CSE110A: Compilers

May 24, 2023

Topics:

- Basic Blocks
- Local Value numbering

Announcements

- HW 4 is due on Monday
 - No guaranteed help on weekends or holidays
- Working on grading HW 2 and HW 3: grades should be out soon.
- HW 5 is planned to be released on Monday

Identify the largest common subexpression of the following program:

int x = 1 + 2; int y = 1 + x * x * x;int z = x + y * 1 + 2 + 3;if (z == 2+ y * 1) { int w = 1 + 2 + 3;} \bigcirc 1 + 2 + 3 $\bigcirc x^*x^*x$ ○ y * 1 + 2 O 2 + 3

Perform Constant propagation on the following program; what would the function return? (assume `if-statement` is a 'constexpr if-statement')

int a = 30; int b = 9 - (a / 5); int c; c = b * 4; if (c > 10) { c = c - 10; } return c * (60 / a);

loop unrolling is a _____ optimization

 \bigcirc local

 \bigcirc regional

 \bigcirc global

Optimization categories

Next category level is how much code we need to reason about for the optimization.

- **local optimizations**: examine a "basic block", i.e. a small region of code with no control flow.
 - Examples?
- Regional optimizations: several basic blocks with simple control flow.
 - Examples?
- Global optimization: optimizes across an entire function

Describe some compiler optimizations you know of. Write one (or more) small example program on Godbolt and look at the llvm IR (using -emit-llvm on a clang compiler) or ISA code. You can also play with optimization flags (-O0, -O3, etc). Did the compiler do the optimization you thought of?

Describe your program and the optimization below. Feel free to share your experiment on piazza!

New material

Basic blocks

- A sequence of 3 address instructions
- Programs can be split into **Basic Blocks**:
 - A sequence of 3 address instructions such that:
 - There is a single entry, single exit

• *Important property*: an instruction in a basic block can assume that all preceding instructions will execute Single Basic Block

Label x: op1; op2; op3; br label z;

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Single Basic Block Label x: op1; op2; op3; br label z;

Two Basic Blocks

```
Label_x:
op1;
op2;
op3;
Label_y:
op4;
op5;
```

How might they appear in a high-level language? What are some examples?

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Label y:

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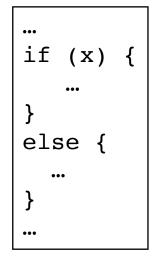
op4;

op5;

- A sequence of 3 address instructions
- Programs can be split into **Basic Blocks**:
 - A sequence of 3 address instructions such that:
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• *Important property*: an instruction in a basic block can assume that all preceding instructions will execute How might they appear in a high-level language?

How many basic blocks?



Two Basic Blocks

Single Basic BlockLabel_x:
op1;
op2;
op3;Image: Description of the second structureImage: Descr

Converting 3 address code into basic blocks

• Let's try an example: test 4 in HW 3:

Converting 3 address code into basic blocks

- Simple algorithm:
 - keep a list of basic blocks
 - a basic block is a list of instructions (3 address code)
 - Iterate over the 3 address instructions
 - if you see a branch or a label, finalize the current basic block and start a new one.

Converting 3 address code into basic blocks

pseudo code

```
basic_blocks = []
bb = []
for instr in program:
    if instr type is in [branch, label]:
        bb.append(instr)
        basic_blocks.append[bb]
        bb = []
    else:
        bb.append(instr)
```

• Local optimizations:

• Optimizes an individual basic block

• Regional optimizations:

• Combines several basic blocks

Global optimizations:

- operates across an entire procedure
- what about across procedures?

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Label_0: x = a + b; y = a + b;

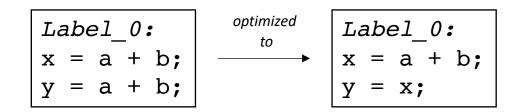
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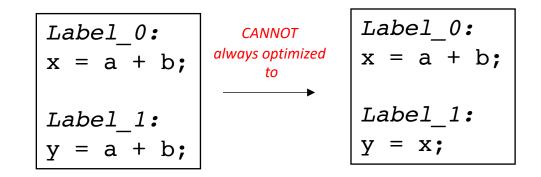


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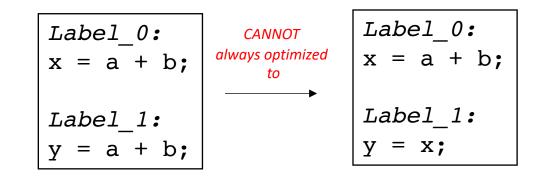
Label_0:	optimized to	Label_0:
x = a + b;	>	x = a + b;
y = a + b;		y = x;



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Label_0:
$$x = a + b;$$

 $y = a + b;$ optimized
toLabel_0:
 $x = a + b;$
 $y = x;$



code could skip Label_0, leaving x undefined!

Regional Optimization

… if (x) {			
… } else {			
x = a + b; }			
y = a + b;			
•••			

we cannot replace: y = a + b. with y = x;

Regional Optimization

•••	
if (x) {	
•••	
}	we
else {	
x = a + b;	
}	
y = a + b;	
•••	

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But in this case, we can check if a and b are not redefined, then y = a + b;can be replaced with y = x;

This requires regional analysis and optimizations

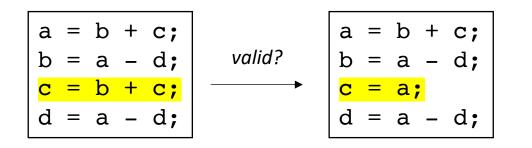
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- Can be extended to a regional optimization using flow analysis

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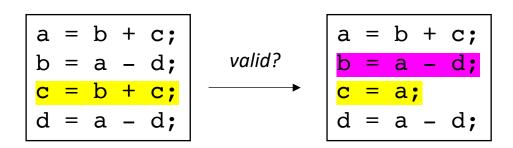
$$a = b + c;$$

 $b = a - d;$
 $c = b + c;$
 $d = a - d;$

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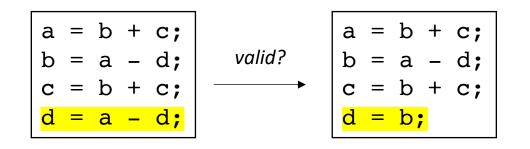


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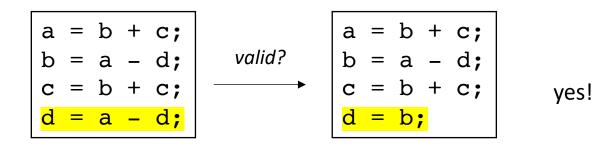


No! Because b is redefined

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Algorithm:

- Provide a number to each variable. Update the number each time the variable is updated.
- Keep a global counter; increment with new variables or assignments

Global_counter = 0

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Global_counter = 7

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- At each step, check to see if the rhs has already been computed.

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$$\Rightarrow \begin{bmatrix} a2 &= b0 + c1; \\ b4 &= a2 - d3; \\ c5 &= b4 + c1; \\ d6 &= a2 - d3; \end{bmatrix}$$

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What else can we do?

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Consider this snippet:

a2	=	c 1	_	b0;
f4	=	d3	*	a2;
c5	=	b0	-	c1;
d6	=	a2	*	d3;

Commutative operations

What is the definition of commutative?

Commutative operations

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$$x OP y == y OP x$$

What operators are commutative? Which ones are not?

Adding commutativity to local value numbering

- For commutative operators (e.g. + *), the analysis should consider a deterministic order of operands.
- You can use variable numbers or lexigraphical order

Algorithm optimization:

Algorithm optimization:

for commutative operations, re-order operands into a deterministic order

cannot re-order because - is not commutative

Algorithm optimization:

Algorithm optimization:

for commutative operations, re-order operands into a deterministic order

re-ordered because a2 < d3 lexigraphically

a2	=	c 1	_	b0; a2; c1; d3;
 f4	=	d3	*	a2;
c5	=	b0	—	c1;
d6	=	a2	*	d3;

Algorithm optimization:

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$$a2 = c1 - b0;$$

$$f4 = d3 * a2;$$

$$c5 = b0 - c1;$$

$$d6 = a2 * d3;$$

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$$f4 = d3 * a2;$$

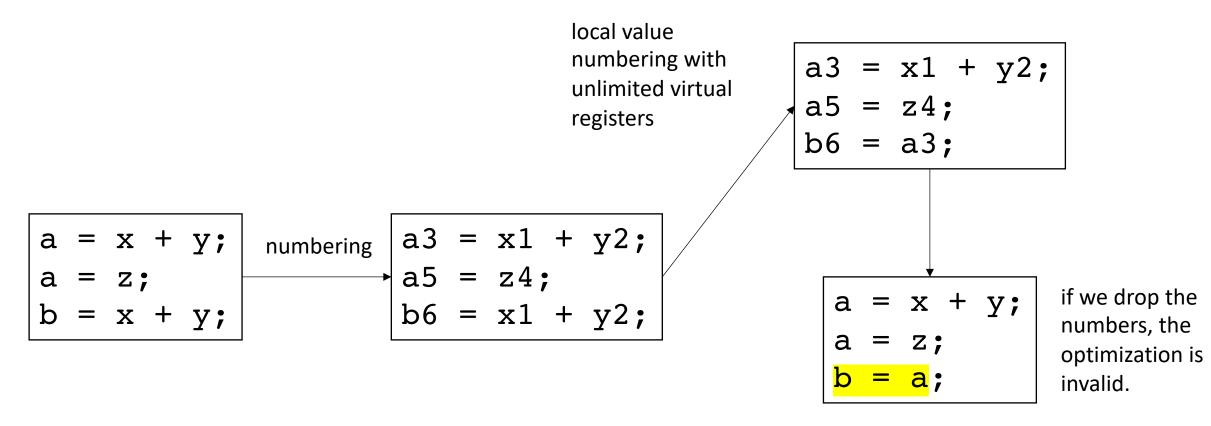
$$c5 = b0 - c1;$$

$$d6 = f4;$$

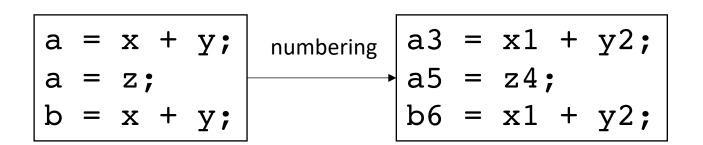
Other considerations?

- We've assumed we have access to an unlimited number of virtual registers.
- In some cases we may not be able to add virtual registers
 - If an expensive register allocation pass has already occurred.
- New constraint:
 - We need to produce a program such that variables without the numbers is still valid.

• Example:

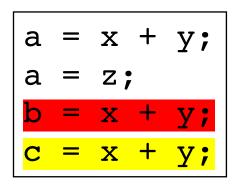


• Solutions?



a	=	x	+	у;
a	=	Z	;	
b	=	X	+	у;
С	=	Χ	+	У;

• Keep another hash table to keep the current variable number



We cannot optimize the first line, but we can optimize the second

a	=	x	+	у;
a	=	Z	;	
b	=	X	+	у;
С	=	Χ	+	У;

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• Keep another hash table to keep the current variable number

 \rightarrow | a3 = x1 + y2; a5 = z4;

b6 = x1 + y2;c7 = x1 + y2;

• Keep another hash table to keep the current variable number

→ a3 = x1 + y2; a5 = z4; b6 = x1 + y2; c7 = x1 + y2;

Current_val = {
"a" : 5,
}

$$A3 = x1 + y2;$$

 $a5 = z4;$
 $b6 = x1 + y2;$
 $c7 = x1 + y2;$
 $Current_val = {
"x1 + y2" : "a3",
}$

• Keep another hash table to keep the current variable number

a3 = x1 + y2;

 $\Rightarrow \begin{vmatrix} a5 &= z4; \\ b6 &= x1 + y2; \\ c7 &= x1 + y2; \end{vmatrix}$

"b6",

• Keep another hash table to keep the current variable number

a3

Local value numbering w/out adding registers

• Keep another hash table to keep the current variable number

a3

a5

b6

Local value numbering w/out adding registers

• Keep another hash table to keep the current variable number

——**)**

a3

a5

b6

Anything else we can add to local value numbering?

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• Final heuristic: keep sets of possible values

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b	=	x	+	у;	
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C	=	X	+	У;	

• Final heuristic: keep sets of possible values

Current_val = {
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а	=	= z;				
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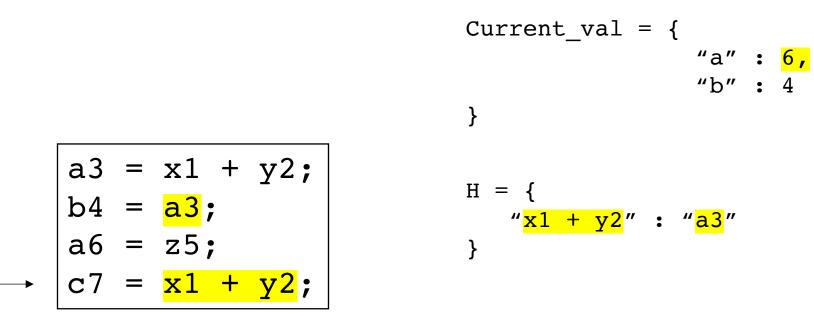
Work through example

• Final heuristic: keep sets of possible values

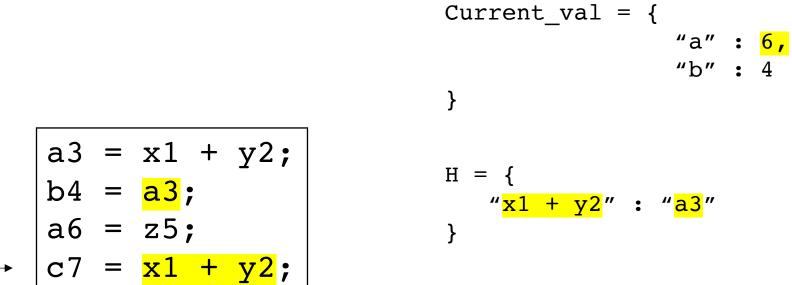
Current_val = {
}

• Final heuristic: keep sets of possible values

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• Final heuristic: keep sets of possible values



but we could have replaced it with b4!

——**—**

• Final heuristic: keep sets of possible values

rewind to this point a3 = x1 + y2; b4 = x1 + y2; a6 = z5; c7 = x1 + y2;

• Final heuristic: keep sets of possible values

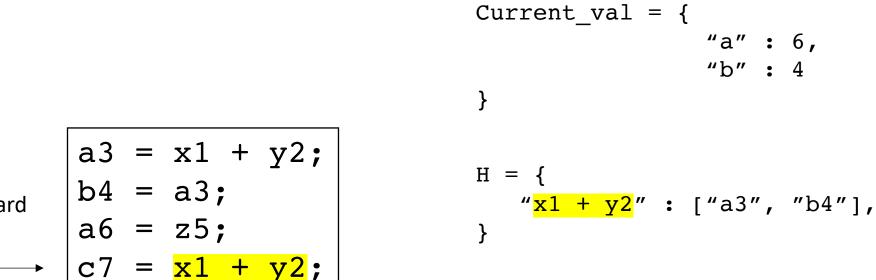
Current_val = {

$$a3 = x1 + y2;$$

 $b4 = a3;$
 $a6 = z5;$
 $c7 = x1 + y2;$
Current_val = {
 $"a" : 3,
"b" : 4
H = {
 $"x1 + y2" : ["a3", "b4"],$
hash a list of$

possible values

• Final heuristic: keep sets of possible values



fast forward again

• Final heuristic: keep sets of possible values

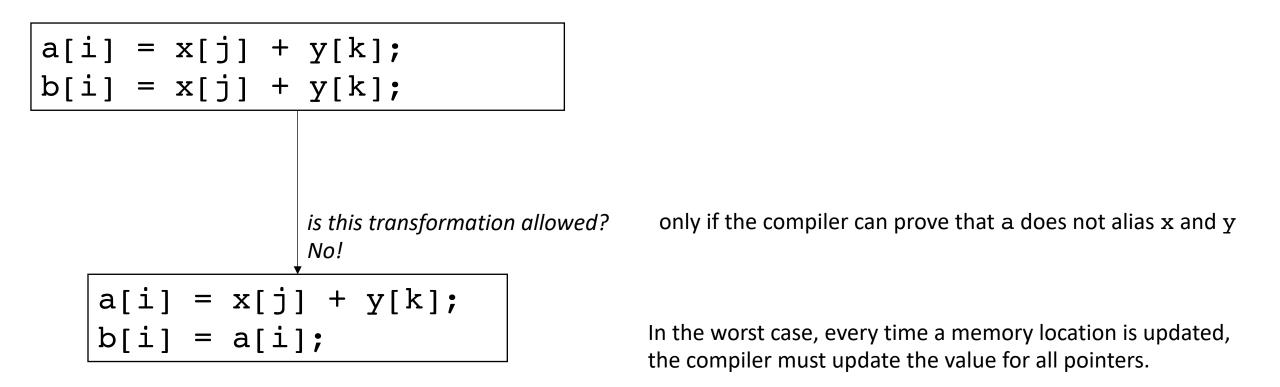
again

fast forward
again

$$\rightarrow$$
 $a3 = x1 + y2;$
 $b4 = a3;$
 $a6 = z5;$
 $c7 = b4;$
 $Current_val = {
"a" : 6,
"b" : 4
}
H = {
"x1 + y2" : ["a3", "b4"]
}$

1

Consider a 3 address code that allows memory accesses



- How to number:
 - Number each pointer/index pair

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 - Any pointer/index pair that might alias must be incremented at each instruction

(a[i],3) = (x[j],1) + (y[k],2);(b[i],6) = (x[j],4) + (y[k],5);

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compiler analysis:

can we trace a, x, y to
a = malloc(...);
x = malloc(...);
y = malloc(...);

// a, x, y are never overwritten

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restrict a

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(a[i],3) = (x[j],1) + (y[k],2); (b[i],6) = (a[i],3);

Optimizing over wider regions

- Local value numbering operated over just one basic block.
- We want optimizations that operate over several basic blocks (a region), or across an entire procedure (global)
- For this, we need Control Flow Graphs and Flow Analysis
 - We may have time to discuss this later in the module

See everyone on Friday

• More about optimizations!