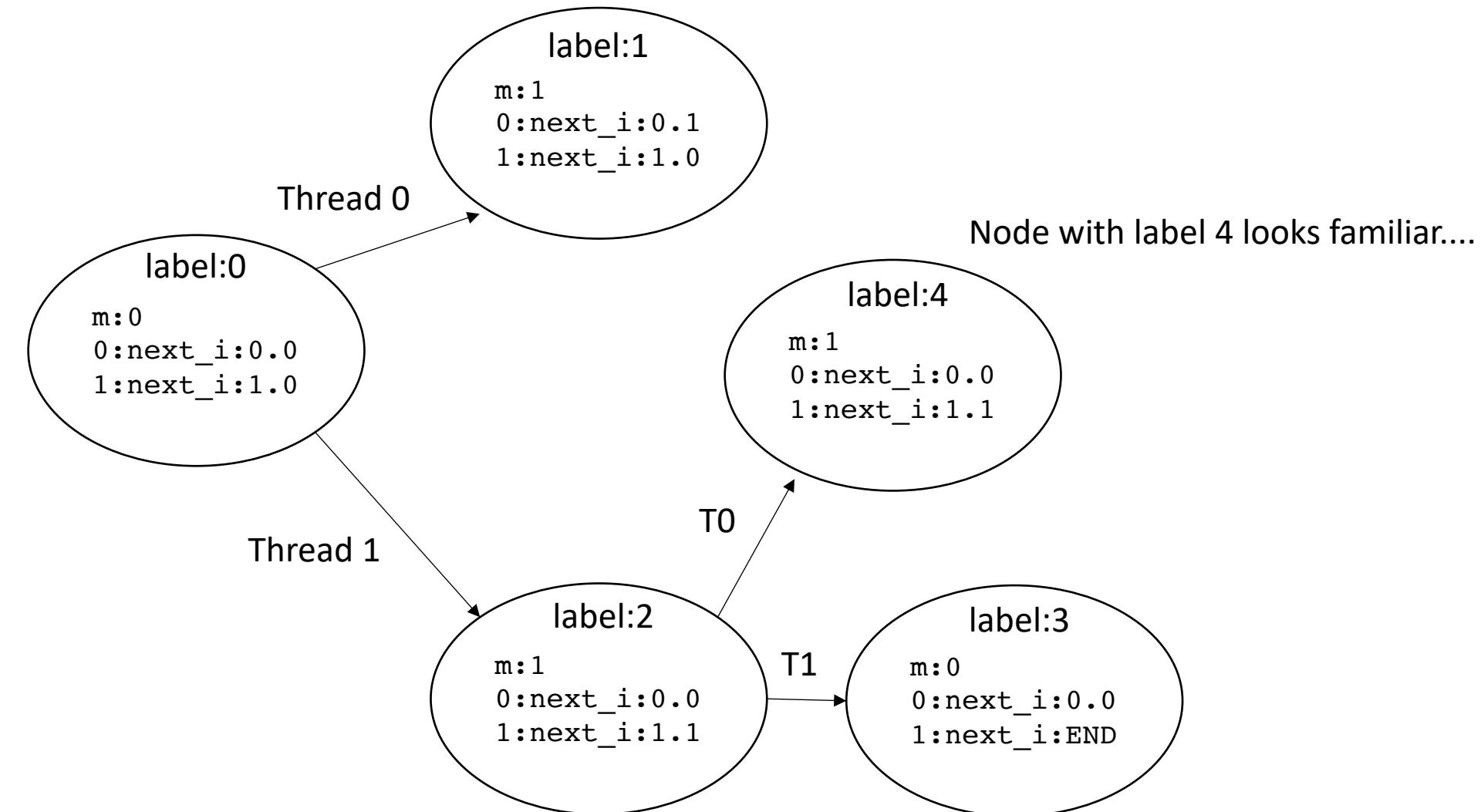
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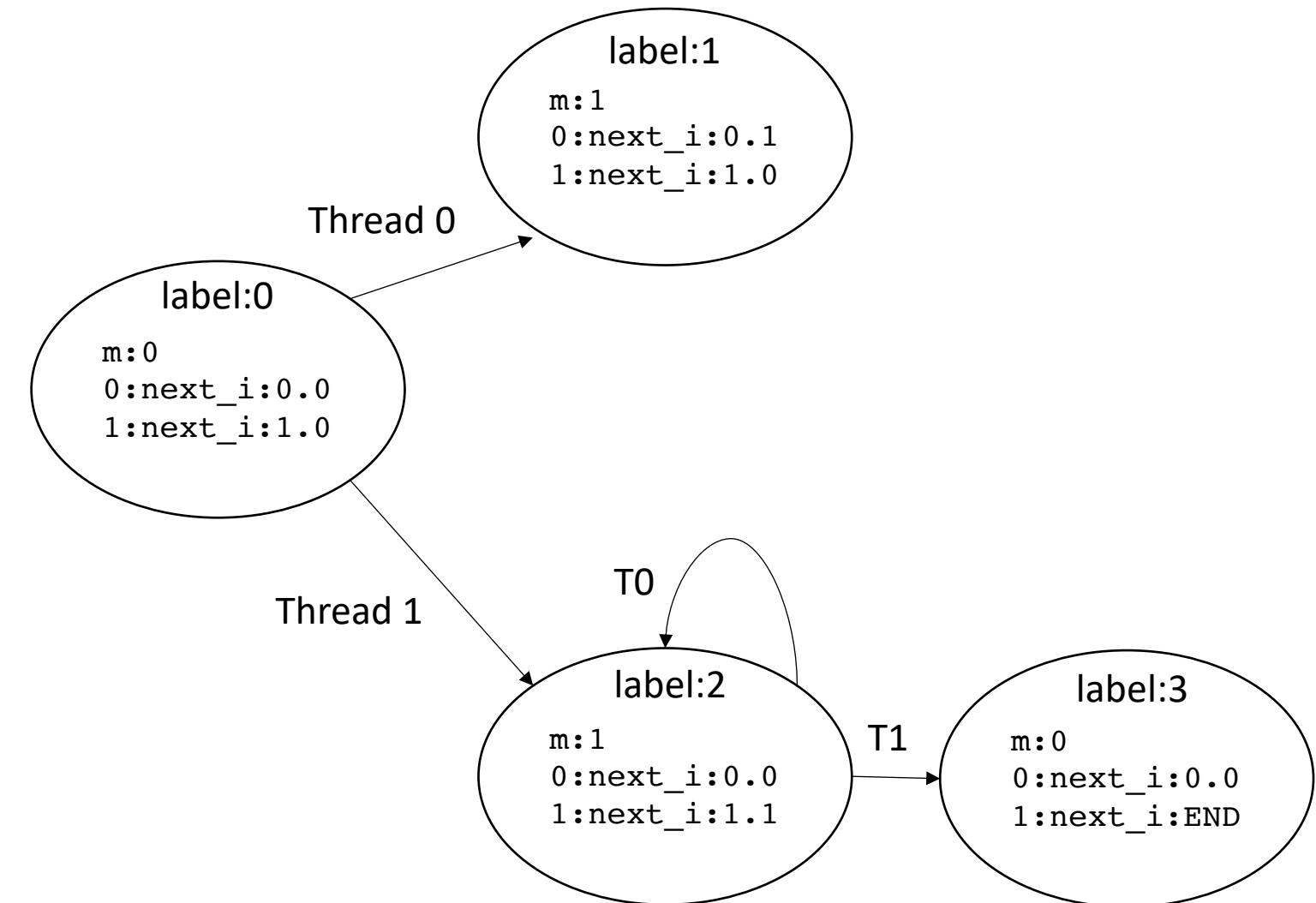


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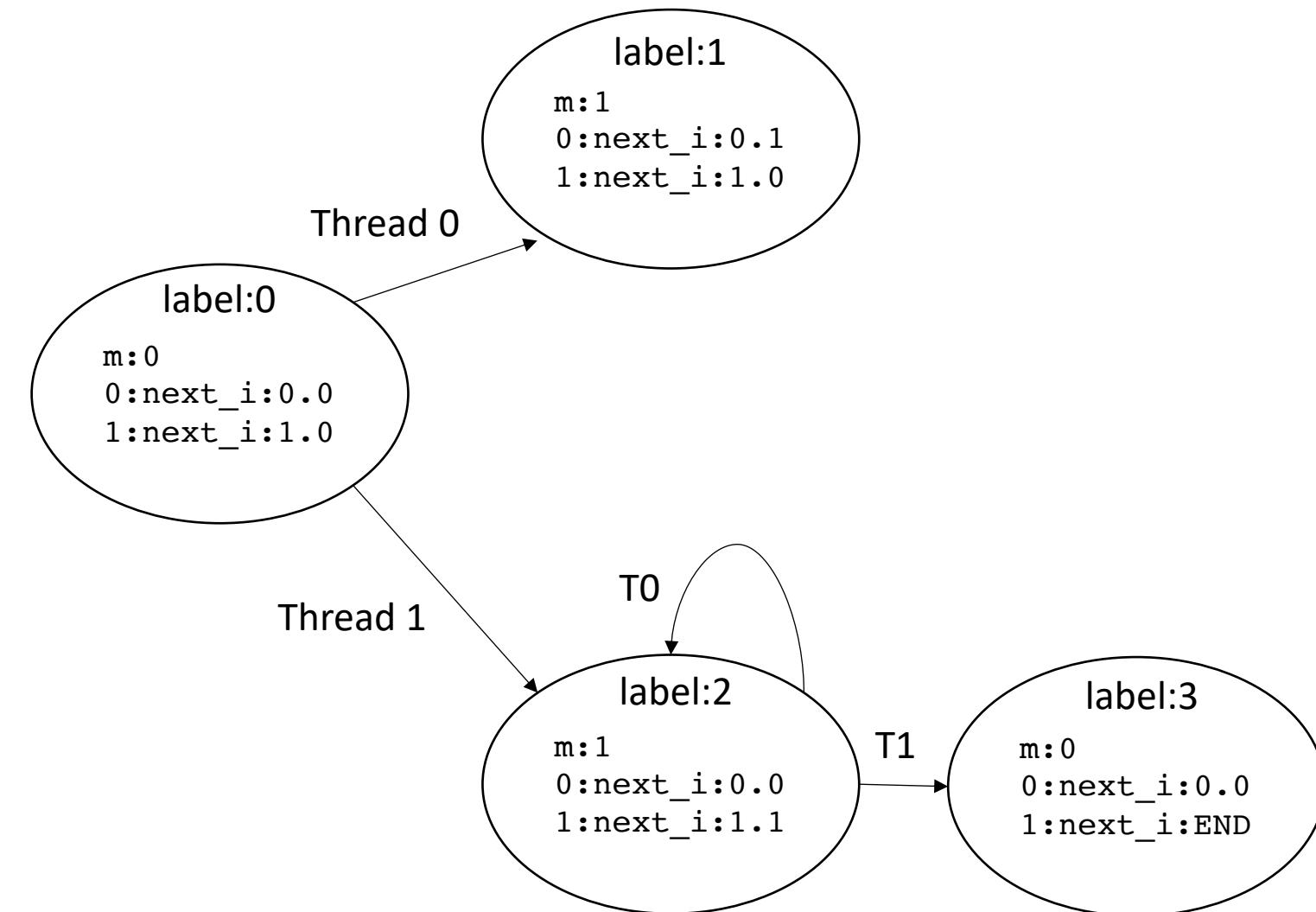


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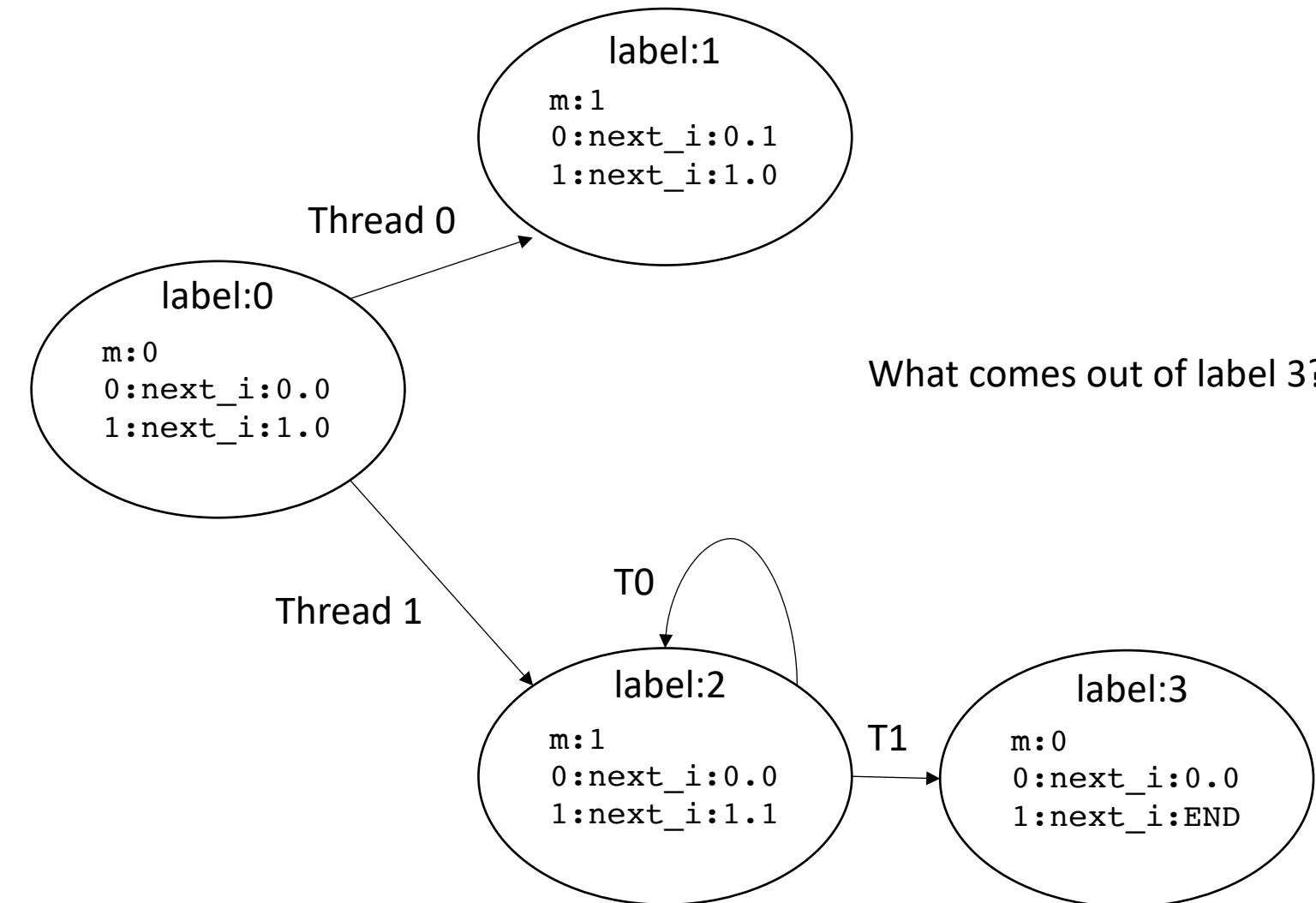


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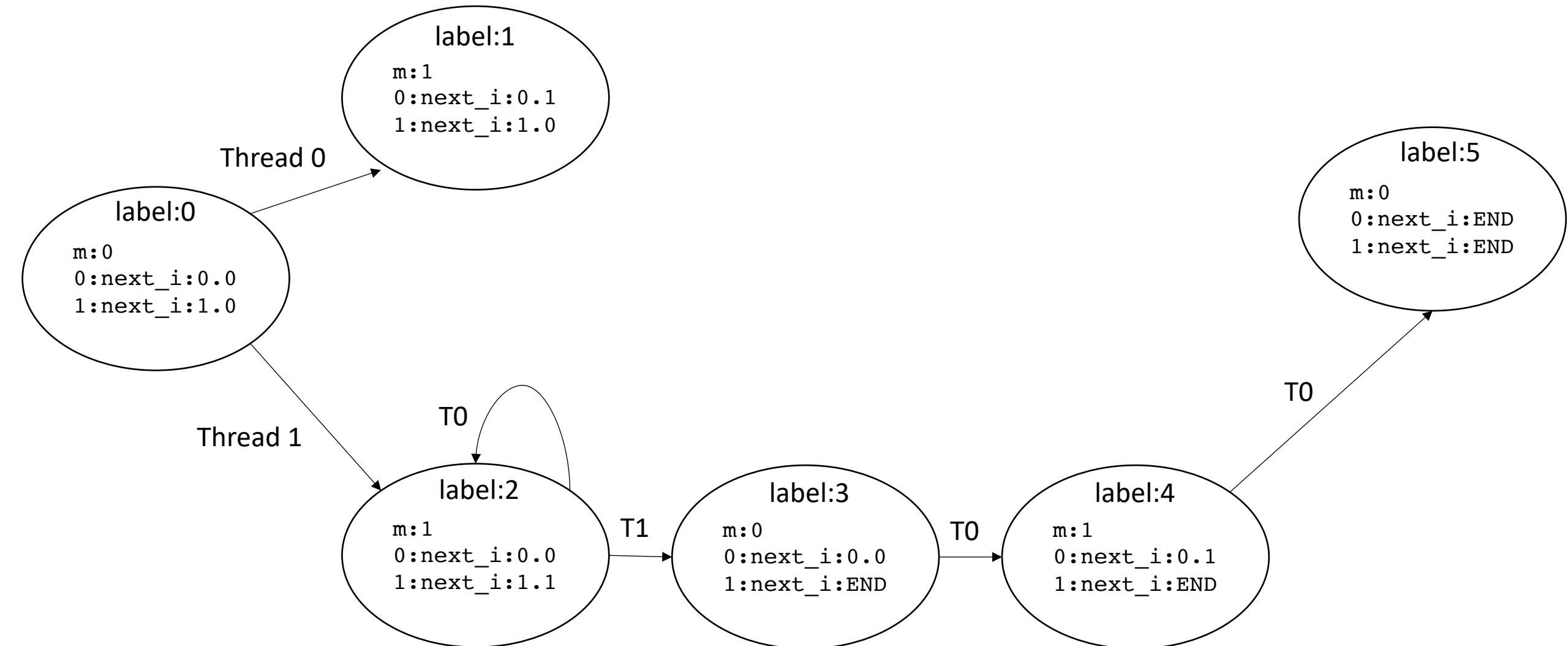


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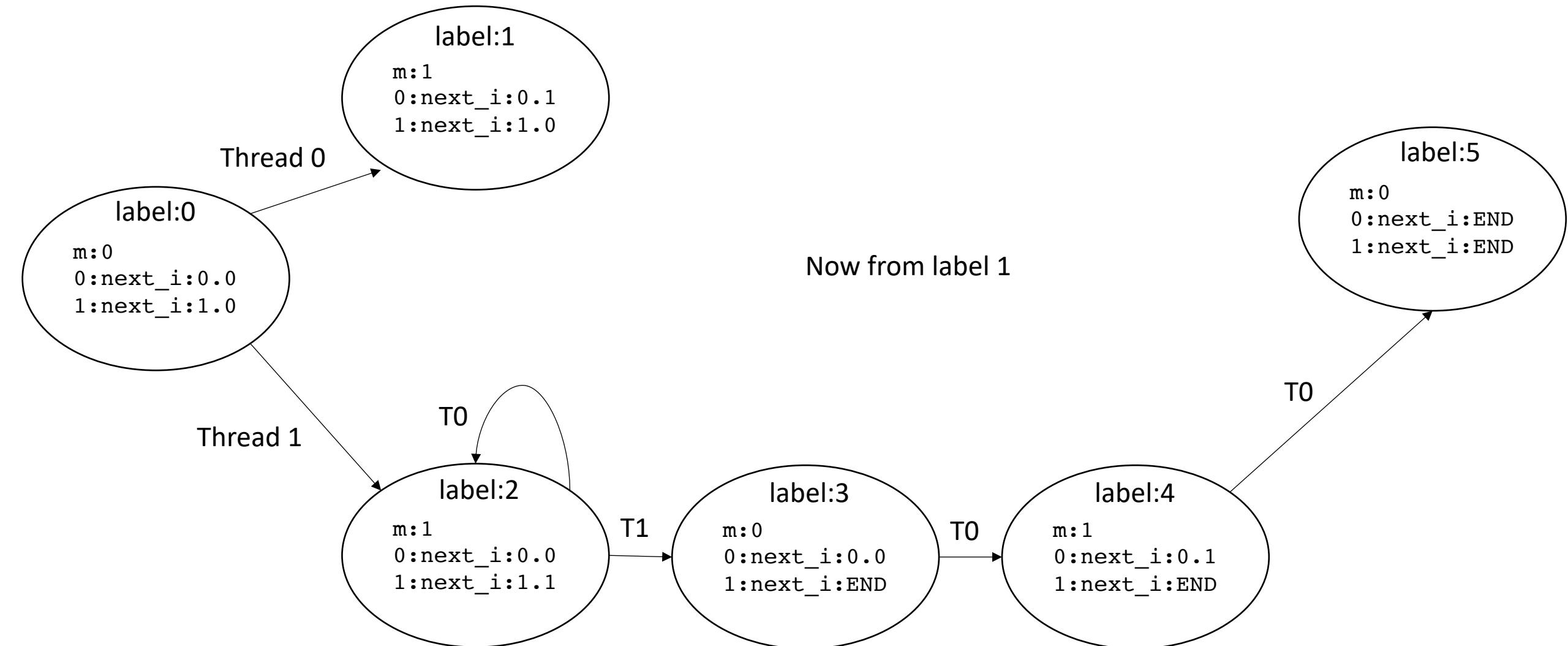


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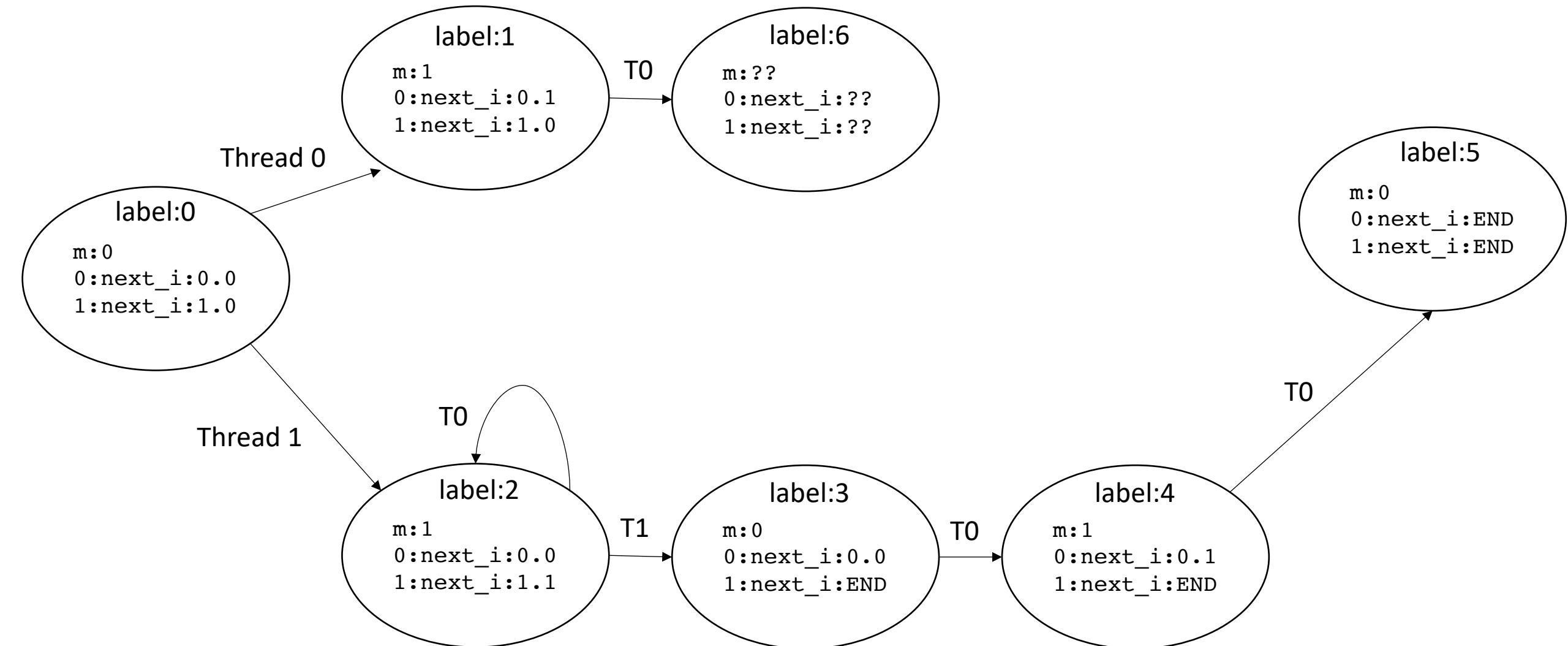


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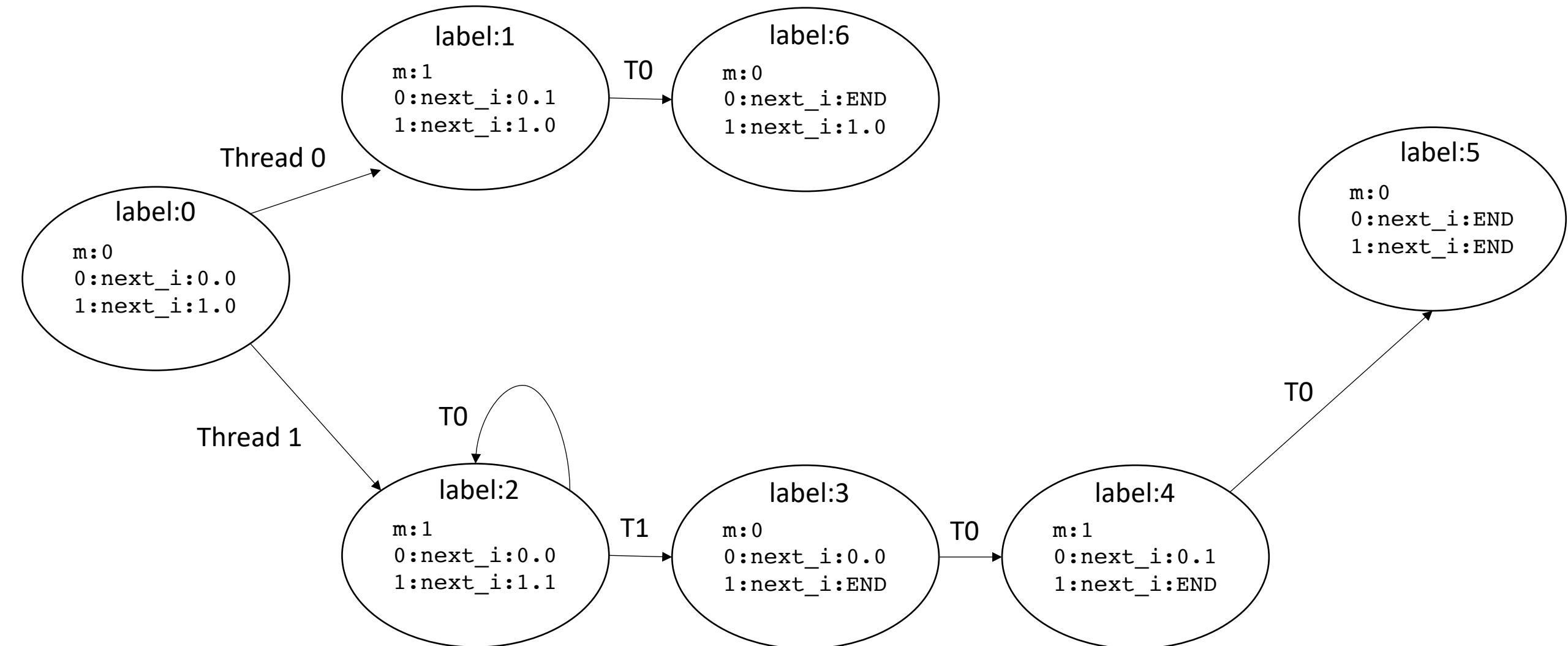


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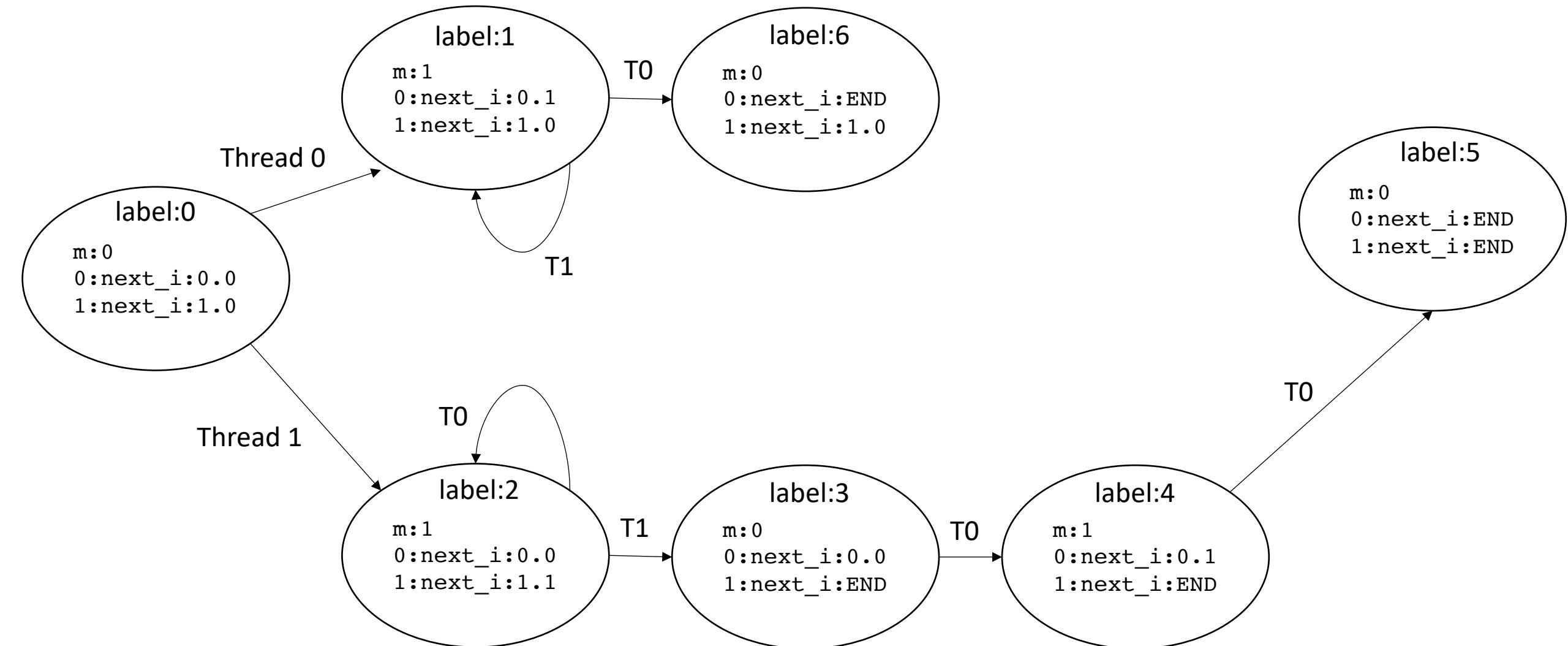


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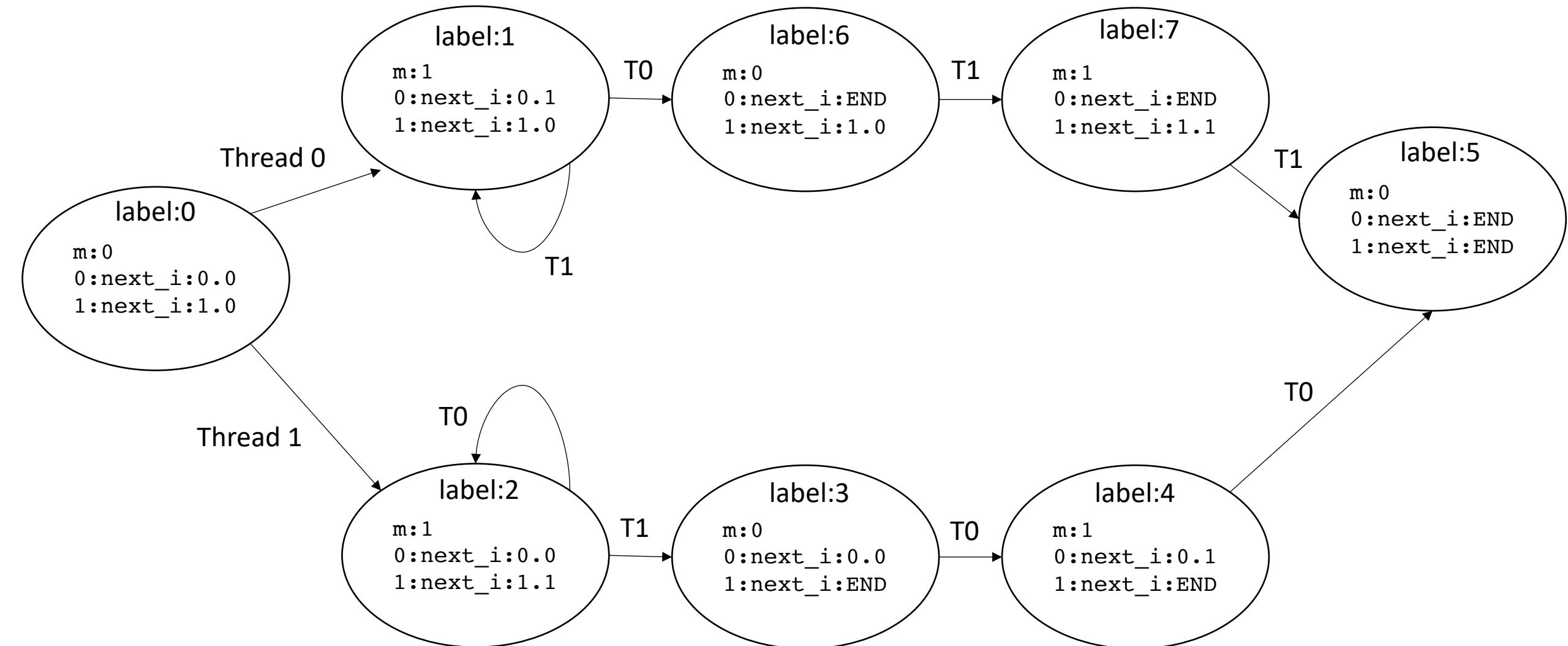


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# This is called an LTS

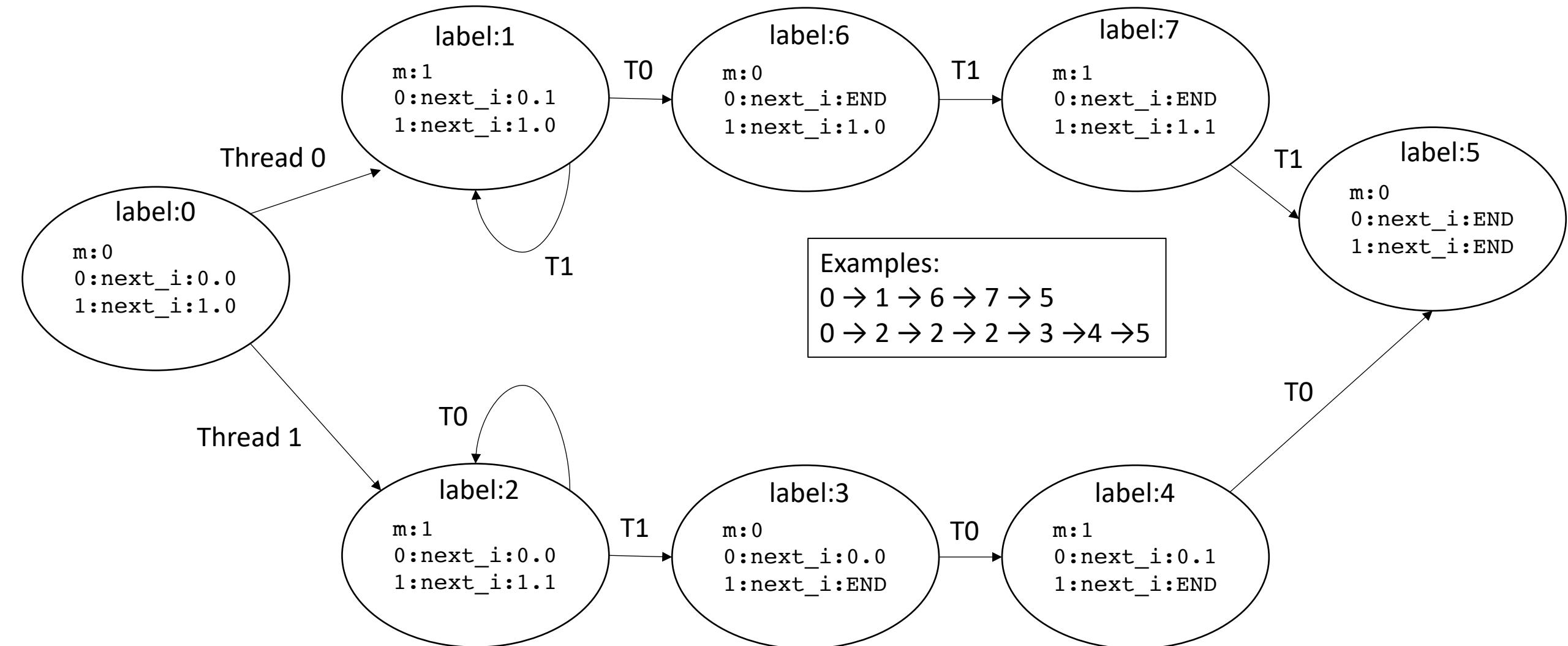
- A graph:
  - Each state encodes all variables/values and what the next instruction to execute is
  - Each edge out of a node is the different threads that can execute
  - A concurrent execution is any path through the LTS

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# What is this good for?

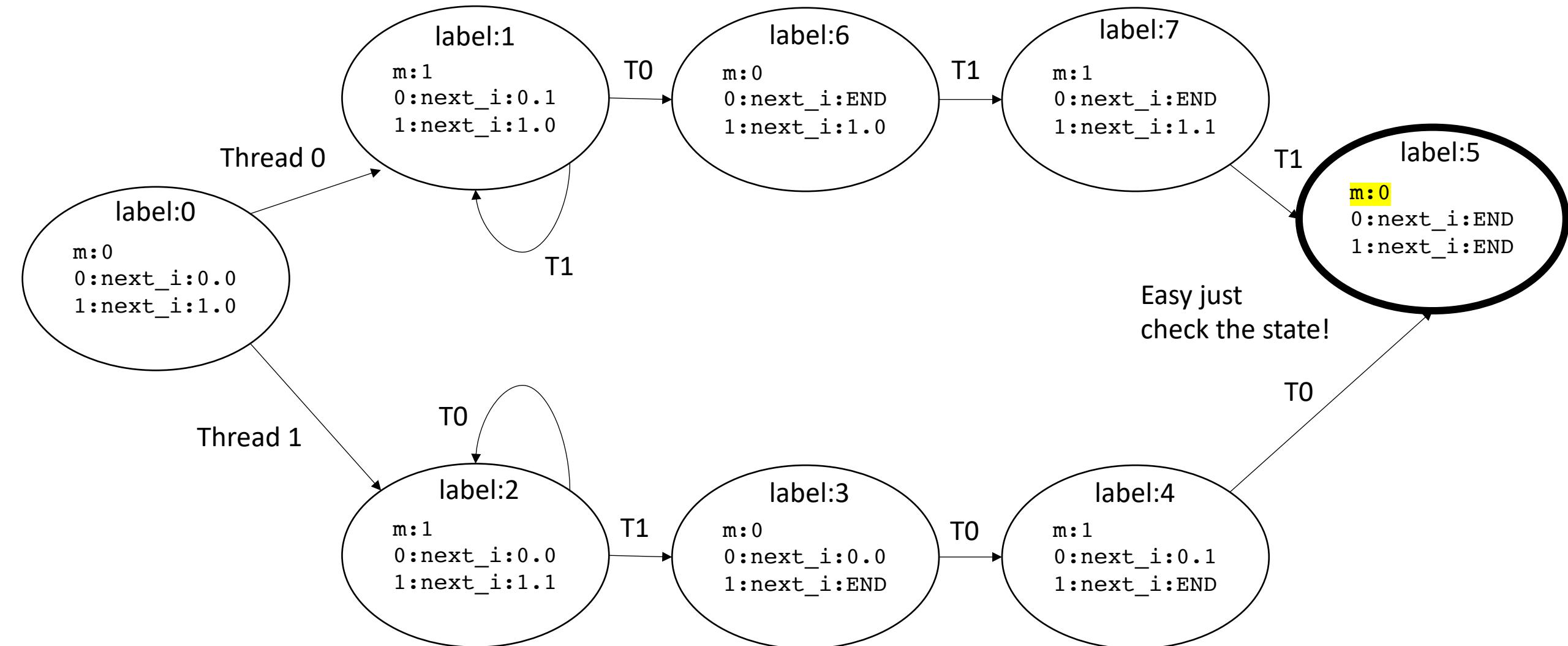
- Given this LTS, what kind of questions can we ask?
- Example:
  - At the end of the program, I want to prove that the mutex will not be taken

Thread 0:

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# Safety property

- ***Something bad will never happen***
  - i.e. the program will not exit with the mutex taken
  - can be specified with assert statements in the program
- Easy to check in a LTS: just search the states
  - You have all the values, easy to check if something is wrong!

# However...

- *Safety is only half of the picture*
- Self driving car example:
  - Design a car that never crashes (safety property)

# However...

- *Safety is only half of the picture*
- Self driving car example:
  - Design a car that never crashes (safety property)
  - **Easy!** Just design a car that can't move!
  - We need include something else in the specification:

# Liveness property

- Something good will eventually happen
- Examples:
  - The mutex program *will eventually terminate*
  - The self driving car *will eventually reach its destination*
- More difficult to reason about than safety properties

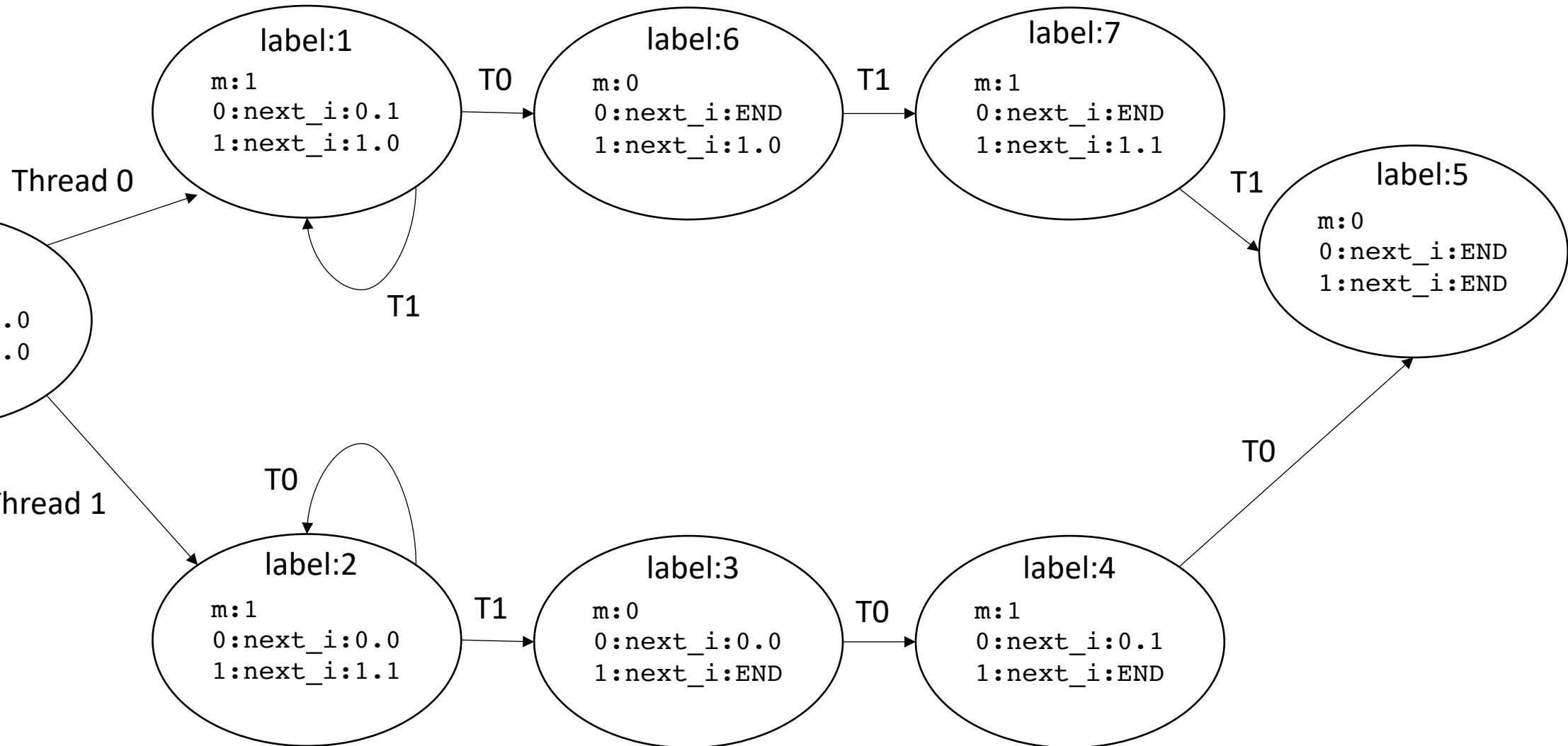
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*Is this program  
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What could go  
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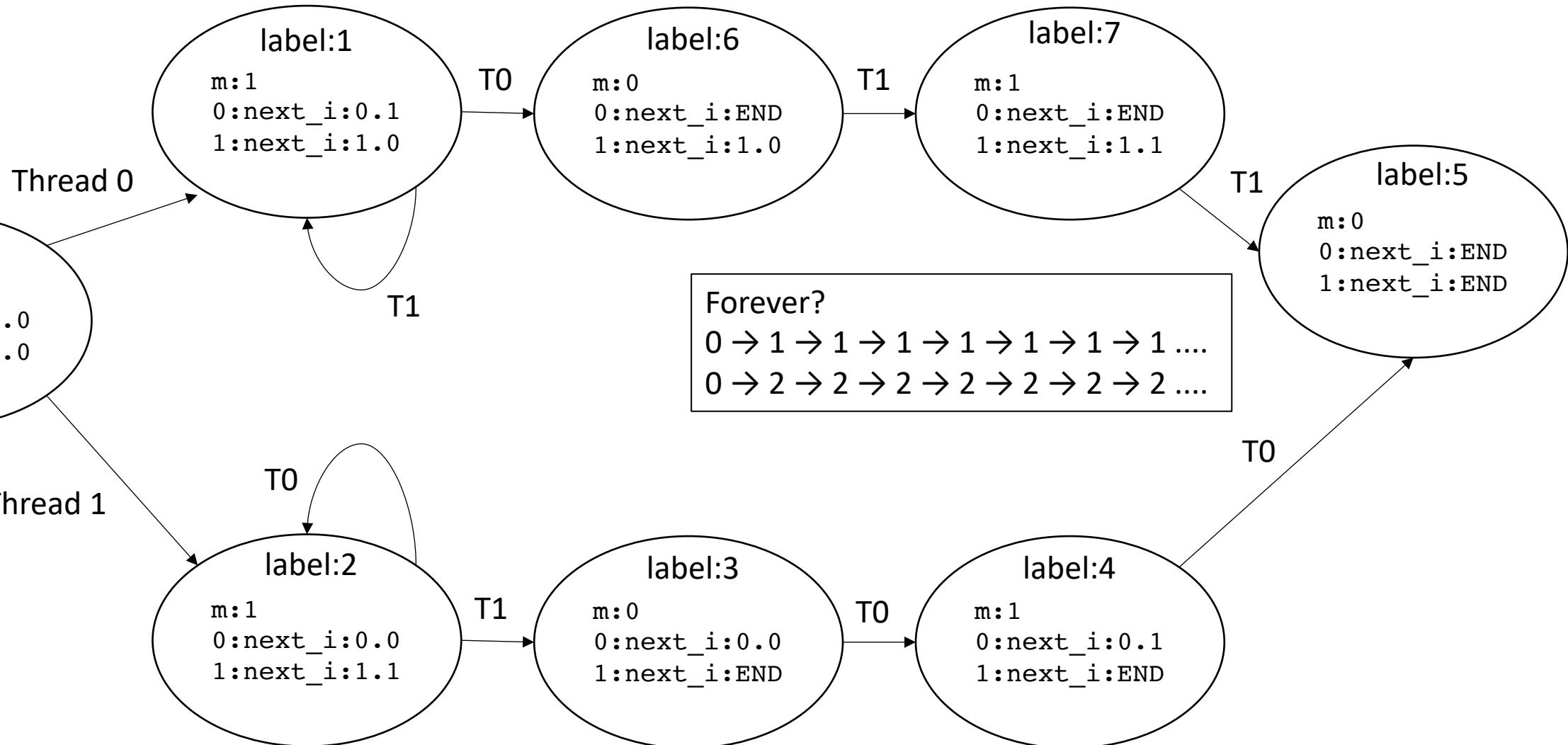
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# Liveness

- Starvation cycles
  - There exists a thread that can break the system out of a cycle, but that thread never executes (i.e. it is starved).
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# Liveness

- Starvation cycles
  - There exists a thread that can break the system out of a cycle, but that thread never executes (i.e. it is starved).
- Can starvation cycles happen?
  - Depends on your scheduler!
  - With no scheduler guarantees, they cannot be ruled out!
- Note that we are talking about scheduler *specifications*, actual implementations are very complicated (take an OS class to learn more)

# Schedule

- Labeled Transition Systems
- **Scheduler specifications**

*5 minute break*

# The fair scheduler

- every thread that has not terminated will “eventually” get a chance to execute.
  - “concurrent forward progress”: defined by C++ not guaranteed, but encouraged (and likely what you will observe)
  - “weakly fair scheduler”: defined by classic concurrency textbooks
- The fair scheduler disallows starvation cycles
  - waiting will always be finite (but no bounds on time)

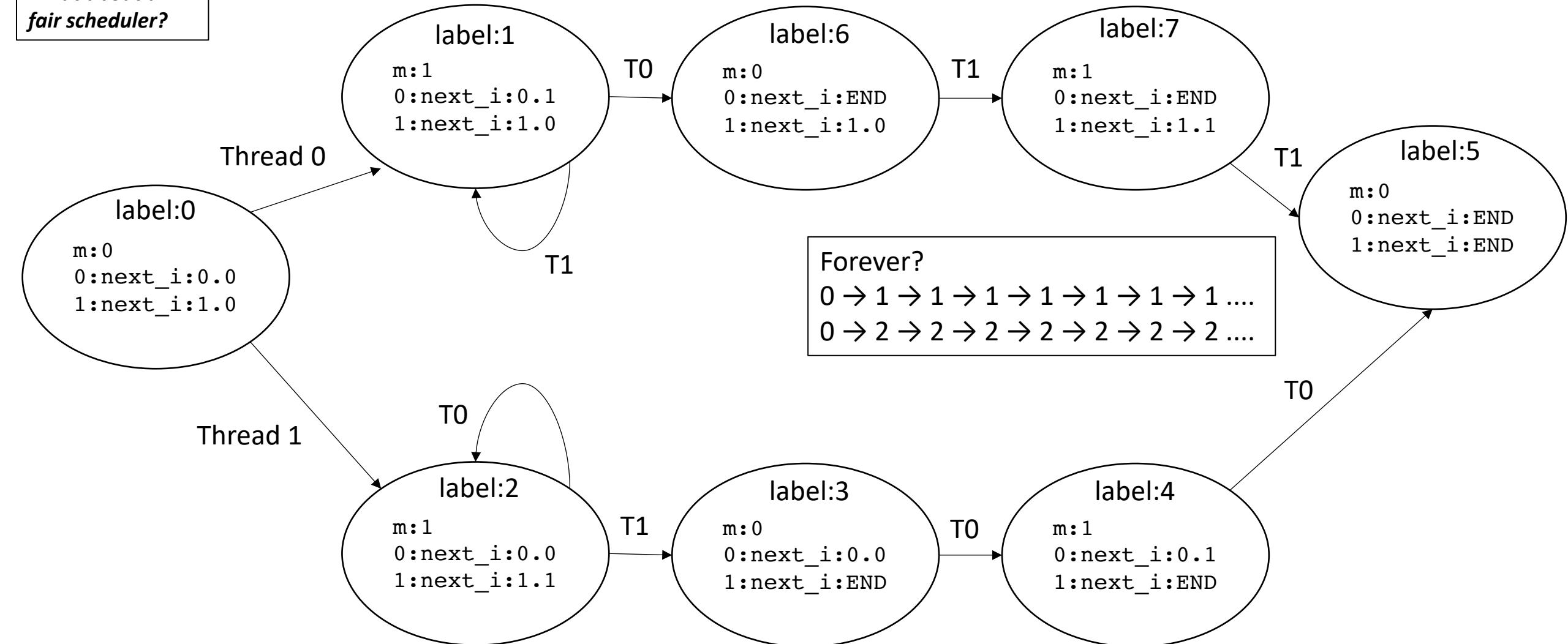
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What about a  
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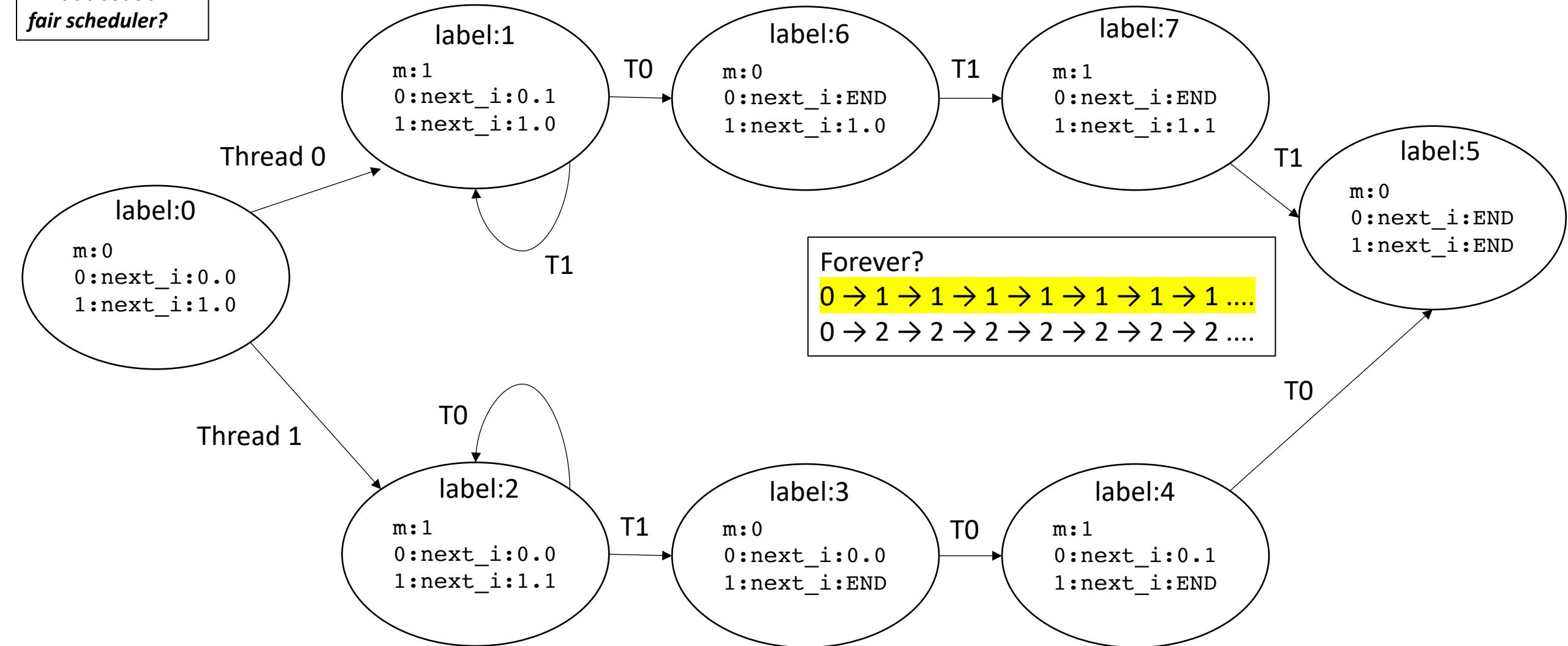
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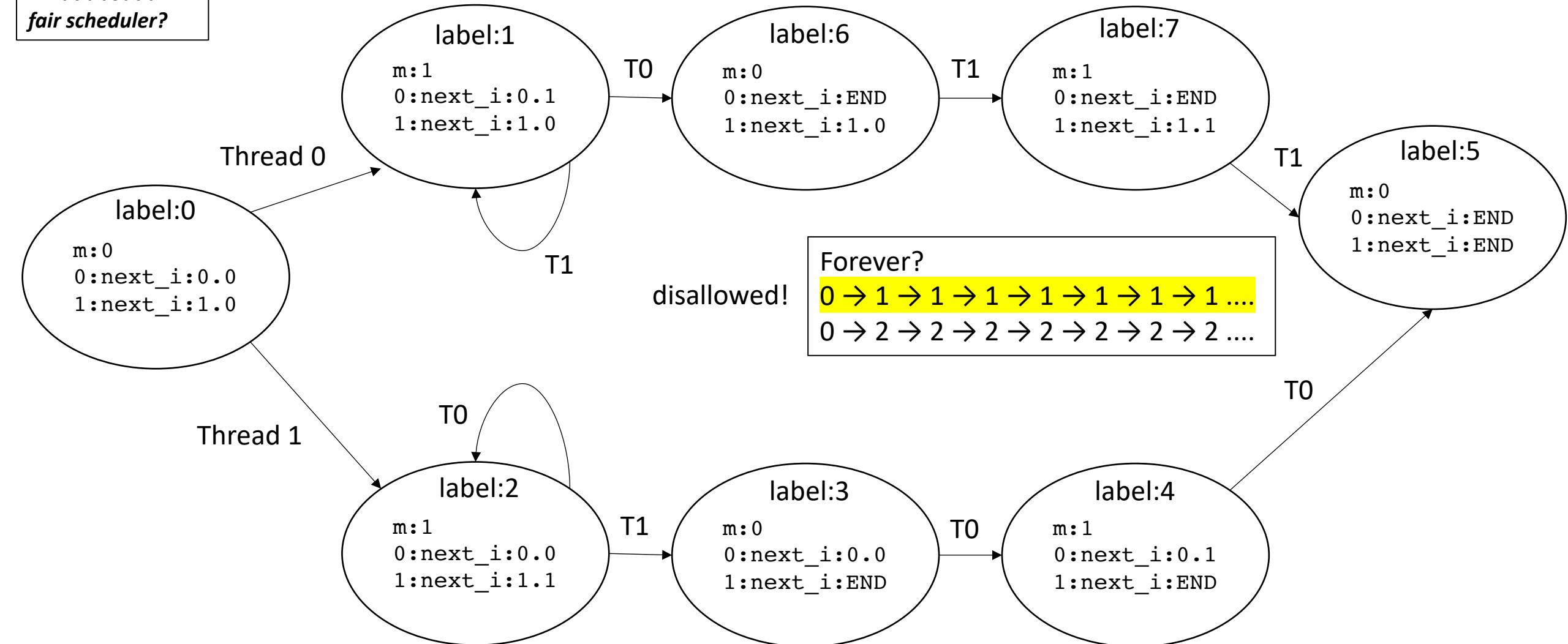
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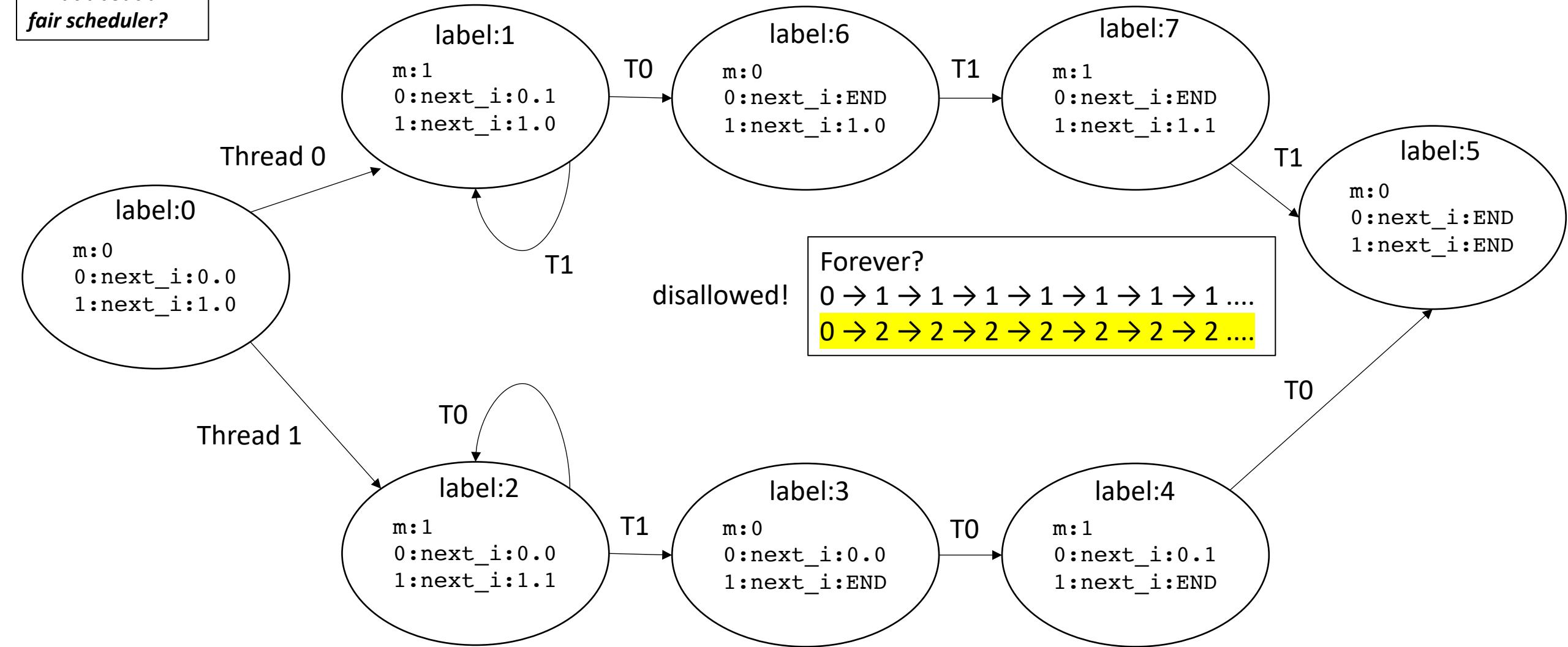
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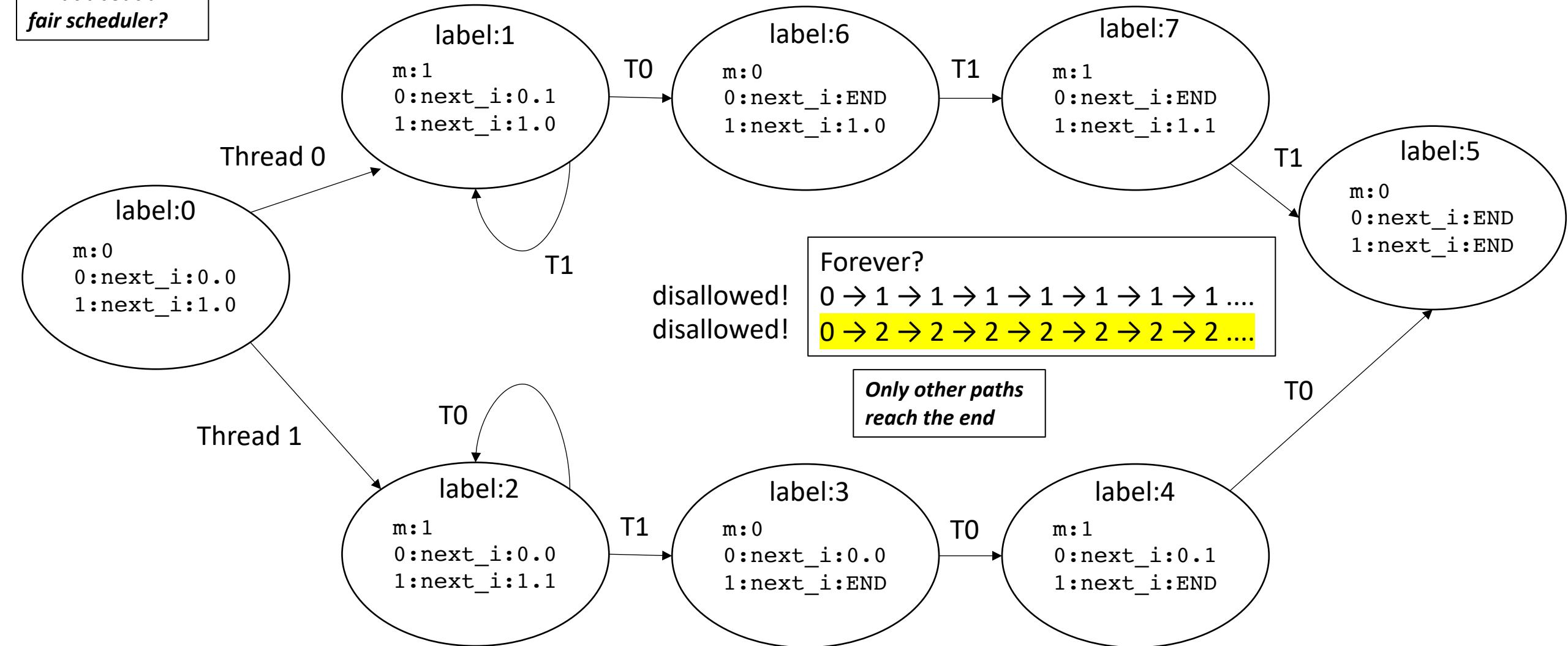
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# Schedulers

- A fair scheduler typically requires preemption



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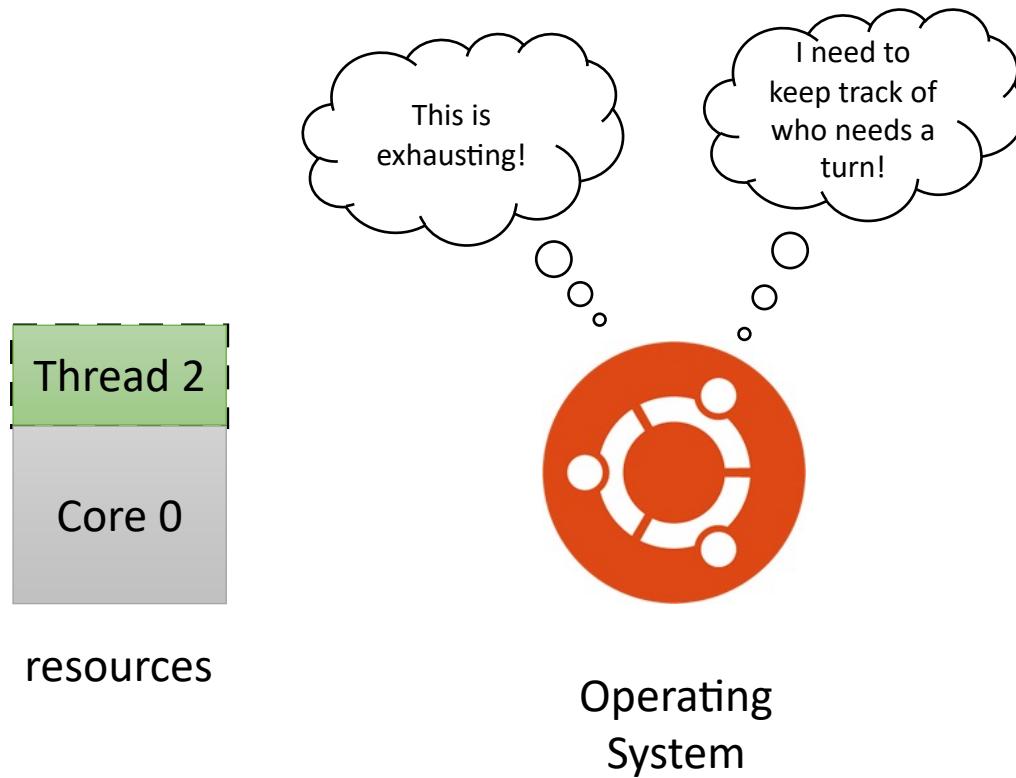
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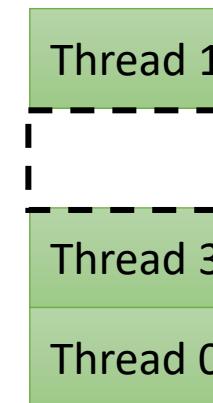


# Schedulers

- A fair scheduler typically requires preemption



Thread list



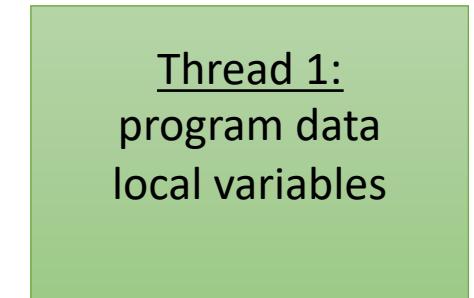
peak into a thread object:

# Schedulers

- A fair scheduler typically requires preemption



peak into a thread object:



Estimated to be ~30K cycles  
to context switch between  
threads

# Schedulers

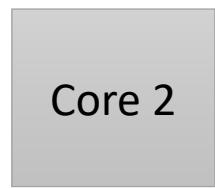
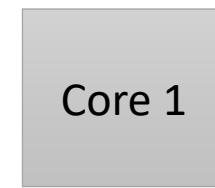
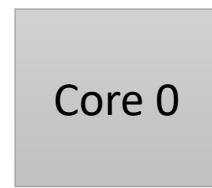
- Systems might not support preemption: e.g. GPUs

# simplified execution model

Program with 5  
threads



*thread pool*



Device with 3 Cores

finished threads

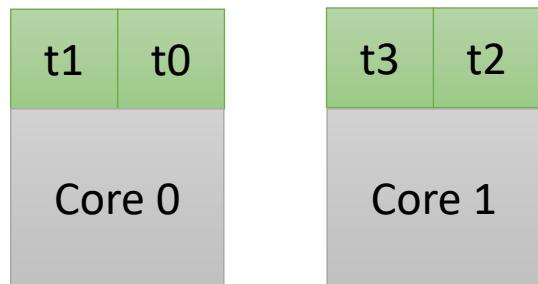
# Solutions?

- I have N cores, only run N threads?

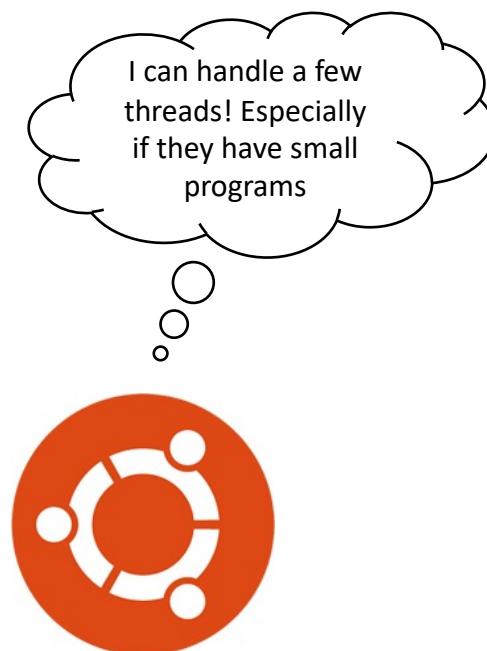
# Solutions?

- I have N cores, only run N threads?

sometimes concurrency can help hide latency! Don't want to completely disallow it!



Device with 2 cores



# Solutions?

- I have N cores, only run N threads?
- GPU examples:
  - Depending on program size Nvidia GPUs support
    - 32 threads per core for small programs
    - 2 threads per core for big programs
- We need a better specification

# Parallel Forward Progress

- “Any thread that has executed at least 1 instruction, is guaranteed to continue to be fairly executed”
- Also called:
  - “Parallel Forward Progress”: by C++
  - “Persistent Thread Model”: by GPU programmers
  - “Occupancy Bound Execution Model”: in some of my papers

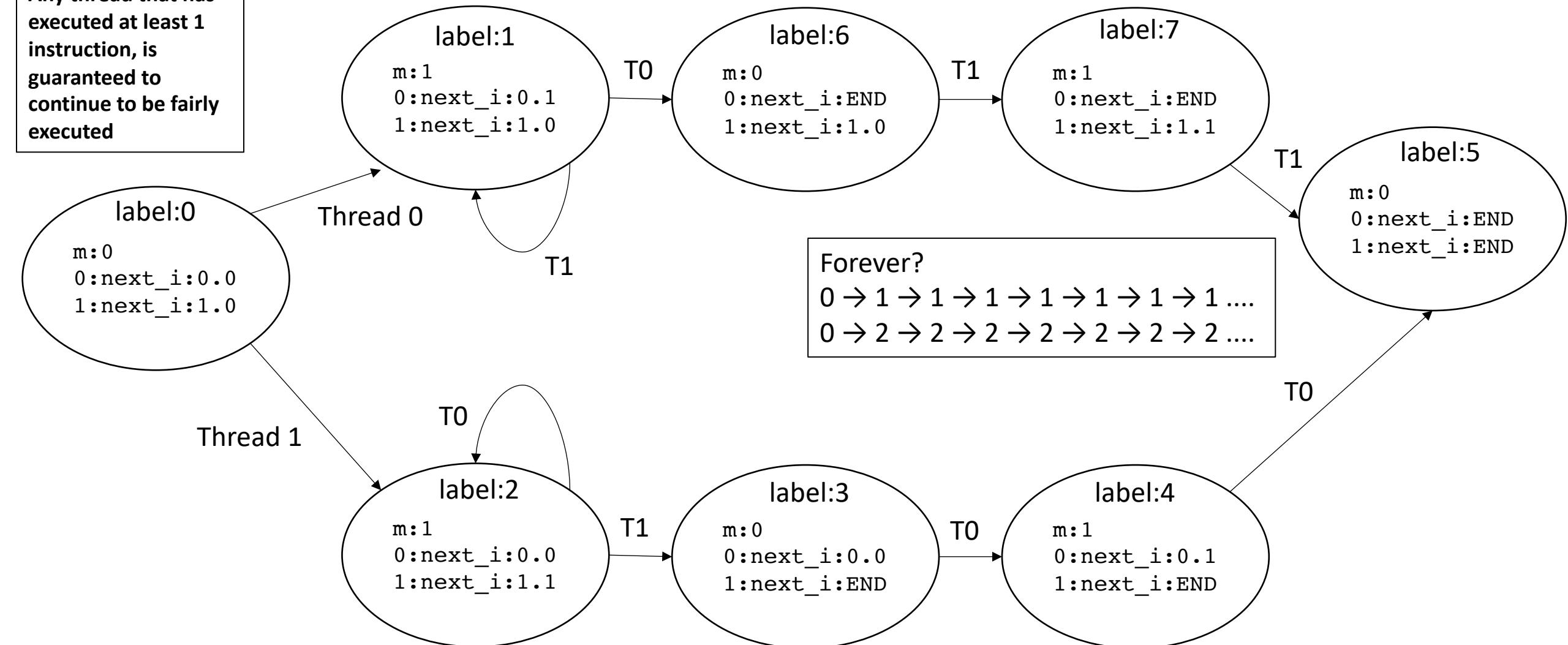
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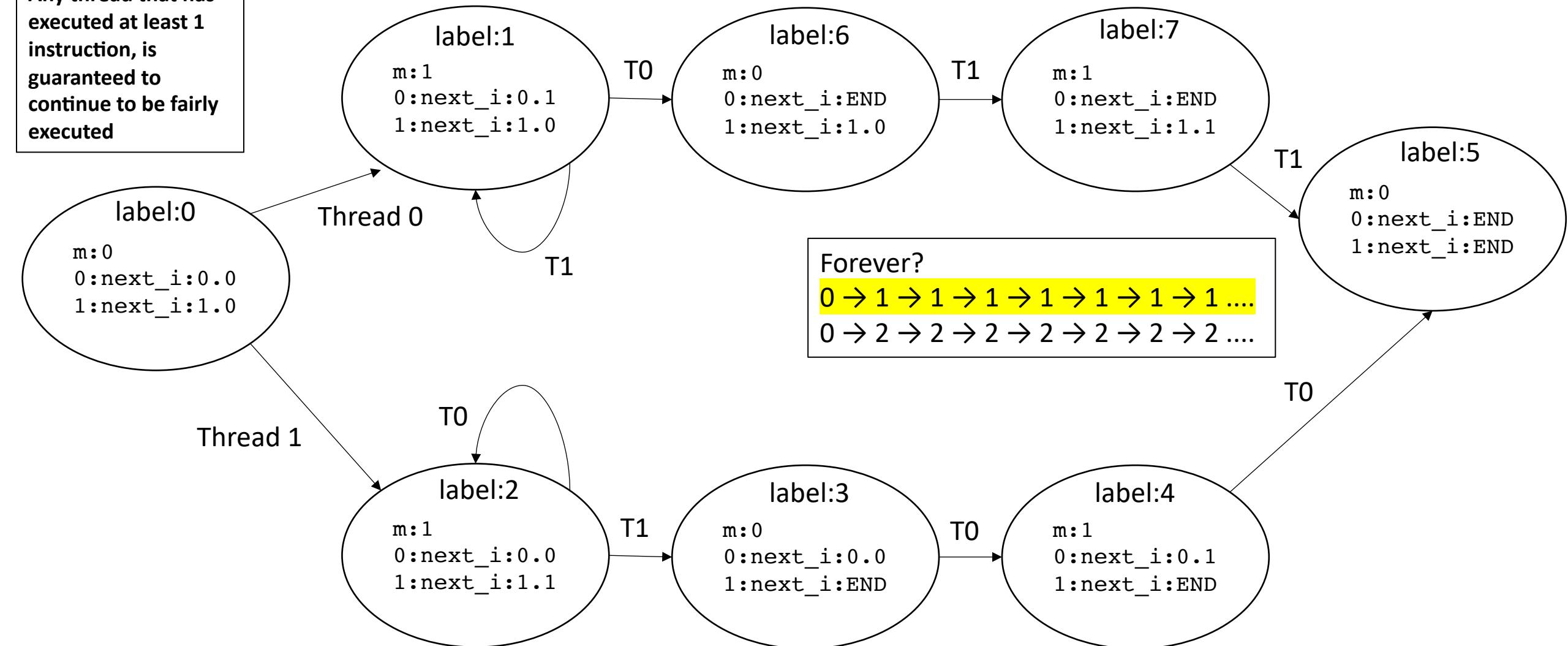
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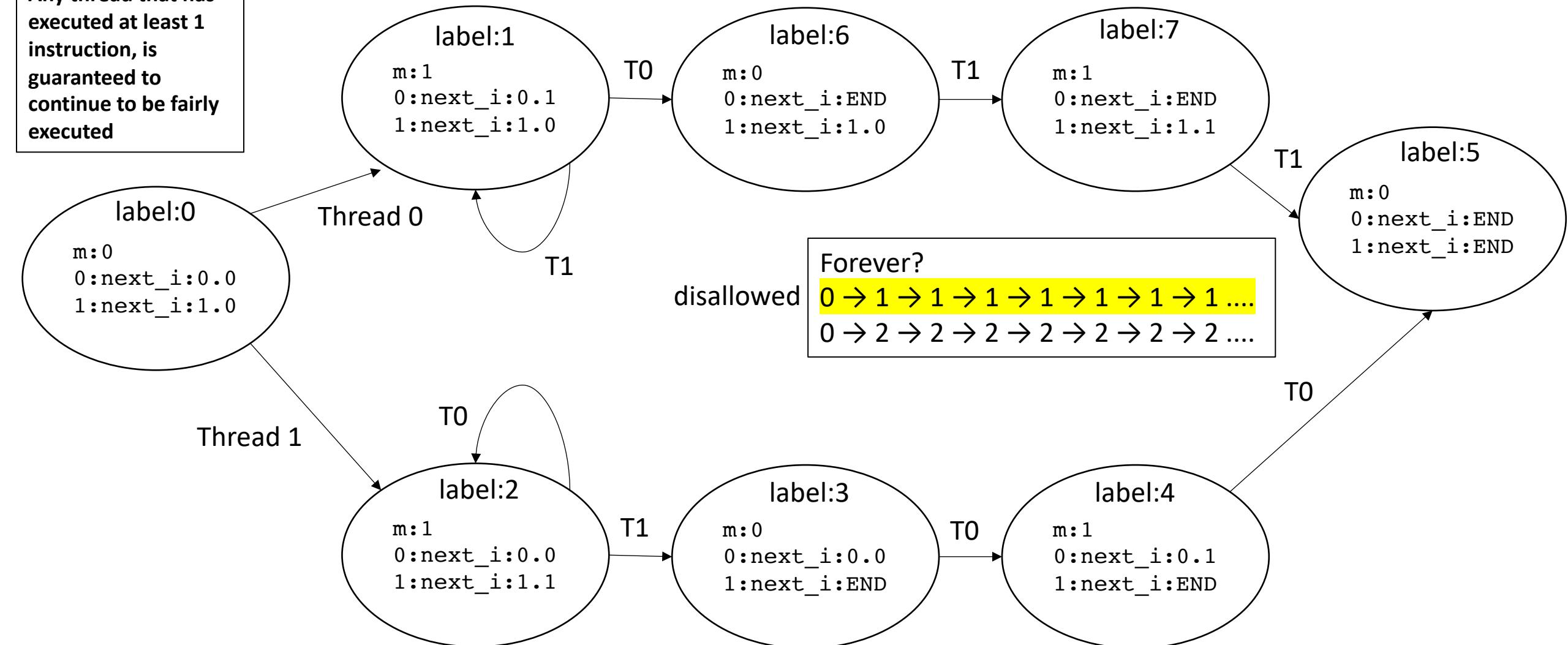
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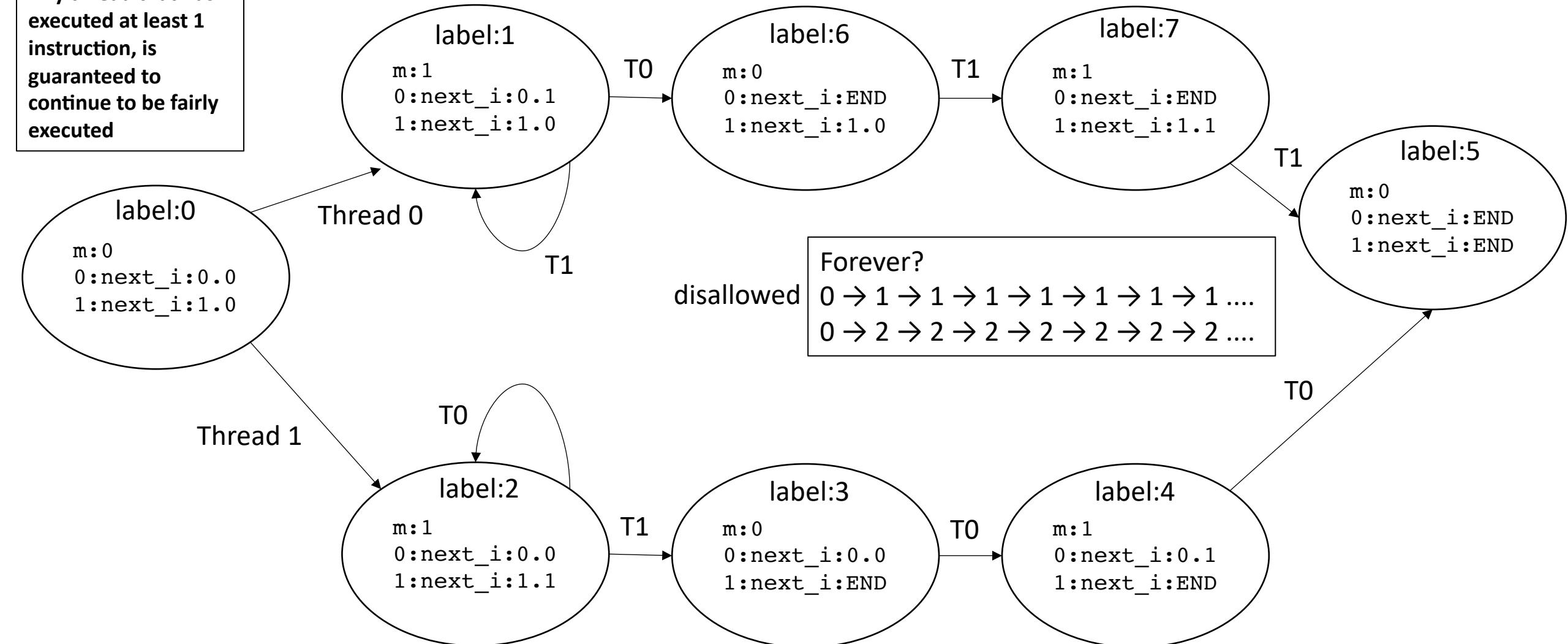
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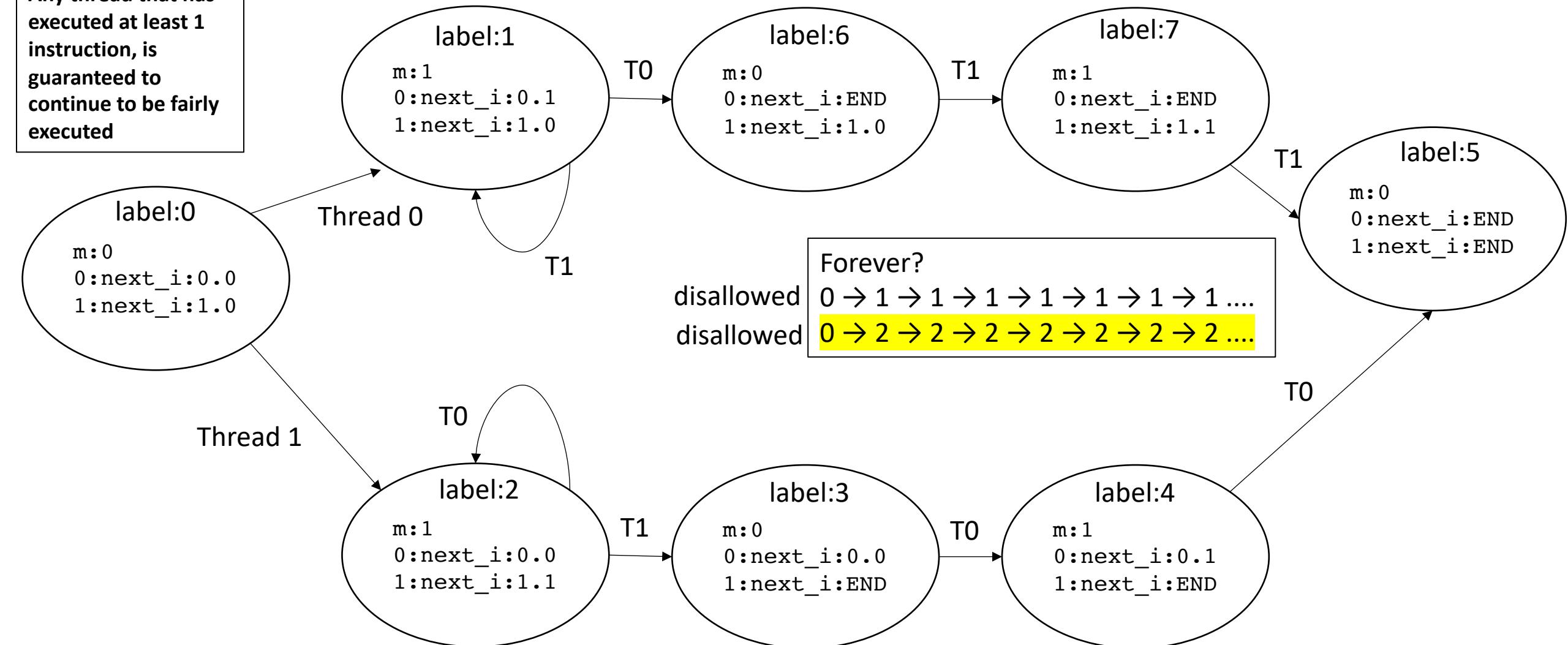
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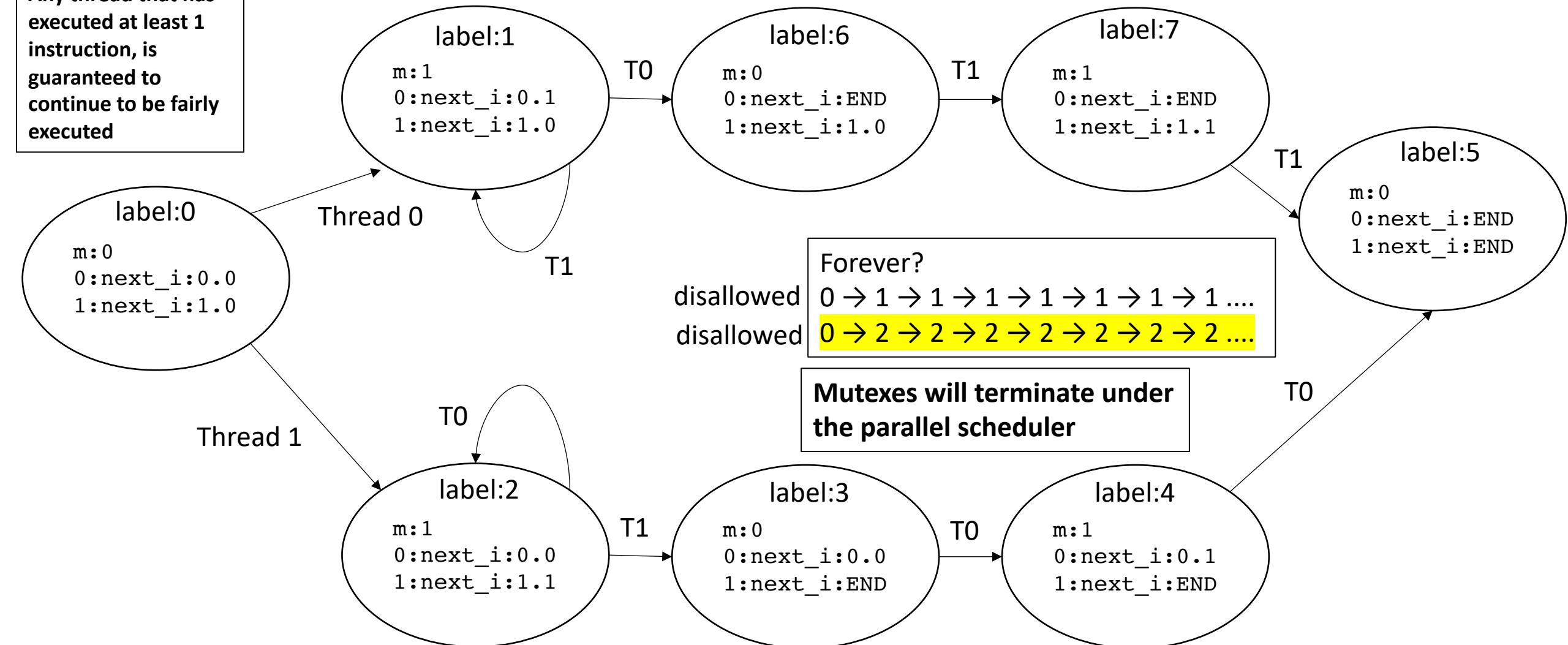
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# Another example

- Producer - consumer
  - Thread 0 waits for Thread 1 to write a flag

Thread 0:

```
0.0: while(flag.load() == 0);
```

Thread 1:

```
1.0: flag.store(1);
```

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start with initial node

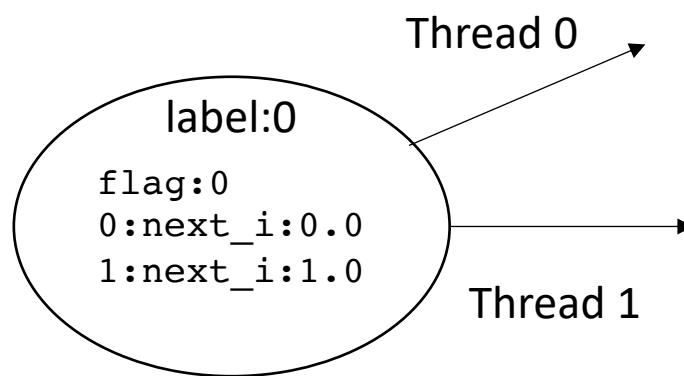


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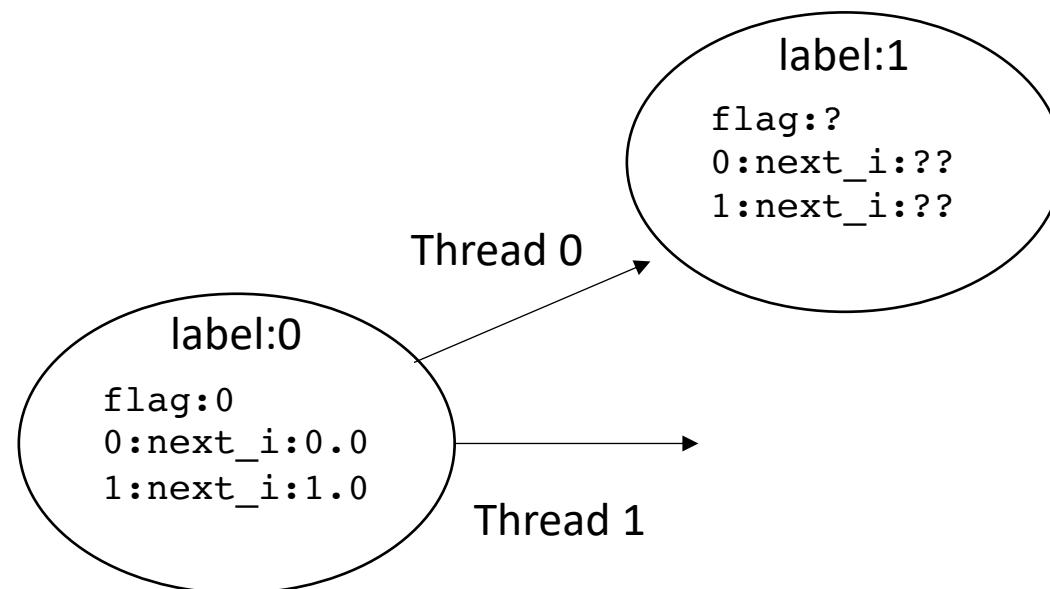


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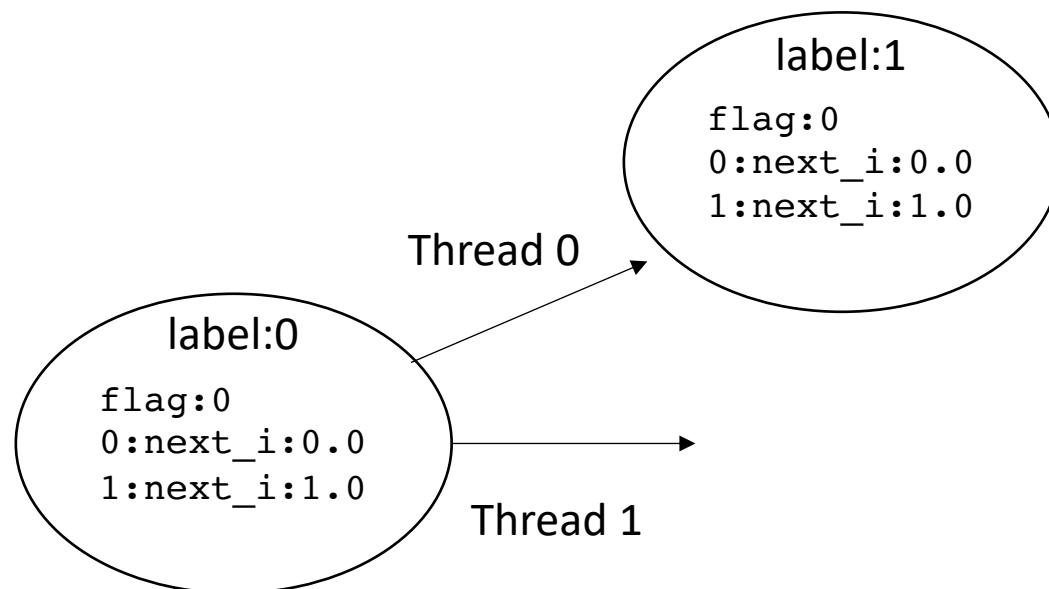


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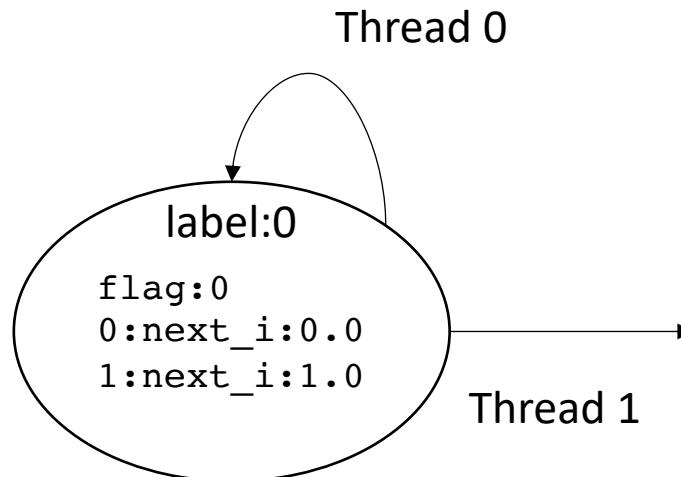


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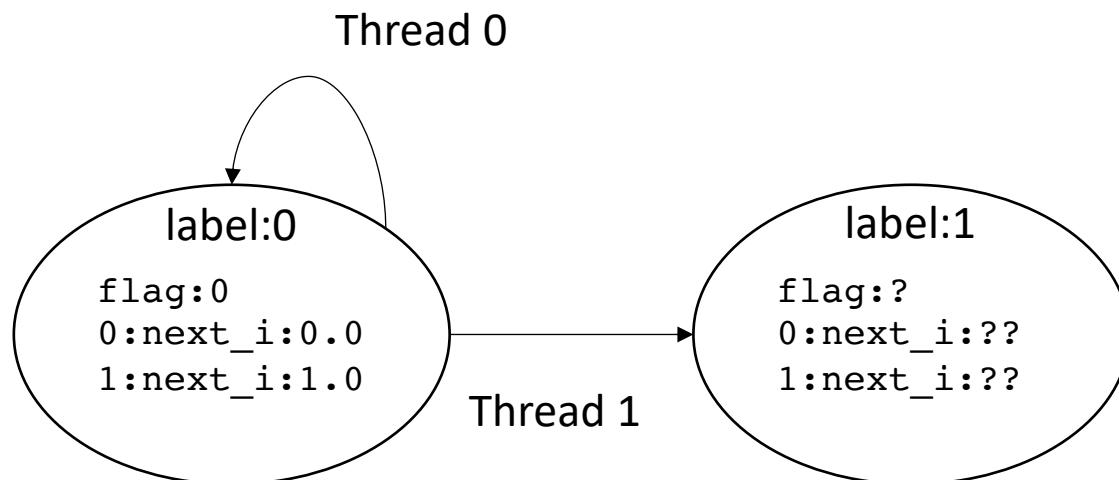


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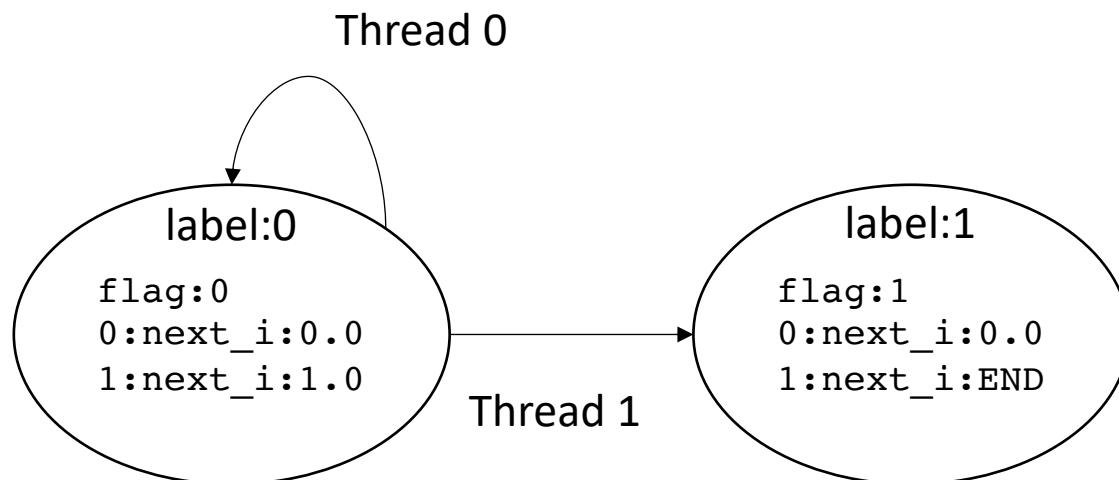


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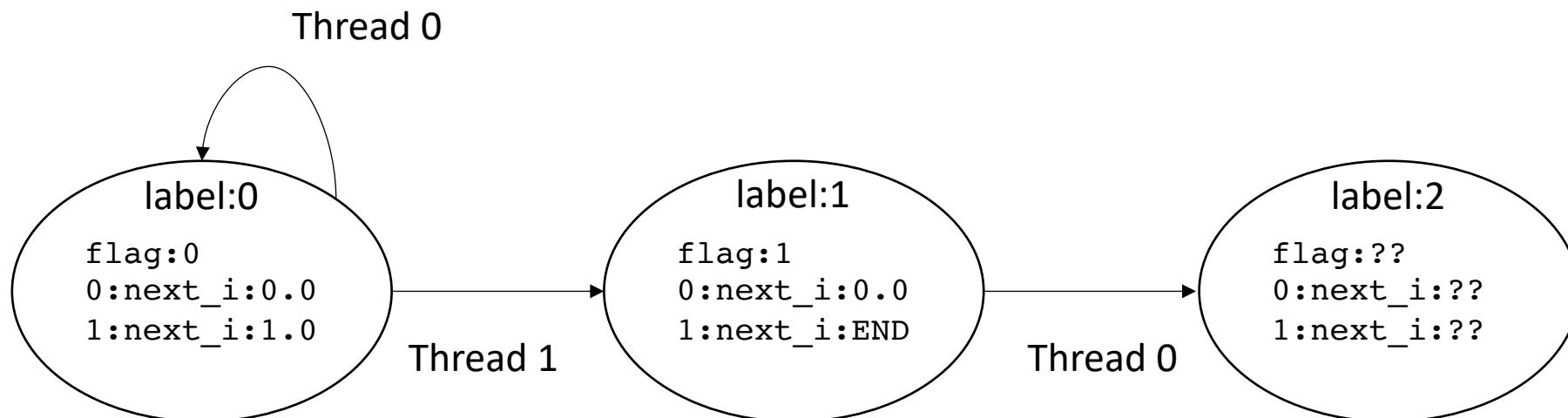


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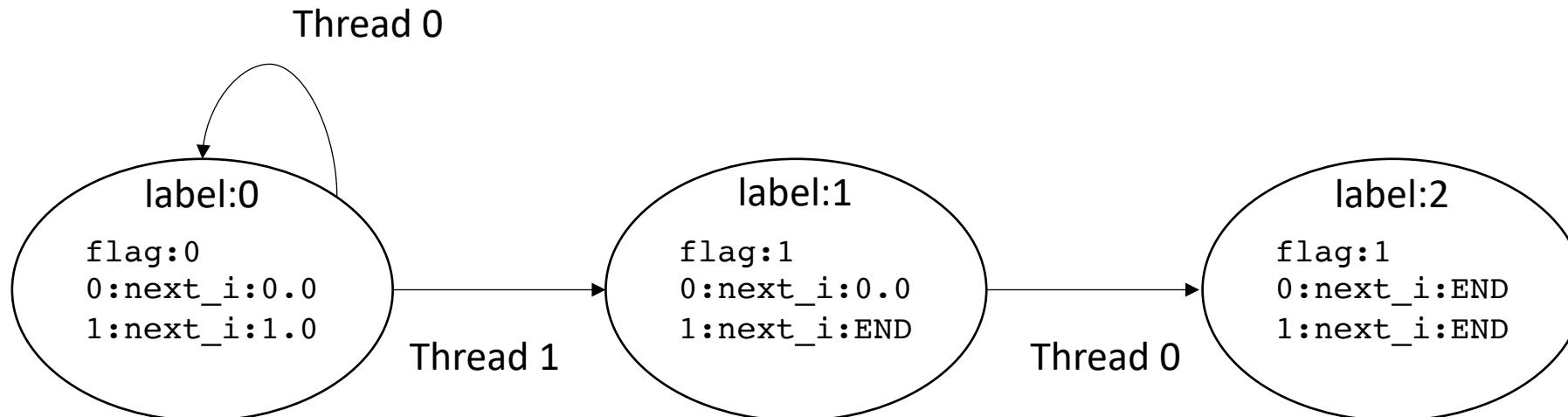


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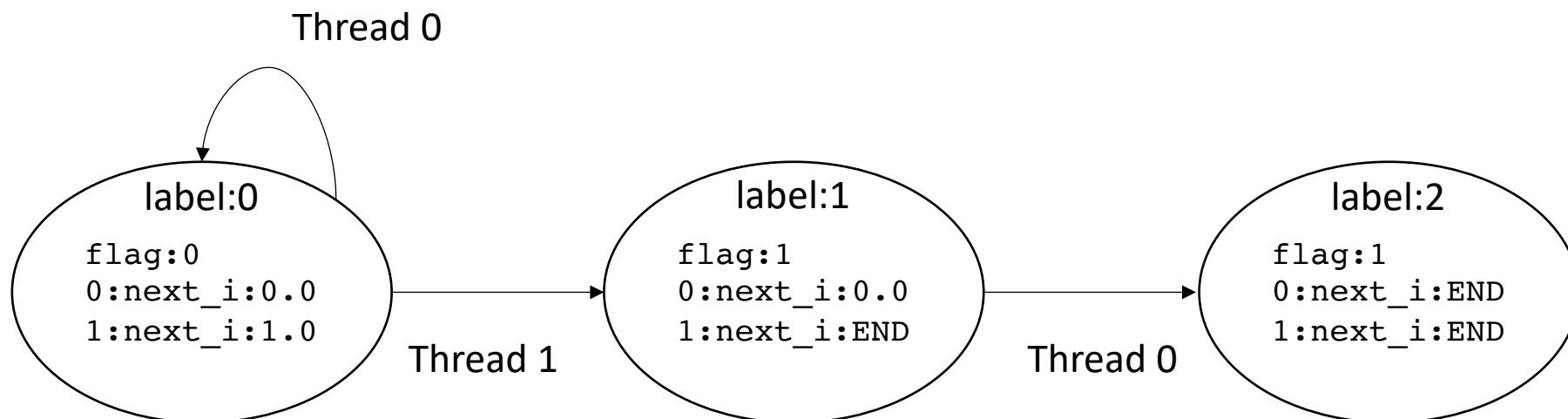
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*Is this program guaranteed to terminate under the fair scheduler?*



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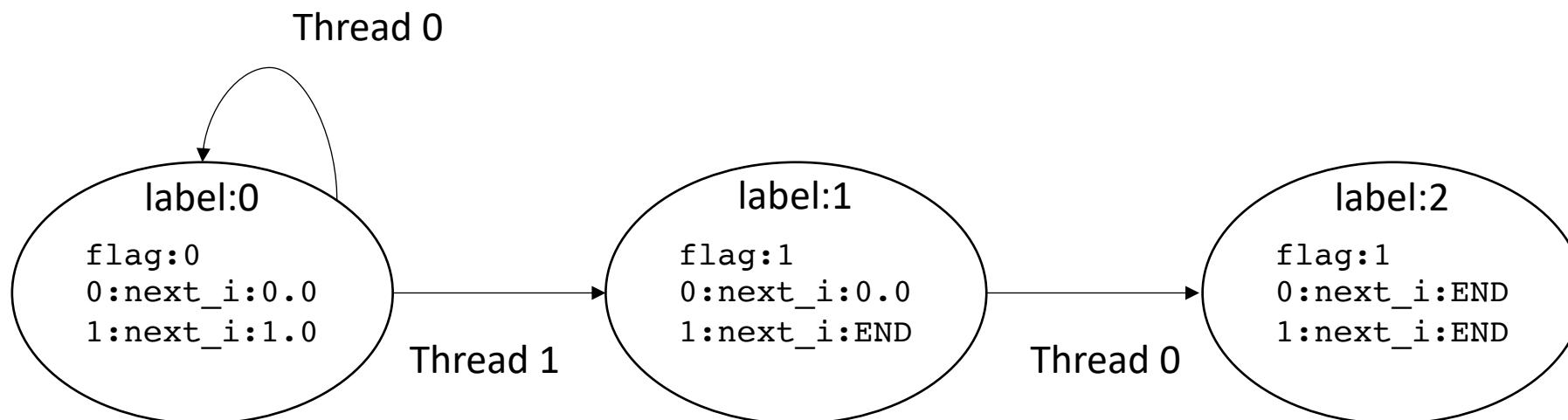
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*Is this program guaranteed to terminate under the fair scheduler?*

*Is this program guaranteed to terminate under the parallel scheduler?*



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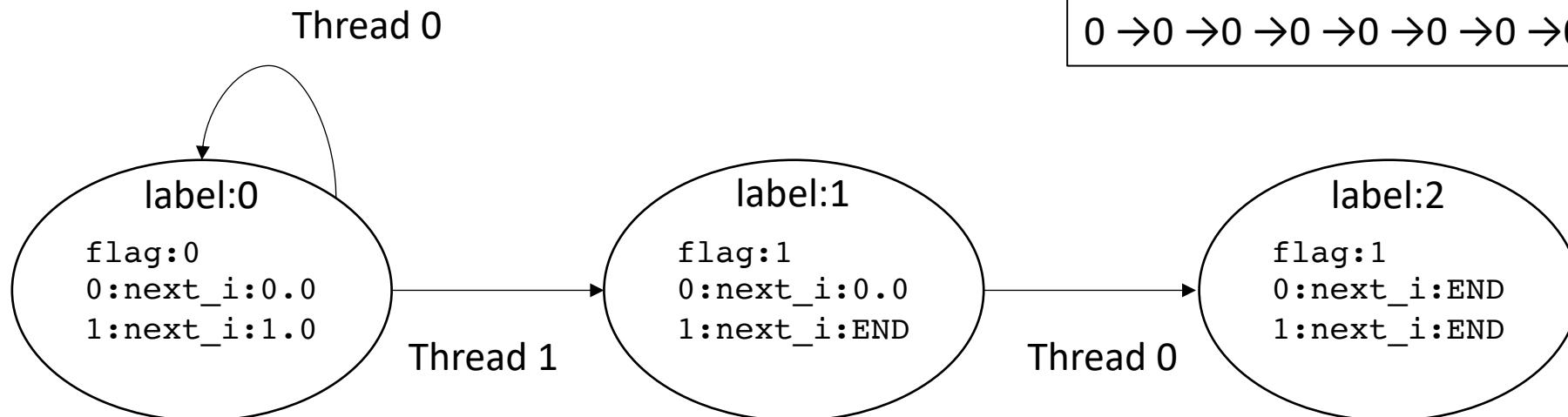
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Any thread that has executed at least 1 instruction, is guaranteed to continue to be fairly executed



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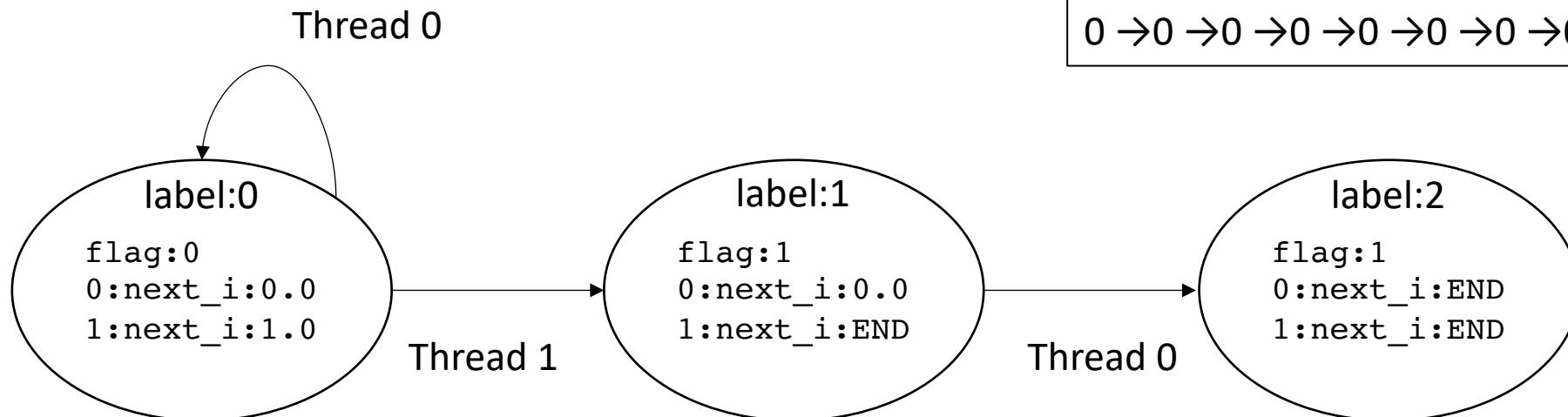
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Any thread that has executed at least 1 instruction, is guaranteed to continue to be fairly executed



*allowed to spin forever in the parallel scheduler!*

*Thread 0 could be scheduled on the only core while thread 1 spins*

# Schedulers

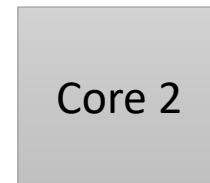
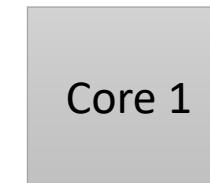
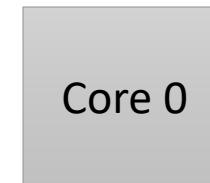
- In some cases the Parallel scheduler might be too strong
- For example dynamic power management on mobile devices

# A power-saving scheduler

Program with 5  
threads



*thread pool*



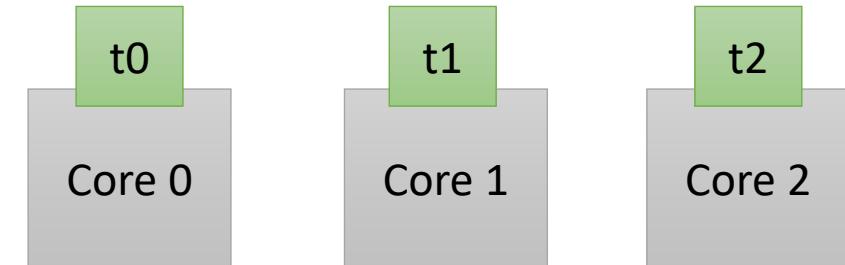
Device with 3 Cores  
finished threads

# A power-saving scheduler

Program with 5  
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*thread pool*



finished threads

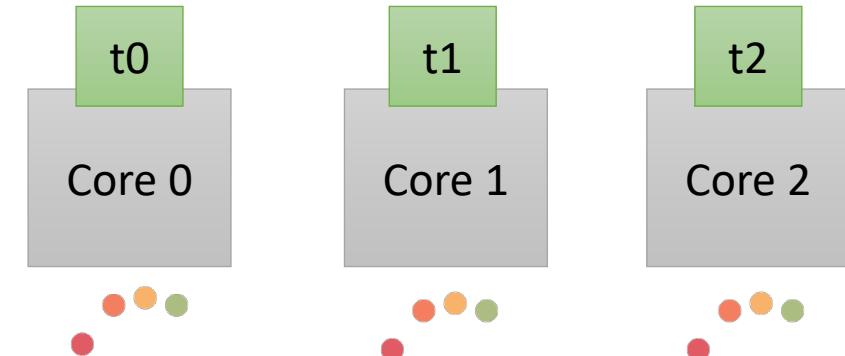
Device with 3 Cores

# A power-saving scheduler

Program with 5  
threads



*thread pool*

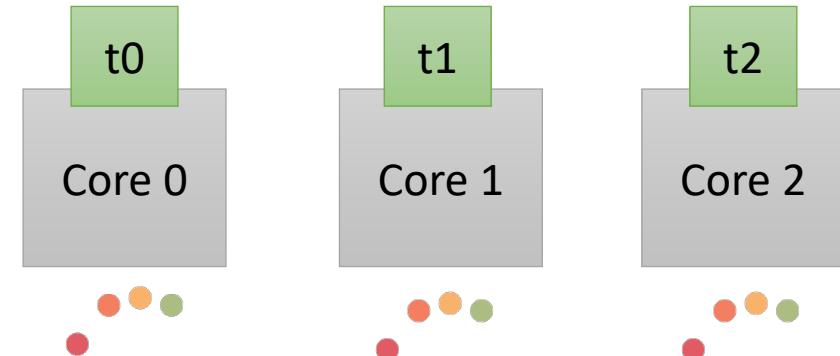


Device with 3 Cores

finished threads

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finished threads

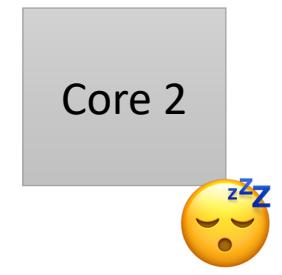
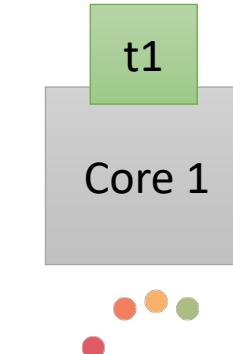
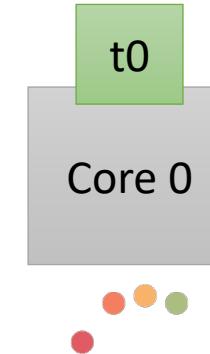
Device with 3 Cores

# A power-saving scheduler

Program with 5 threads



preempted



finished threads

Device with 3 Cores

# A power-saving scheduler

Program with 5 threads

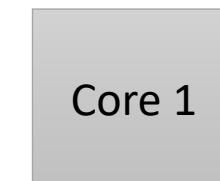
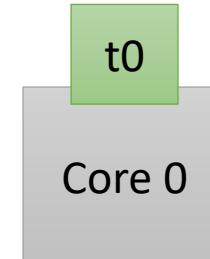


finished threads



t2

preempted



Device with 3 Cores

# A power-saving scheduler

Program with 5 threads



t1

finished threads

t0  
Core 0

t2  
Core 1

Core 2



Device with 3 Cores

# Schedulers

- This power-saving optimization messes up the Parallel Scheduler guarantees
- Can we do anything interesting with a scheduler like this?

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# Schedulers

- This power-saving optimization messes up the Parallel Scheduler guarantees
- Can we do anything interesting with a scheduler like this?
- The OS can give guarantees about the threads that it preempts for energy savings.
- The OS could target threads with higher ids and give priority with threads with the lower id.

# The HSA scheduler

- The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.
- Called:
  - “HSA” - Heterogeneous System Architecture, programming language proposed by AMD for new systems.
  - The HSA language appears to be defunct now, but the scheduler is a good fit for mobile devices (esp. mobile GPUs).

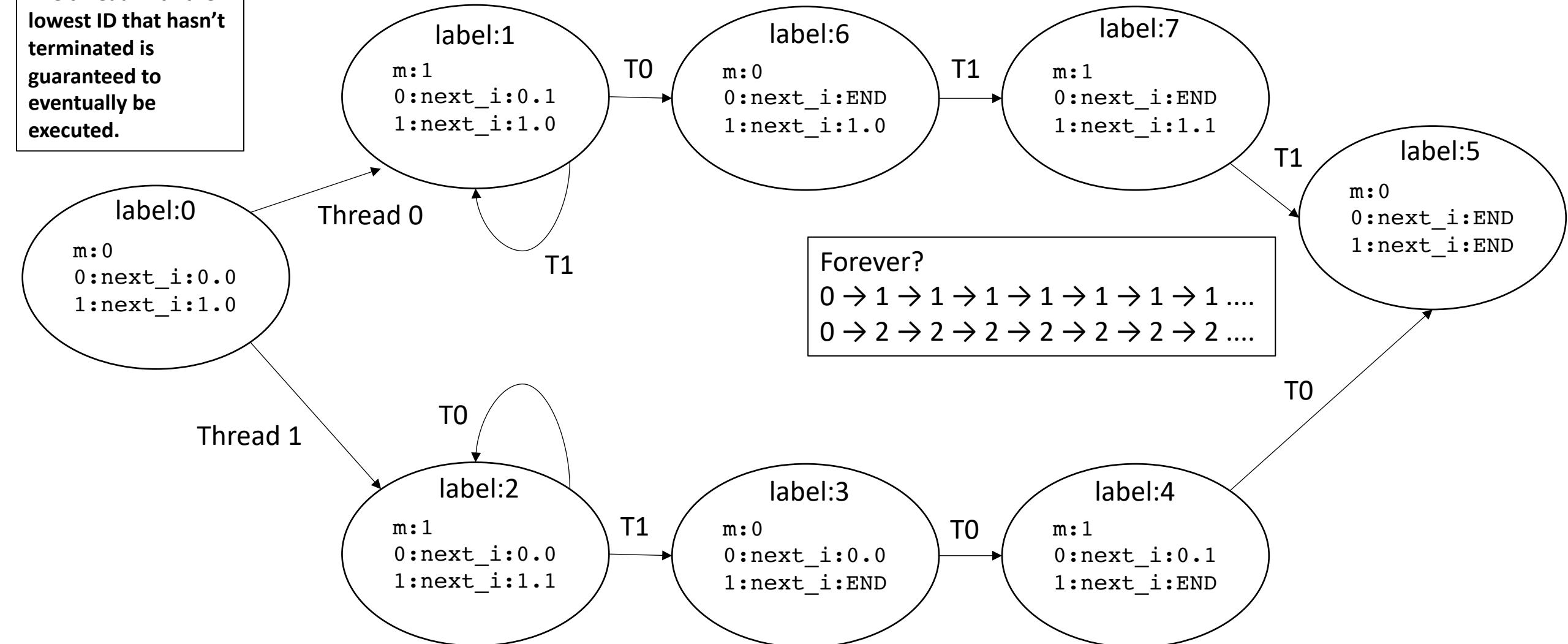
Thread 0:

```
0.0: while(CAS(&m,0,1) == false); //lock  
      // critical section  
0.1: m.store(0); //unlock
```

Thread 1:

```
1.0: while(CAS(&m,0,1) == false); //lock  
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The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.



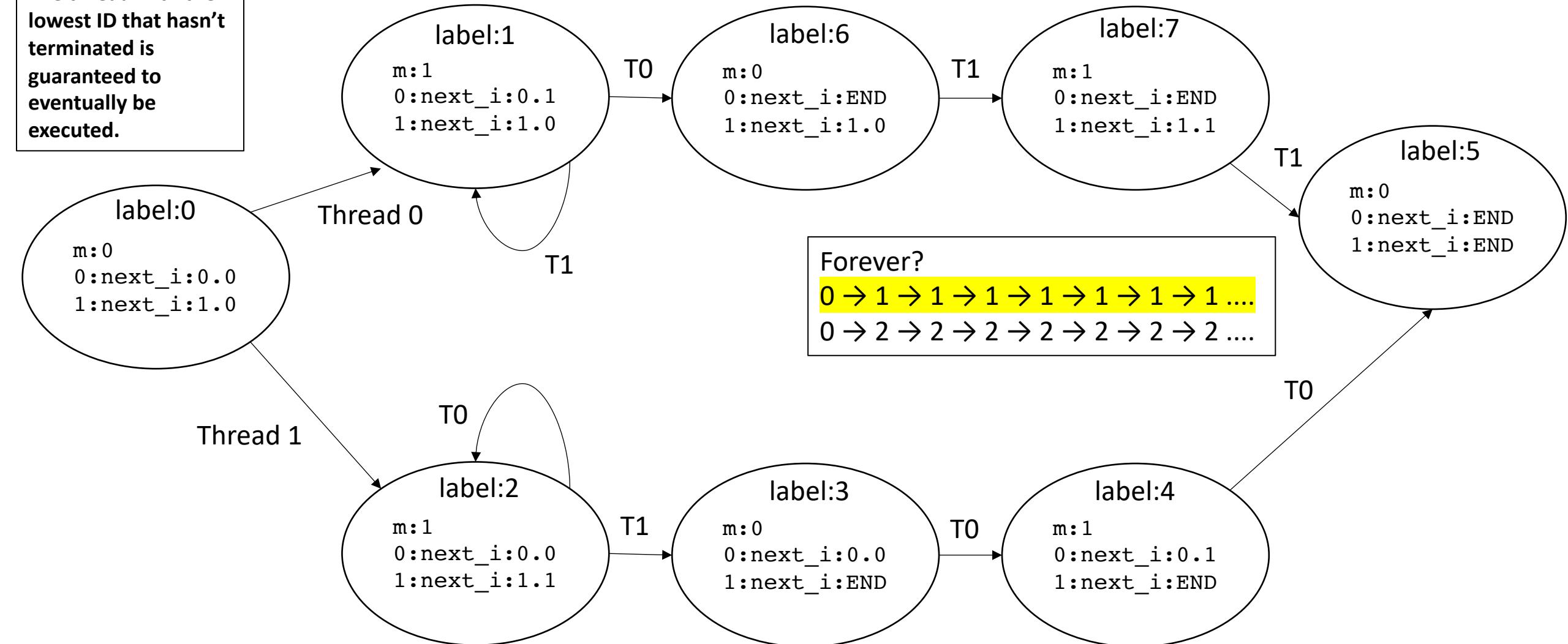
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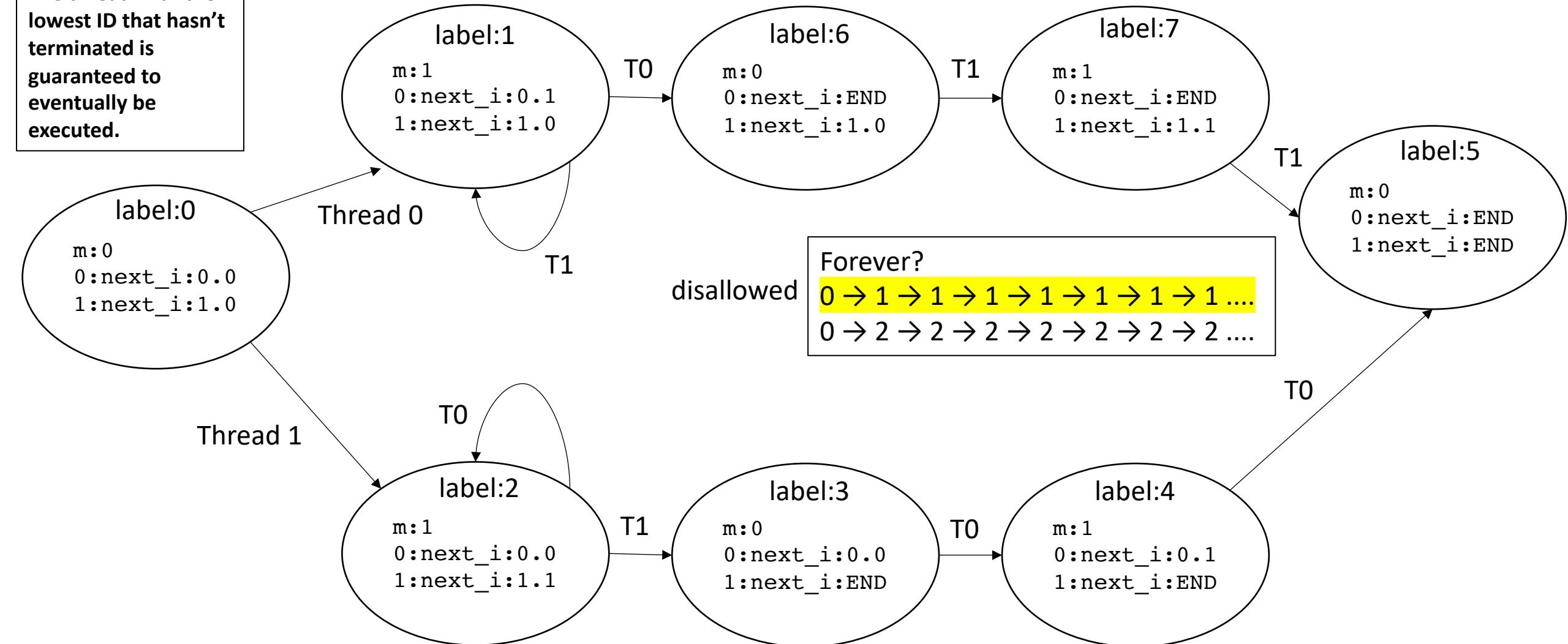
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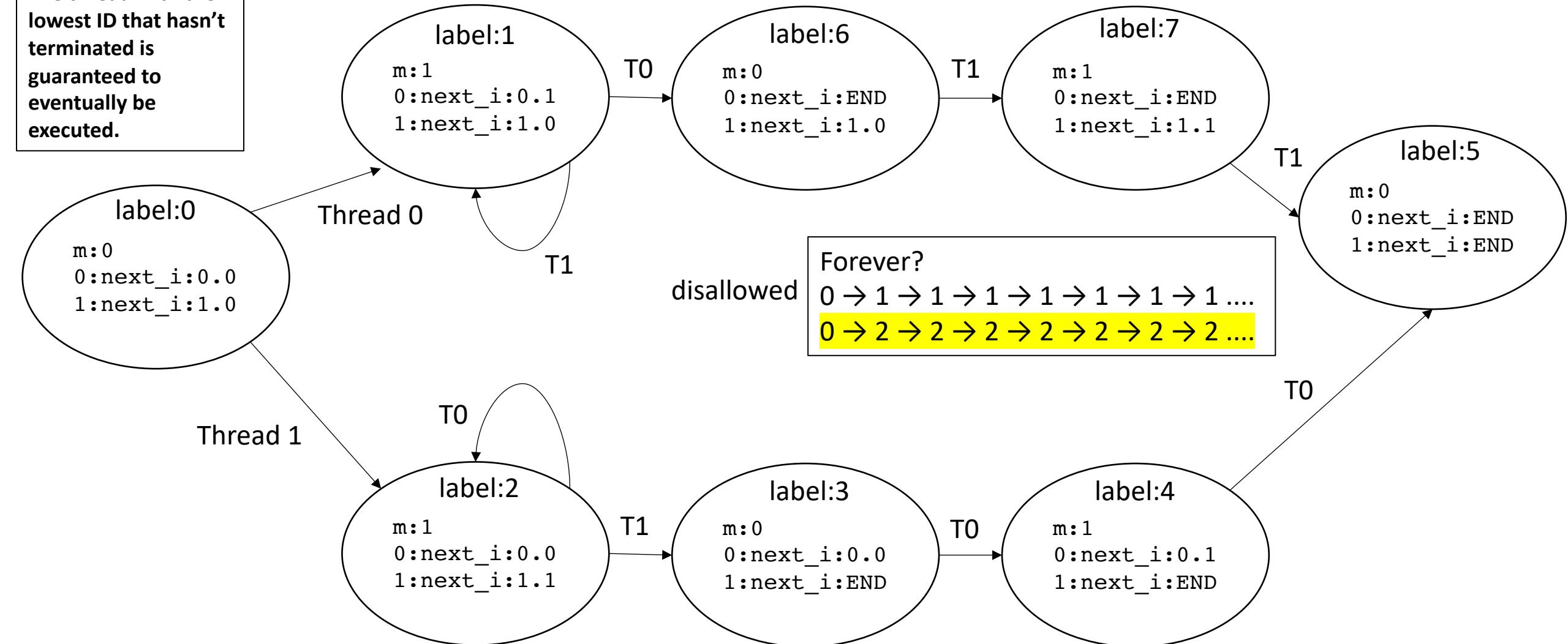
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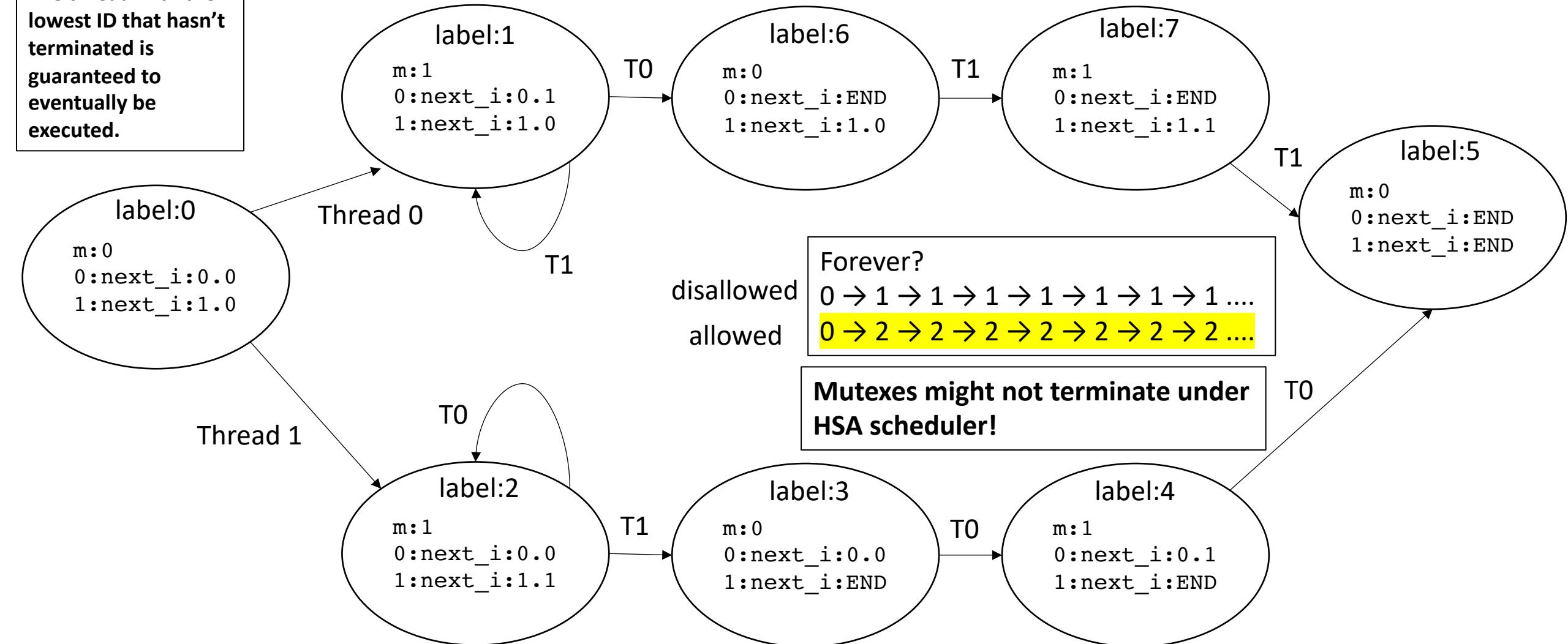
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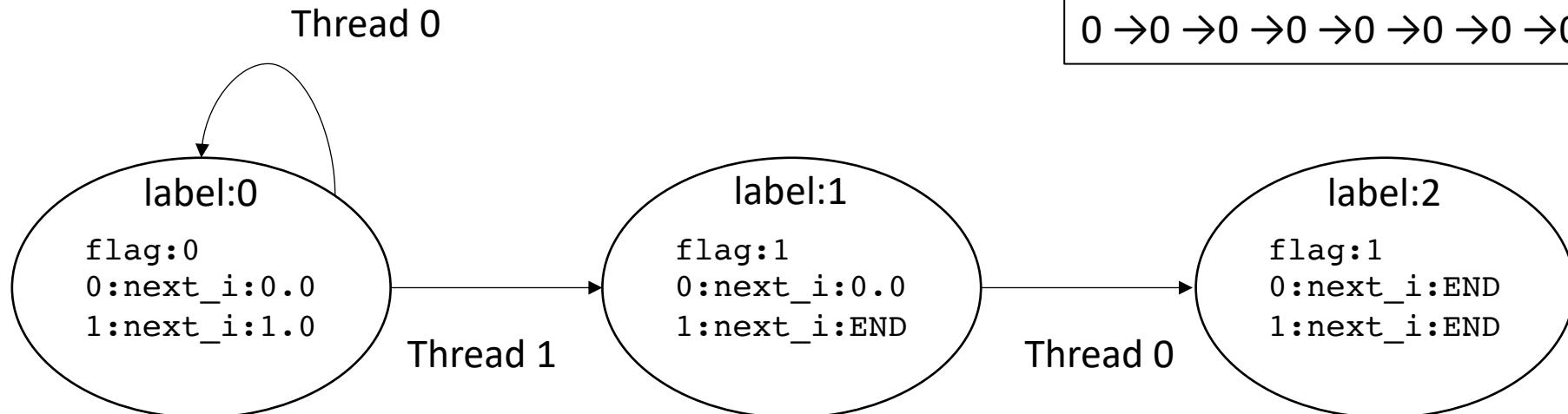
```
0.0: while(flag.load() == 0);
```

Thread 1:

```
1.0: flag.store(1);
```

*Is this program guaranteed to terminate under the HSA scheduler*

**The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.**



Thread 0:

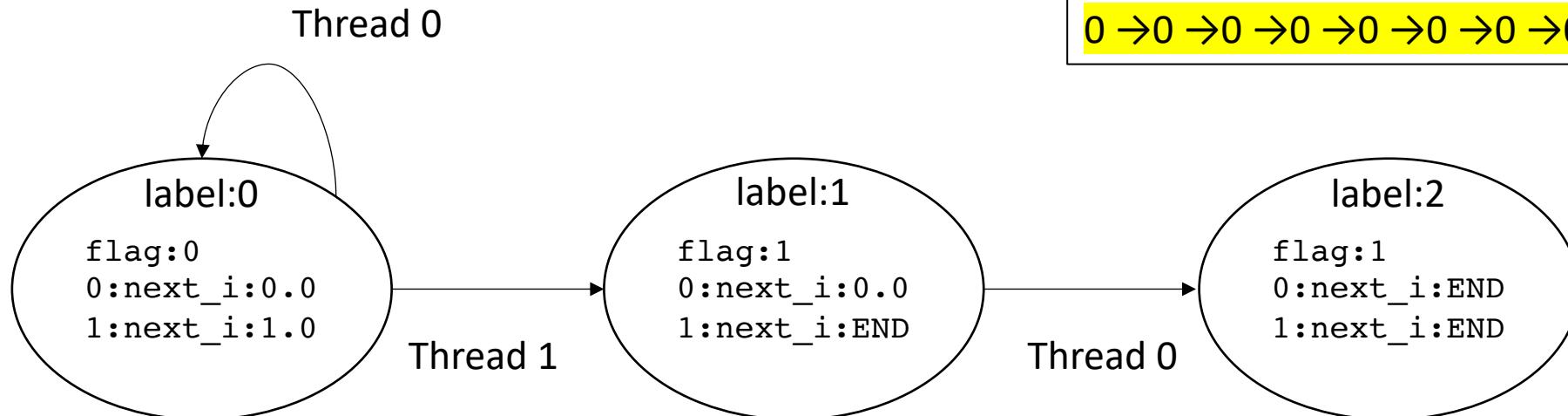
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*Is this program guaranteed to terminate under the HSA scheduler*

**The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.**



Forever?

0 → 0 → 0 → 0 → 0 → 0 → 0 → 0....

Thread 0:

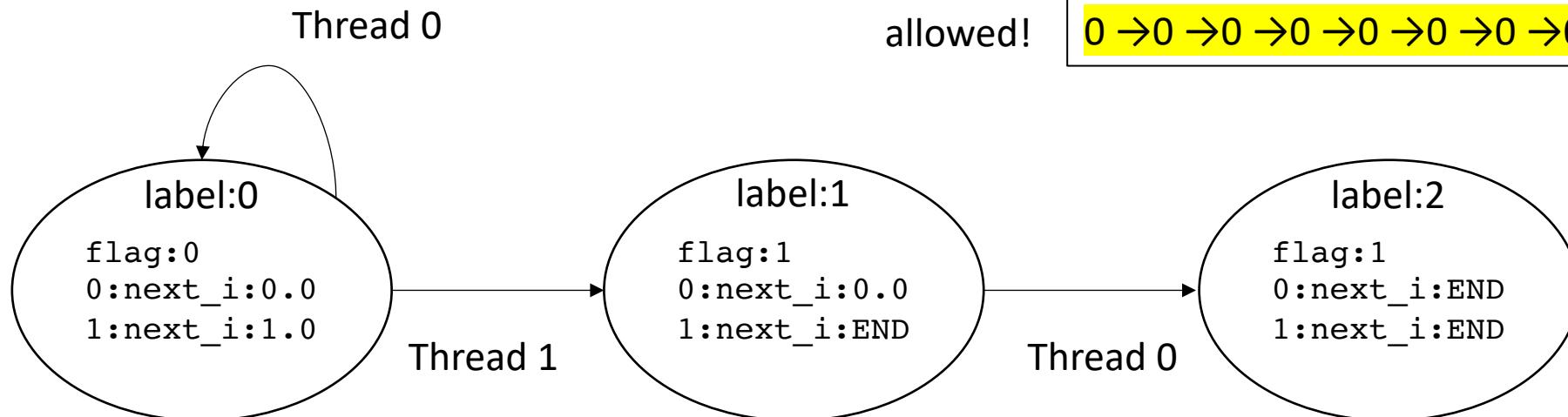
```
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```

Thread 1:

```
1.0: flag.store(1);
```

*Is this program guaranteed to terminate under the HSA scheduler?*

The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.



*allowed to spin forever in the HSA scheduler!*

*Thread 0 is guaranteed to be executed because it has the lowest id. Thread 1 is not!*

Thread 0:

```
0.0: while(flag.load() == 0);
```

Thread 1:

```
1.0: flag.store(1);
```

What if we switch the threads?

Thread 1 waits for Thread 0?

Thread 0:

```
0.0: flag.store(1);
```

Thread 1:

```
1.0: while(flag.load() == 0);
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What if we switch the threads?

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Thread 0:

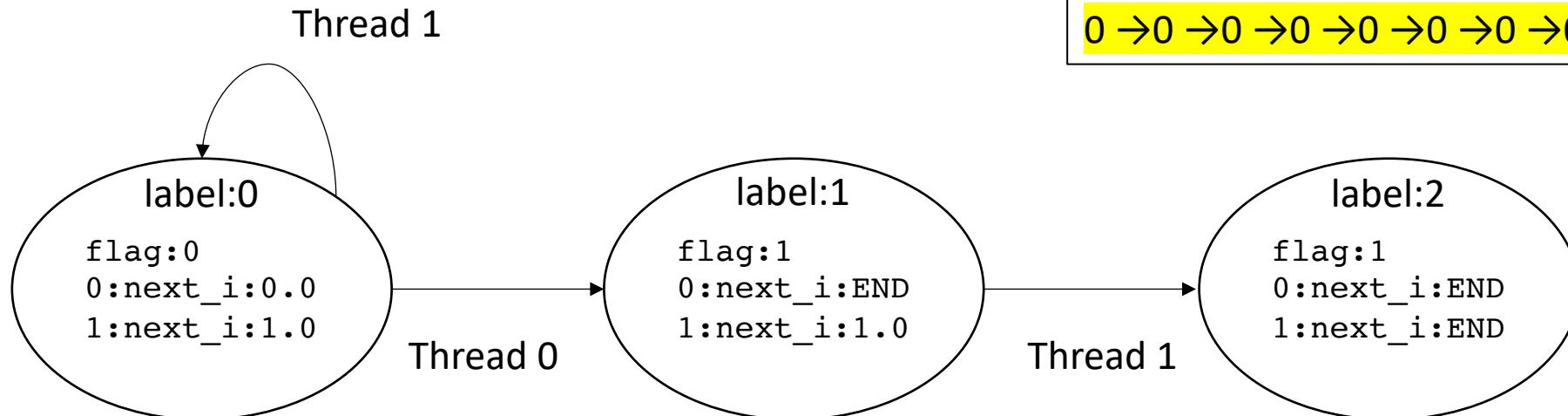
```
0.0: flag.store(1);
```

Thread 1:

```
1.0: while(flag.load() == 0);
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What if we switch the threads?  
Thread 1 waits for Thread 0?

The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.



Forever?

0 → 0 → 0 → 0 → 0 → 0 → 0 → 0....

*thread 0 has the lowest id so it is guaranteed to eventually be executed*

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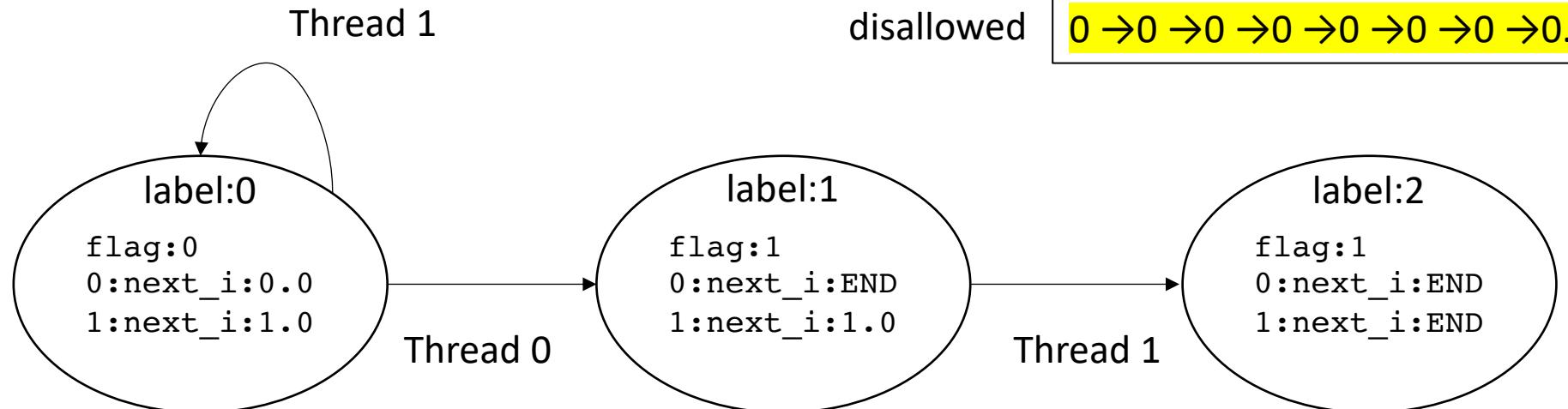
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Thread 1:

```
1.0: while(flag.load() == 0);
```

What if we switch the threads?  
Thread 1 waits for Thread 0?

The thread with the lowest ID that hasn't terminated is guaranteed to eventually be executed.



*thread 0 has the lowest id so it is guaranteed to eventually be executed*

# Liveness

- Combining HSA and Parallel Execution?
- Threads are scheduled in the order of their thread IDs and are guaranteed fair execution once they start executing.
- Most modern GPUs seem to support this:
  - With the exception of ARM and Apple GPUs

# Liveness

- So where are we now?
- C++ gives 3 degrees of progress guarantees:
  - Concurrent scheduler
    - what you will likely see on your machine; fair scheduler!
  - Parallel scheduler
    - Threads that start executing will continue to be fairly executed. Allows mutexes!
  - Weakly parallel scheduler
    - No guarantees. Any cycle in the LTS can potentially execute forever!

# Liveness

- So where are we now?
- GPU schedulers:
  - Nvidia provides Parallel Forward Progress
    - Allows mutexes, concurrent data structures, etc.
  - OpenCL, Vulkan, and Metal provide no documentation on scheduler behaviors.
    - In practice, many assume parallel forward progress
    - This is not portable (esp. to ARM and Apple)
    - Working with specification groups to try and provide these

# Conclusion

- Schedulers are becoming more aggressive
  - Preemption is expensive
  - Power saving shut downs are possible
- Concurrent objects require different amounts of fairness
  - Mutexes require parallel forward progress
  - Producer Consumer requires HSA forward progress
- Be careful that the programs you are writing make the correct assumptions about the underlying scheduler!

# Conclusion

- Demo about how things can go wrong on Ipad.

# A different type of non-termination

Hallway problem



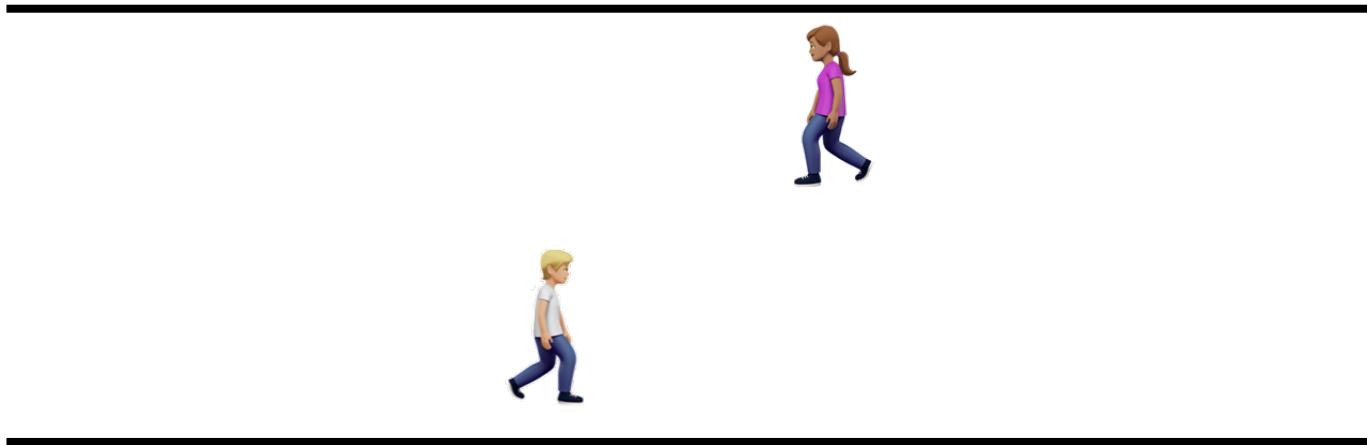
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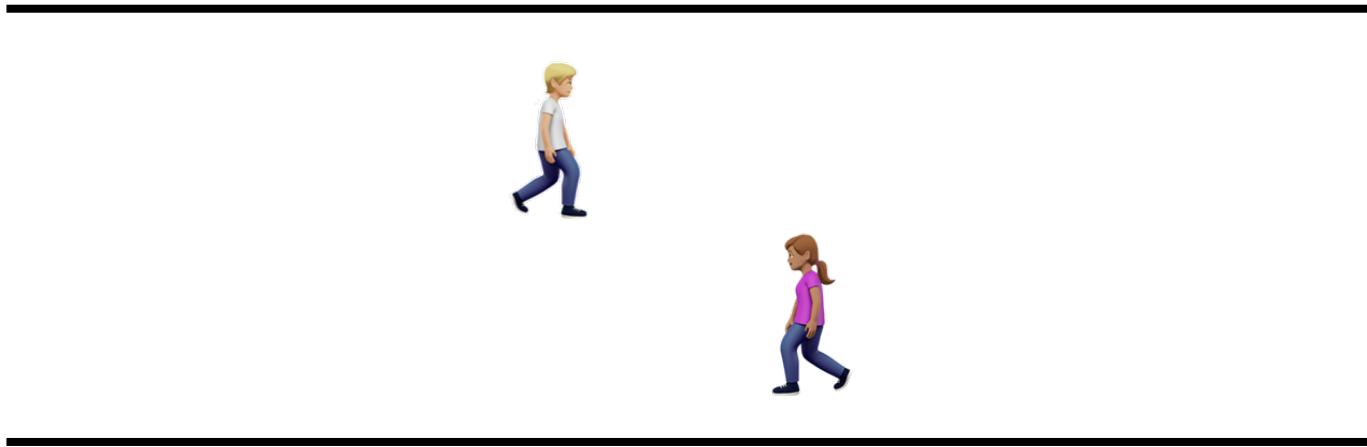
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---

# A different type of non-termination

Hallway problem



# A different type of non-termination

Hallway problem



Can they dance around each other forever?

Thread 0:

```
... do {  
0.0  x.store(0);  
0.1 } while (x.load() != 0)
```

Thread 1:

```
... do {  
1.0  x.store(1);  
1.1 } while (x.load() != 1)
```

Each thread stores their thread id,  
and then loads the thread id. It loops while  
it doesn't see its id

Each thread gets a chance to execute, but they  
get in each others way.

This is called a livelock

We don't have time to get into it deeply here,  
but there are lots of interesting research challenges  
around these types of behaviors!

# Thanks!

- See you on Thursday!
- We will start a 2 part lecture on GPUs